

Geometry of Sparsity-Inducing Balls

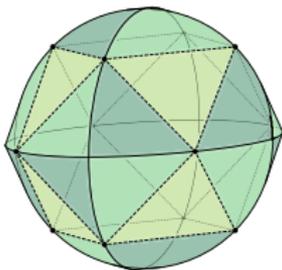
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Seventh Conference on DO \times ML
12th – 16th May 2025, Kyoto, Japan



Support and the ℓ_0 pseudonorm

Let $d \in \mathbb{N}^*$ be a fixed natural number and

$$\llbracket 0, d \rrbracket = \{0, 1, \dots, d\}, \quad \llbracket 1, d \rrbracket = \{1, \dots, d\}$$

For any vector $x \in \mathbb{R}^d$, we define

- ▶ its **support** by

$$\text{supp}(x) = \{j \in \llbracket 1, d \rrbracket \mid x_j \neq 0\}$$

$$\text{supp}((0, *, 0, *, *, 0)) = \{2, 4, 5\} \subset \llbracket 1, 6 \rrbracket$$

- ▶ its **ℓ_0 pseudonorm**(x) by

$$\ell_0(x) = \overbrace{|\text{supp}(x)|}^{\text{cardinality}} = \overbrace{\sum_{i=1}^d \mathbf{1}_{\{x_i \neq 0\}}}_{\text{number of nonzero entries}}$$

$$\ell_0((0, *, 0, *, *, 0)) = |\{2, 4, 5\}| = 3 \in \llbracket 0, 6 \rrbracket$$

The ℓ_0 pseudonorm is not a norm

The function ℓ_0 pseudonorm : $\mathbb{R}^d \rightarrow \llbracket 0, d \rrbracket$
satisfies 3 out of 4 axioms of a norm

- ▶ we have $\ell_0(x) \geq 0$ ✓
- ▶ we have $\left(\ell_0(x) = 0 \iff x = 0 \right)$ ✓
- ▶ we have $\ell_0(x + x') \leq \ell_0(x) + \ell_0(x')$ ✓
- ▶ **But...** instead of 1-homogeneity,
it is **0-homogeneity** that holds true

$$\ell_0(\rho x) = \ell_0(x), \quad \forall \rho \neq 0$$

$$\text{supp}(\rho x) = \text{supp}(x), \quad \forall \rho \neq 0$$

The ℓ_0 pseudonorm maps **continuous onto discrete**

Talk outline

Design of sparsity-inducing unit balls [10 min]

What are sparsity-inducing norms/balls?

Exposed faces of unit balls with k -sparse extreme points

Support identification using k -sparsity inducing norms

Geometry of sparsity-inducing balls [6 min]

Orthant-strictly monotonicity and Capra-convexity of ℓ_0 [9 min]

Orthant-strictly monotonic (OSM) norms

OSM norms and hidden convexity in the ℓ_0 pseudonorm

Crash course on generalized convexity

OSM norms, Capra conjugacies and the ℓ_0 pseudonorm

Conclusion

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Archetypal sparse optimization problems

- ▶ (Pure sparse) For $X \subset \mathbb{R}^d$ a nonempty set

$$\text{minimal } \ell_0 \text{ pseudonorm} \quad \min_{x \in X} \ell_0(x)$$

is an optimization problem for which any point in X is a local minimizer

Jean-Baptiste Hiriart-Urruty and Hai Le. A variational approach of the rank function. *TOP: An Official Journal of the Spanish Society of Statistics and Operations Research*, 21(2):207–240, 2013.

- ▶ (Sparsity constraint) For $k \in \llbracket 1, d \rrbracket$ and a function $f : \mathbb{R}^d \rightarrow \overline{\mathbb{R}}$

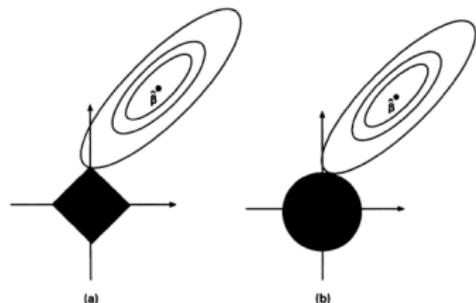
$$\text{optimal } k\text{-sparse vector} \quad \min_{\substack{\ell_0(x) \leq k \\ \text{\small } k\text{-sparse vectors}}} f(x)$$

- ▶ (Sparsity penalty) For $\gamma > 0$ and a function $f : \mathbb{R}^d \rightarrow \overline{\mathbb{R}}$

$$\min_{x \in \mathbb{R}^d} \left(f(x) + \underbrace{\gamma \ell_0(x)}_{\text{\small sparse penalty}} \right)$$

The intuition behind Lasso

$$\min_{x \in \mathbb{R}^d} (f(x) + \gamma \|x\|_1)$$



$$\min_{x \in \mathbb{R}^d} (f(x) + \gamma \|x\|_2)$$

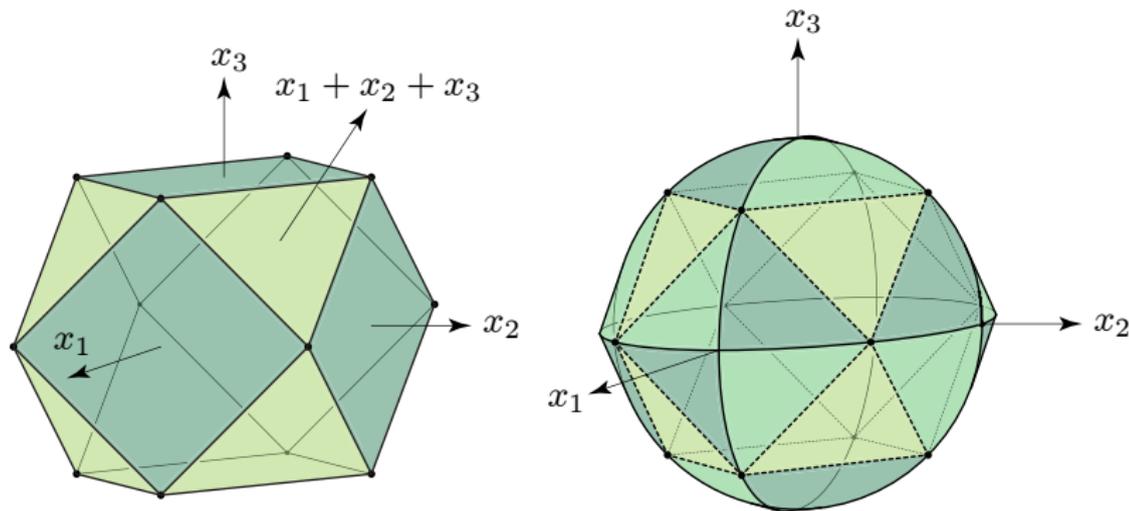
Comments of

[Tibshirani, 1996, Figure 2]

“The lasso solution is the first place that the contours touch the square, and this will sometimes occur at a corner, corresponding to a zero coefficient. The picture for ridge regression is shown in Fig. 2(b): there are no corners for the contours to hit and hence zero solutions will rarely result.”

Robert Tibshirani. Regression shrinkage and selection via the lasso. *Journal of the Royal Statistical Society. Series B (Methodological)*, 58(1):267–288, 1996

Here are other examples of balls
with kinks sitting at 2-sparse points



Geometric (alignment) expression of optimality condition

- ▶ We consider an **optimal solution** $x^* \neq 0$ of

$$\min_{x \in \mathbb{R}^d} (f(x) + \gamma \|x\|)$$

where $f : \mathbb{R}^d \rightarrow \mathbb{R}$ is a smooth convex function,
 $\gamma > 0$ and $\|\cdot\|$ is a norm with **unit ball** B

$$\underbrace{0 \in \nabla f(x^*) + \gamma \partial \|\cdot\|(x^*)}_{\text{Fermat rule}} \implies \underbrace{\frac{x^*}{\|x^*\|}}_{\text{0-homogeneity}} \in \underbrace{F_{\perp}(B, -\nabla f(x^*))}_{\text{face of the unit ball } B \text{ exposed by } -\nabla f(x^*)}$$

- ▶ We expect that the **support of** x^*
can be recovered from the **dual information** $-\nabla f(x^*)$

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We reformulate sparsity in terms of coordinate subspaces

- ▶ For any $K \subset \llbracket 1, d \rrbracket$, we introduce the (coordinate) subspace

$$\mathcal{R}_K = \{y \in \mathbb{R}^d \mid y_j = 0, \forall j \notin K\} \subset \mathbb{R}^d$$

- ▶ The connection with the **level sets** of the ℓ_0 pseudonorm is

$$\ell_0^{\leq k} = \underbrace{\{x \in \mathbb{R}^d \mid \ell_0(x) \leq k\}}_{k\text{-sparse vectors}} = \bigcup_{|K| \leq k} \mathcal{R}_K, \quad \forall k \in \llbracket 0, d \rrbracket$$

- ▶ We denote by $\pi_K : \mathbb{R}^d \rightarrow \mathcal{R}_K$ the **orthogonal projection**

$$y = (*, *, *, *, *, *) \rightarrow \pi_{\{2,4,5\}}(y) = (0, *, 0, *, *, 0) \in \mathcal{R}_{\{2,4,5\}}$$

Design of unit ball
with k -sparse extreme points
(for example, 2-sparse points in \mathbb{R}^3)

Design of unit ball with k -sparse extreme points

For given **sparsity threshold** $k \in \llbracket 1, d \rrbracket$ (or sparsity **budget**) we consider a **source norm** $\|\cdot\|$, with **unit ball** B

- ▶ 1) **project** B onto $\ell_0^{\leq k}$ 2) form the convex hull

$$B_{\star, (k)}^{\top\star} = \underbrace{\text{co} \left(\underbrace{\bigcup_{|K| \leq k} \pi_K(B)}_{\text{projection onto } \ell_0^{\leq k}} \right)}_{\text{convex hull}}$$

- ▶ and we get the unit ball of the **generalized k -support dual norm** $\|\cdot\|_{\star, (k)}^{\top\star}$
[Chancelier and De Lara, 2022b]
- ▶ the **extreme points** of $B_{\star, (k)}^{\top\star}$ belong to $\bigcup_{|K| \leq k} \mathcal{R}_K = \ell_0^{\leq k}$, hence are **k -sparse vectors**

Generalized top- k and k -support dual norms

[Chancelier and De Lara, 2022b]

Definition

For any source norm $\|\cdot\|$ on \mathbb{R}^d , for any $k \in \llbracket 1, d \rrbracket$,

- ▶ the **generalized k -support dual norm** $\|\cdot\|_{\star,(k)}^{\top\star}$

is the dual norm $\|\cdot\|_{\star,(k)}^{\top\star} = (\|\cdot\|_{\star,(k)}^{\top})_{\star}$

- ▶ of the **generalized top- k dual norm** $\|\cdot\|_{\star,(k)}^{\top}$ defined by

$$\|y\|_{\star,(k)}^{\top} = \underbrace{\sup_{|K| \leq k} \|\overbrace{\pi_K(y)}^{k\text{-sparse projection on } \mathcal{R}_K}\|_{\star}}_{\text{exploring all } k\text{-sparse projections}}, \quad \forall y \in \mathbb{R}^d$$

Characterization of the exposed faces of the new unit ball

Characterization of the exposed faces of the new unit ball

Theorem

Let $k \in \llbracket 1, d \rrbracket$

Then, for any nonzero dual vector $y \in \mathbb{R}^d \setminus \{0\}$,
the exposed face of the unit ball $B_{\star, (k)}^{\top\star}$ is given by

$$F_{\perp}(B_{\star, (k)}^{\top\star}, y) = \overline{\text{co}} \left\{ \overbrace{\pi_{K^*} \left(\underbrace{F_{\perp}(B, \pi_{K^*} y)}_{\substack{\text{exposed face} \\ \text{of the original} \\ \text{unit ball}}} \right)}^{\text{projection on } \mathcal{R}_{K^*}} : K^* \in \arg \max_{|K| \leq k} \|\pi_K y\|_{\star} \right\}$$

Characterization of the exposed faces of the new unit ball

Theorem

Let $k \in \llbracket 1, d \rrbracket$

Suppose that the source norm $\|\cdot\|$ is **orthant-strictly monotonic**

Then, for any nonzero dual vector $y \in \mathbb{R}^d \setminus \{0\}$,
the exposed face of the unit ball $B_{\star, (k)}^{\top\star}$ is given by

$$F_{\perp}(B_{\star, (k)}^{\top\star}, y) = \overline{\text{co}} \left\{ \underbrace{\text{no projection needed}}_{\underbrace{F_{\perp}(B, \pi_{K^*} y)}_{\substack{\text{exposed face} \\ \text{of the original} \\ \text{unit ball}}}} : K^* \in \arg \max_{|K| \leq k} \|\pi_K y\|_{\star} \right\}$$

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Support identification: main result

Theorem

Let $f : \mathbb{R}^d \rightarrow \mathbb{R}$ be a smooth convex function, and $\gamma > 0$

For given **sparsity threshold** $k \in \llbracket 1, d \rrbracket$,
an **optimal solution** x^* of

$$\min_{x \in \mathbb{R}^d} \left(f(x) + \gamma \underbrace{\|x\|_{*,(k)}^{\top*}}_{\substack{\text{generalized} \\ k\text{-support} \\ \text{dual norm}}} \right)$$

has support

$$\text{supp}(x^*) \subset \bigcup_{K^* \in \arg \max_{|K| \leq k} \|\pi_K(-\nabla f(x^*))\|_*} K^*$$

Sparse support identification: corollary

Corollary

Let $f : \mathbb{R}^d \rightarrow \mathbb{R}$ be a smooth convex function and $\gamma > 0$

For given **sparsity threshold** $k \in \llbracket 1, d \rrbracket$, if an **optimal solution** x^* of

$$\min_{x \in \mathbb{R}^d} (f(x) + \gamma \|x\|_{\star, (k)}^{\top \star})$$

is such that $\arg \max_{|K| \leq k} \|\pi_K(-\overbrace{\nabla f(x^*)}^{\text{dual information}})\|_{\star} = K^*$ is **unique**

then it has support

$$\text{supp}(x^*) \subset K^* \text{ with } |K^*| \leq k$$

so that the **optimal solution** x^* is **k -sparse**

Support identification: Lasso

Corollary

Let $f : \mathbb{R}^d \rightarrow \mathbb{R}$ be a smooth convex function,
 $\gamma > 0$ and $\|\cdot\|_1$ be the ℓ_1 norm

An **optimal solution** x^* of

$$\min_{x \in \mathbb{R}^d} (f(x) + \gamma \|x\|_1)$$

has support

$$\text{supp}(x^*) \subset \arg \max_{j \in \llbracket 1, d \rrbracket} |\nabla_j f(x^*)|$$

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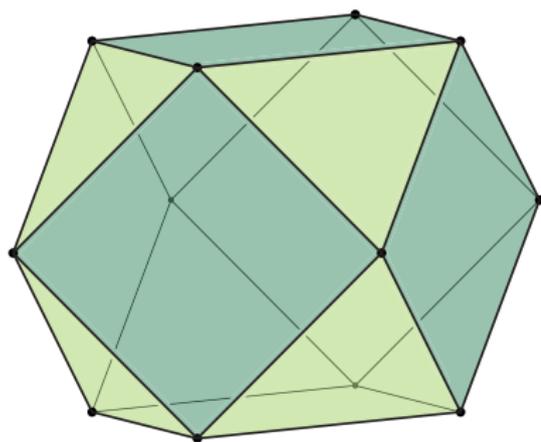
The case of ℓ_p -norms $\|\cdot\|_p$

$$\|x\|_\infty = \sup_{i \in \llbracket 1, d \rrbracket} |x_i| \quad \text{and} \quad \|x\|_p = \left(\sum_{i=1}^d |x_i|^p \right)^{1/p} \quad \text{for } p \in [1, \infty[$$

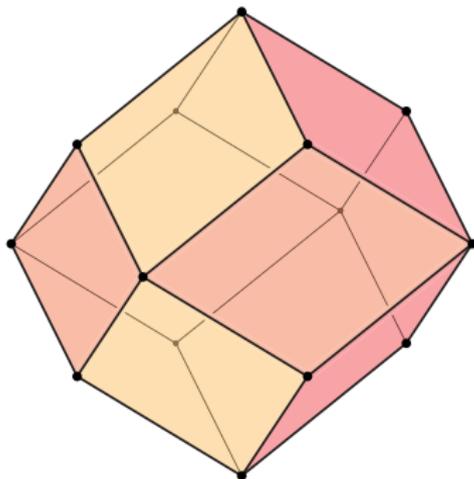
source norm $\ \cdot\ $	$\ \cdot\ _{\star, (k)}^T, k \in \llbracket 1, d \rrbracket$	$\ \cdot\ _{\star, (k)}^{T\star}, k \in \llbracket 1, d \rrbracket$
$\ \cdot\ _p$	top- (q, k) norm $\ y\ _{q, k}^T$ $\ y\ _{q, k}^T = \left(\sum_{l=1}^k y_{\nu(l)} ^q \right)^{\frac{1}{q}}$	(p, k) -support norm $\ x\ _{p, k}^{T\star}$ no analytic expression
$\ \cdot\ _1$	top- (∞, k) norm ℓ_∞ -norm $\ y\ _{\infty, k}^T = \ y\ _\infty, \forall k \in \llbracket 1, d \rrbracket$	$(1, k)$ -support norm ℓ_1 -norm $\ x\ _{1, k}^{T\star} = \ x\ _1, \forall k \in \llbracket 1, d \rrbracket$
$\ \cdot\ _2$	top- $(2, k)$ norm $\ y\ _{2, k}^T = \sqrt{\sum_{l=1}^k y_{\nu(l)} ^2}$	$(2, k)$ -support norm $\ x\ _{2, k}^{T\star}$ no analytic expression
$\ \cdot\ _\infty$	top- $(1, k)$ norm $\ y\ _{1, k}^T = \sum_{l=1}^k y_{\nu(l)} $ $\ y\ _{2, 1}^T = \ y\ _\infty$ $\ y\ _{1, 1}^T = \ y\ _\infty$	(∞, k) -support norm $\ x\ _{\infty, k}^{T\star} = \max\left\{ \frac{\ x\ _1}{k}, \ x\ _\infty \right\}$ $\ x\ _{1, 1}^{T\star} = \ x\ _1$

When the source norm is the ℓ_∞ -norm

Case of sparsity threshold $k = 2$ in \mathbb{R}^3
with source norm the ℓ_∞ -norm



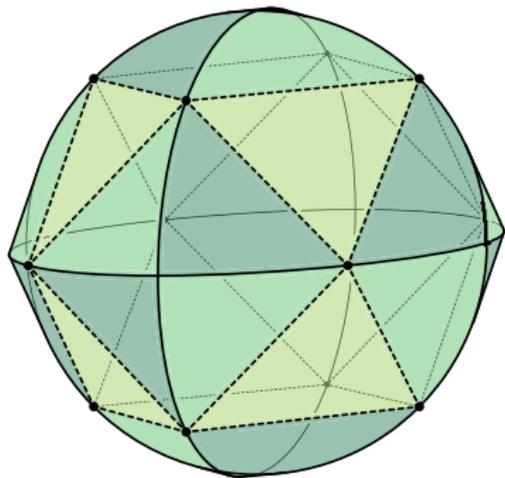
(a) Unit ball $B_{\infty,2}^{\top*}$
(support norm)



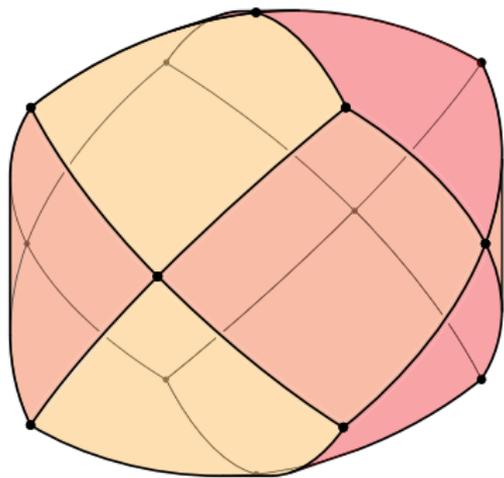
(b) Unit ball $B_{1,2}^{\top}$
(top norm)

When the source norm is the ℓ_2 -norm

Case of sparsity threshold $k = 2$ in \mathbb{R}^3
with source norm the ℓ_2 -norm

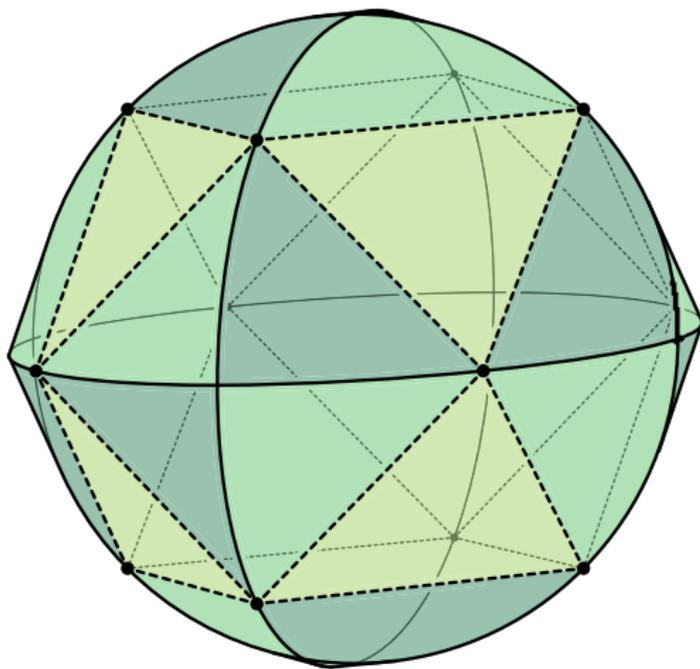


(a) Unit ball $B_{2,2}^{\top*}$
(support norm)



(b) Unit ball $B_{2,2}^{\top}$
(top norm)

An allegory of $DO \times ML$

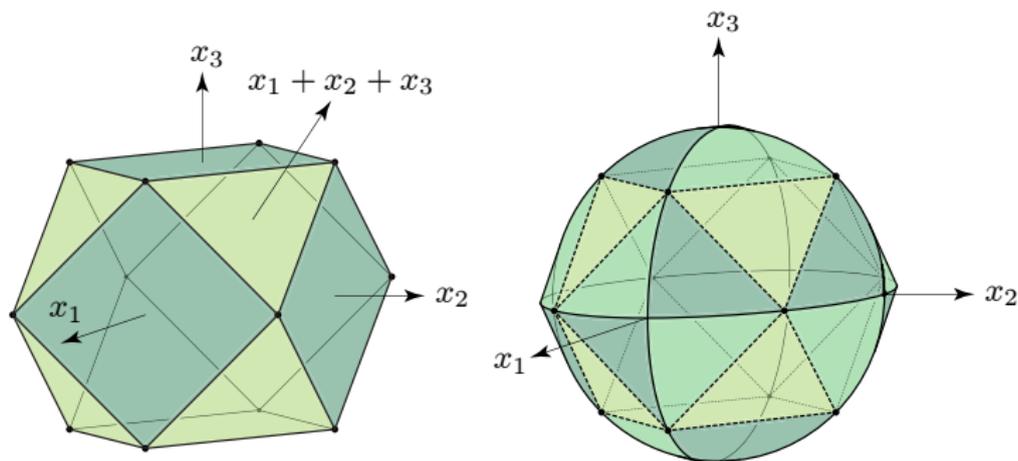


Kinks sting where polytopes connect with curved smooth surfaces

Geometric description

Proposition

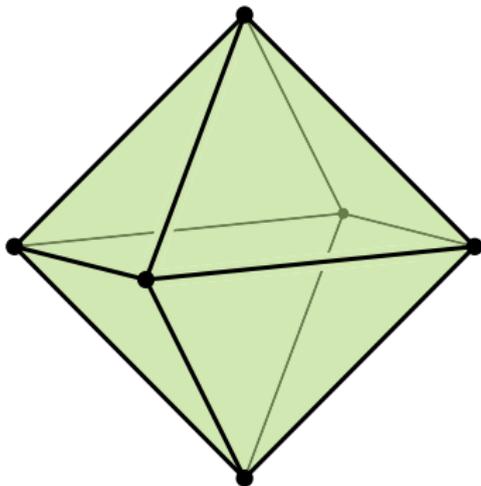
For any $k \in \llbracket 1, d \rrbracket$, all the **proper faces** of $B_{2,k}^{\top\star}$ are **hypersimplices**, and the normal fan of $B_{2,k}^{\top\star}$ refines the normal fan of $B_{\infty,k}^{\top\star}$



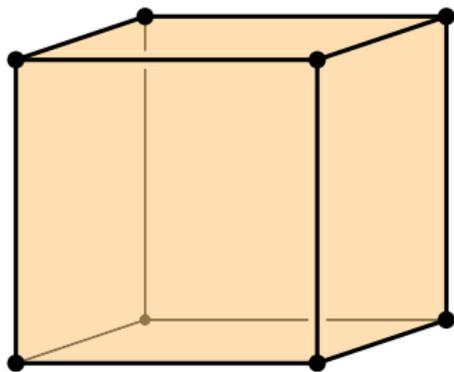
Hypersimplex $\Delta_{k,d}$: the convex hull of the d -dimensional vectors whose coefficients consist of k ones and $d - k$ zeros

When the source norm is the ℓ_1 -norm

Case of sparsity threshold $k = 2$ in \mathbb{R}^3
with source norm the ℓ_1 -norm



(a) Unit ball $B_{1,2}^{\top+}$
(support norm)



(b) Unit ball $B_{\infty,2}^{\top}$
(top norm)

What comes next?

- ▶ What are **orthant-strictly monotonic norms**?
- ▶ In what are they related to the **ℓ_0 pseudonorm**?

Background on the original motivation
Jean-Philippe Chancelier, Michel De Lara

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Orthant-monotonic norms

For any $x \in \mathbb{R}^d$, we denote by $|x|$
the vector of \mathbb{R}^d with components $|x_i|$, $i \in \llbracket 1, d \rrbracket$

Definition

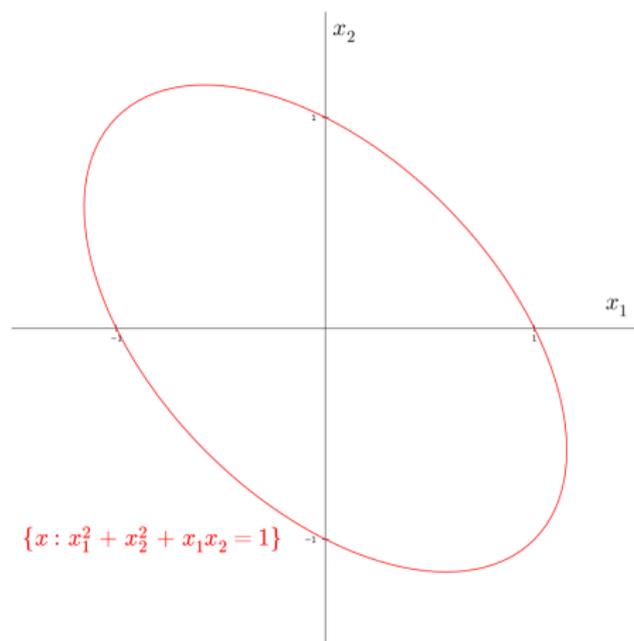
A norm $\|\cdot\|$ on the space \mathbb{R}^d is called **orthant-monotonic** [Gries, 1967] if, for all x, x' in \mathbb{R}^d , we have

$$|x| \leq |x'| \text{ and } x \circ x' \geq 0 \implies \|x\| \leq \|x'\|$$

where $x \circ x' = (x_1x'_1, \dots, x_dx'_d)$ is the Hadamard product

$$\text{and } \left. \begin{array}{l} |x_1| \leq |x'_1|, \dots, |x_d| \leq |x'_d| \\ \underbrace{x_1x'_1 \geq 0, \dots, x_dx'_d \geq 0}_{x, x' \text{ belong to the same orthant}} \end{array} \right\} \implies \|x\| \leq \|x'\|$$

Example of unit sphere of a non orthant-monotonic norm



In the bottom right orthant,
consider

$$|(0, -1)| \leq |(0.5, -1)|$$

and

$$(0, -1) \circ (0.5, -1) \geq (0, 0)$$

but

$$1 = \|(0, -1)\| > \|(0.5, -1)\|$$

Orthant-strictly monotonic norms

[Chancelier and De Lara, 2023]

Definition

A norm $\|\cdot\|$ on the space \mathbb{R}^d is called **orthant-strictly monotonic** (OSM) if, for all x, x' in \mathbb{R}^d , we have

$$|x| < |x'| \text{ and } x \circ x' \geq 0 \implies \|x\| < \|x'\|$$

where $|x| < |x'|$ means that there exists $j \in \llbracket 1, d \rrbracket$ such that $|x_j| < |x'_j|$

Intuition: $\epsilon \neq 0 \implies \|(0, *, 0, *, *, 0)\| < \|(0, *, \epsilon, *, *, 0)\|$

Examples of orthant-strictly monotonic norms

$$\|x\|_\infty = \sup_{i \in \llbracket 1, d \rrbracket} |x_i| \quad \text{and} \quad \|x\|_p = \left(\sum_{i=1}^d |x_i|^p \right)^{1/p} \quad \text{for } p \in [1, \infty[$$

- ▶ All the ℓ_p -norms $\|\cdot\|_p$ on the space \mathbb{R}^d , for $p \in [1, \infty[$, are monotonic, hence **orthant-monotonic**

$$\ell_1, \ell_2, \ell_\infty$$

- ▶ All the ℓ_p -norms $\|\cdot\|_p$ on the space \mathbb{R}^d , for $p \in [1, \infty[$, are **orthant-strictly monotonic**, but ℓ_∞ is not

$$\ell_1, \ell_2, \cancel{\ell_\infty}$$

$$|\epsilon| < 1 \implies \|(1, 0)\|_\infty = 1 = \|(1, \epsilon)\|_\infty$$

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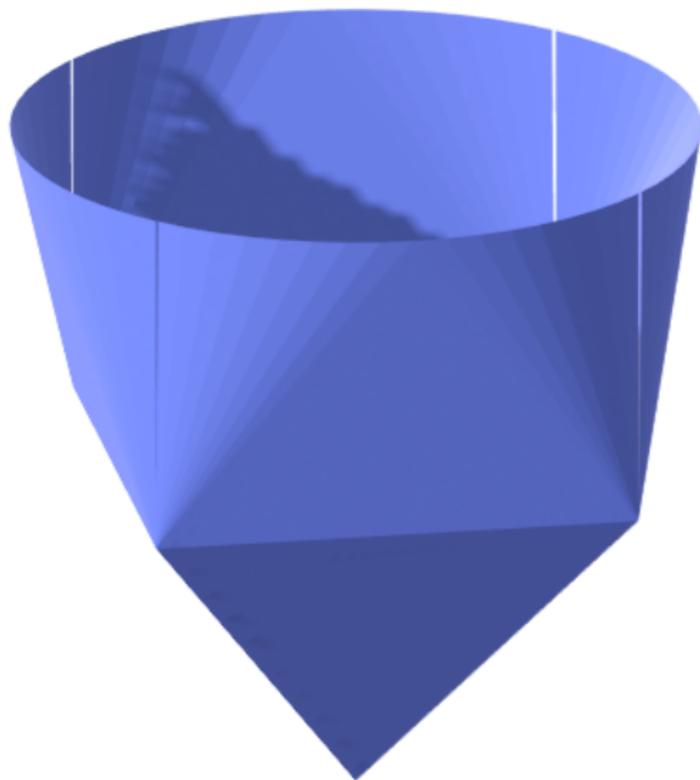
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Graph of the Euclidean ℓ_0 -cup function \mathcal{L}_0



Orthant-strictly monotonic norms and hidden convexity in the ℓ_0 pseudonorm

[Chancelier and De Lara, 2022b]

Theorem

If **both** the **norm** $\|\cdot\|$ and the **dual norm** $\|\cdot\|_*$ are **OSM**,
there exists a **proper convex lsc function** \mathcal{L}_0 such that

$$\ell_0(x) = \underbrace{\mathcal{L}_0}_{\substack{\text{convex lsc} \\ \text{function}}} \left(\frac{x}{\|x\|} \right), \quad \forall x \in \mathbb{R}^d \setminus \{0\}$$

and, as a consequence, the ℓ_0 **pseudonorm coincides**,
on the **unit sphere** S , with the proper convex lsc function \mathcal{L}_0

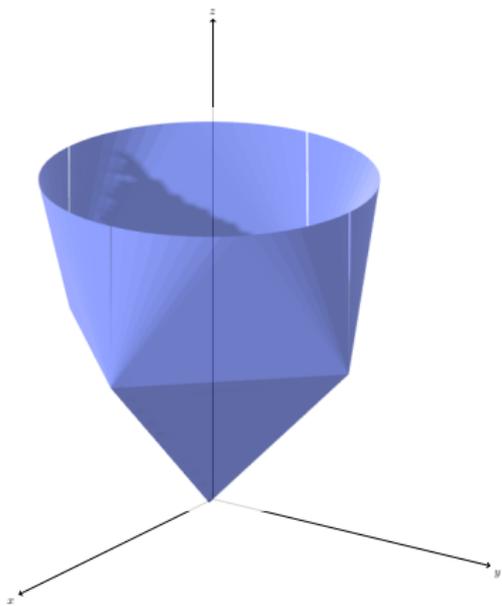
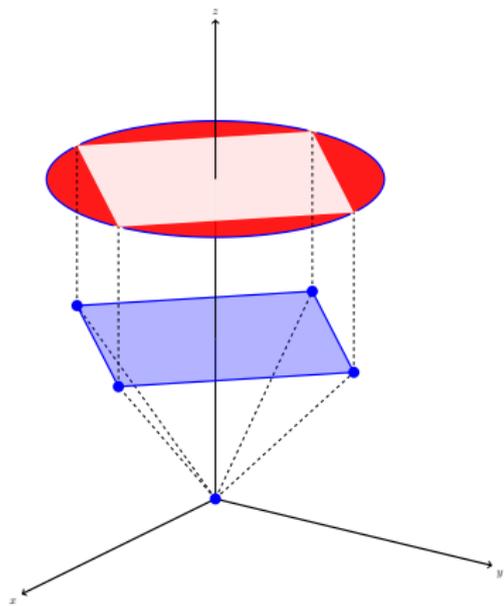
$$\ell_0(x) = \mathcal{L}_0(x), \quad \forall x \in S$$

The ℓ_0 -cup function as a convex envelope

Proposition

The proper convex lsc function \mathcal{L}_0 is the convex envelope of the following piecewise constant function

$$L_0(x) = \begin{cases} 0 & \text{if } x = 0 \\ 1 & \text{if } x \in B_{(1)}^{\top\star} \setminus \{0\} \\ 2 & \text{if } x \in B_{(2)}^{\top\star} \setminus B_{(1)}^{\top\star} \\ \dots & \dots \\ \ell & \text{if } x \in B_{(\ell)}^{\top\star} \setminus B_{(\ell-1)}^{\top\star}, \ell \in \llbracket 1, d \rrbracket \\ \dots & \dots \\ d & \text{if } x \in B_{(d)}^{\top\star} \setminus B_{(d-1)}^{\top\star} \\ +\infty & \text{if } x \notin B_{(d)}^{\top\star} = B \end{cases}$$



The ℓ_0 -cup function as best proper convex lsc lower approximation of the ℓ_0 pseudonorm on the unit ball

Theorem

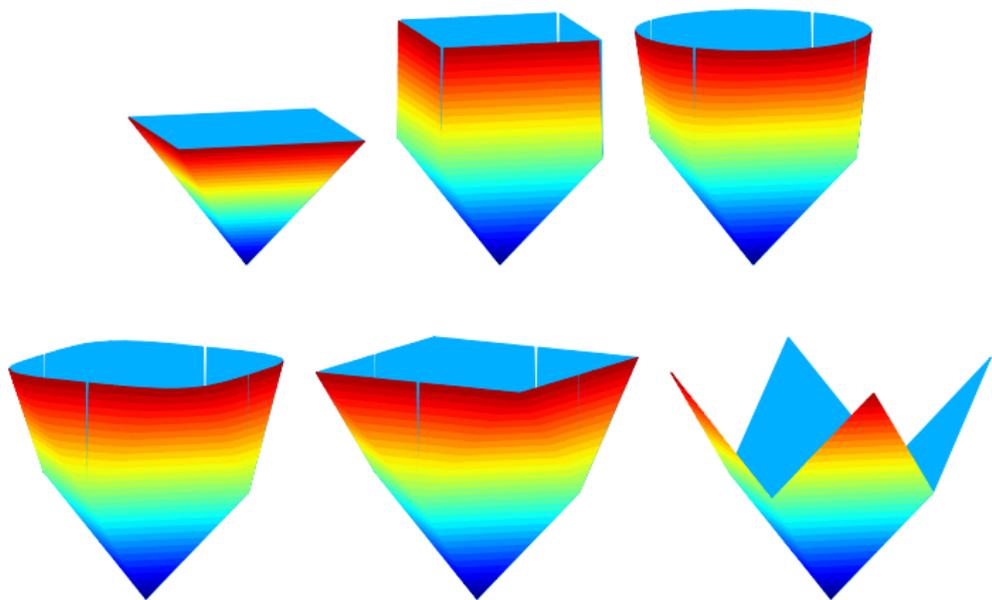
The ℓ_0 -cup function \mathcal{L}_0 is the best convex lsc lower approximation of the ℓ_0 pseudonorm on the unit ball B

$$\text{best convex lsc function} \quad \mathcal{L}_0(x) \leq \ell_0(x), \quad \forall x \in B$$

and coincides with the ℓ_0 pseudonorm on the unit sphere S

$$\ell_0(x) = \mathcal{L}_0(x), \quad \forall x \in S$$

Tightest closed convex function below the ℓ_0 pseudonorm
on the ℓ_p -unit balls on \mathbb{R}^2 for $p \in \{1, 1.1, 2, 4, 300, \infty\}$



Outline of the presentation

Design of sparsity-inducing unit balls [10 min]

What are sparsity-inducing norms/balls?

Exposed faces of unit balls with k -sparse extreme points

Support identification using k -sparsity inducing norms

Geometry of sparsity-inducing balls [6 min]

Orthant-strictly monotonicity and Capra-convexity of ℓ_0 [9 min]

Orthant-strictly monotonic (OSM) norms

OSM norms and hidden convexity in the ℓ_0 pseudonorm

Crash course on generalized convexity

OSM norms, Capra conjugacies and the ℓ_0 pseudonorm

Conclusion

Motivation: Legendre transform and Fenchel conjugacy in convex analysis

Definition

Two **vector spaces** \mathcal{X} and \mathcal{Y} , paired by a **bilinear form** $\langle \cdot, \cdot \rangle$, give rise to the classic **Fenchel conjugacy**

$$f \in \overline{\mathbb{R}}^{\mathcal{X}} \mapsto f^* \in \overline{\mathbb{R}}^{\mathcal{Y}}$$

given by the **Legendre transform**

$$f^*(y) = \sup_{x \in \mathcal{X}} \left(\langle x, y \rangle + (-f(x)) \right), \quad \forall y \in \mathcal{Y}$$

Coupling function between sets

- ▶ Let be given two sets \mathcal{X} (“primal”) and \mathcal{Y} (“dual”) not necessarily paired vector spaces (nodes and arcs, etc.)
- ▶ We consider a **coupling function**

$$c : \mathcal{X} \times \mathcal{Y} \rightarrow \overline{\mathbb{R}}$$

We also use the notation $\mathcal{X} \overset{c}{\leftrightarrow} \mathcal{Y}$ for a coupling
[Moreau, 1966-1967, 1970]

In duality in convex analysis, one uses the bilinear coupling

$$c(x, y) = \langle x, y \rangle$$

and, on a Hilbert space, the scalar product

$$c(x, y) = \langle x \mid y \rangle$$

Constant Along Primal RAYS (Capra) coupling

[Chancelier and De Lara, 2021, 2022a]

Definition

On the vector space \mathbb{R}^d , equipped with a (source) norm $\|\cdot\|$, the Capra coupling (Capra) $\mathbb{R}^d \overset{\dot{\phi}}{\longleftrightarrow} \mathbb{R}^d$ is given by

$$\forall y \in \mathbb{R}^d, \begin{cases} \dot{\phi}(x, y) = \frac{\langle x | y \rangle}{\|x\|}, \quad \forall x \in \mathbb{R}^d \setminus \{0\} \\ \dot{\phi}(0, y) = 0 \end{cases}$$

The coupling Capra has the property of being
Constant Along Primal RAYS (Capra)

Fenchel-Moreau conjugate of a function

$$f \in \overline{\mathbb{R}}^{\mathcal{X}} \mapsto f^c \in \overline{\mathbb{R}}^{\mathcal{Y}}$$

Definition

The c -Fenchel-Moreau conjugate $f^c : \mathcal{Y} \rightarrow \overline{\mathbb{R}}$ of a function $f : \mathcal{X} \rightarrow \overline{\mathbb{R}}$ is defined by

$$f^c(y) = \sup_{x \in \mathcal{X}} \left(c(x, y) \dot{+} (-f(x)) \right), \quad \forall y \in \mathcal{Y}$$

We use the Moreau *lower* and *upper* additions on $\overline{\mathbb{R}}$ that extend the usual addition with

$$(+\infty) \dot{+} (-\infty) = (-\infty) \dot{+} (+\infty) = -\infty$$

$$(+\infty) \dot{+} (-\infty) = (-\infty) \dot{+} (+\infty) = +\infty$$

Capra-conjugate of the ℓ_0 pseudonorm

[Chancelier and De Lara, 2021, 2022a]

$$\begin{aligned}\ell_0^{\dot{c}}(y) &= \sup_{x \in \mathbb{R}^d} \left\{ \dot{c}(x, y) \dot{+} (-\ell_0(x)) \right\} \\ &= \sup \left\{ 0, \sup_{x \neq 0} \left\{ \frac{\langle x \mid y \rangle}{\|x\|} - \ell_0(x) \right\} \right\} \\ &= \sup \left\{ 0, \sup_{s \in S} \left\{ \langle s \mid y \rangle - \ell_0(s) \right\} \right\}\end{aligned}$$

where $S \subset \mathbb{R}^d$ is the **unit sphere**

$$= \sup \left\{ 0, \sup_{i \in \llbracket 1, d \rrbracket} \left\{ \underbrace{\sup_{\substack{s \in S \\ \ell_0(s) = i}} \langle s \mid y \rangle}_{\text{coordinate-}i \text{ norm } \|y\|_{(i)}^{\mathcal{R}}} - i \right\} \right\}$$

$$= \sup_{i \in \llbracket 1, d \rrbracket} \left[\|y\|_{(i)}^{\mathcal{R}} - i \right]_+$$

Wrap-up on generalized/abstract convexity

▶ Generalized convexity

- ▶ coupling function between two sets

$$c : \mathcal{X} \times \mathcal{Y} \rightarrow \overline{\mathbb{R}}$$

- ▶ conjugacy and biconjugacy

$$f \in \overline{\mathbb{R}}^{\mathcal{X}} \mapsto f^c \in \overline{\mathbb{R}}^{\mathcal{Y}} \mapsto f^{cc'} \in \overline{\mathbb{R}}^{\mathcal{X}}$$

- ▶ generalized convex functions

$$f = f^{cc'}$$

- ▶ subdifferential

$$\partial^c f(x) \subset \mathcal{Y}$$

▶ Abstract convexity

- ▶ set of elementary functions

- ▶ abstract convex envelope:
supremum of lower elementary functions

- ▶ abstract convex function:
equal to its abstract convex envelope

- ▶ subdifferential:
tight lower elementary functions

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Conclusion

Capra = Fenchel coupling after primal normalization

- ▶ We define the primal **radial projection** ϱ as

$$\varrho : \mathbb{R}^d \rightarrow S \cup \{0\}, \quad \varrho(x) = \begin{cases} \frac{x}{\|x\|} & \text{if } x \neq 0 \\ 0 & \text{if } x = 0 \end{cases}$$

- ▶ so that the coupling Capra

$$\psi(x, y) = \langle \varrho(x) \mid y \rangle, \quad \forall x \in \mathbb{R}^d, \quad \forall y \in \mathbb{R}^d$$

appears as the **Fenchel coupling after primal normalization**
(and the coupling Capra is **one-sided linear**)

The Capra conjugacy shares properties with the Fenchel conjugacy

Proposition

- ▶ For any function $f : \mathbb{R}^d \rightarrow \overline{\mathbb{R}}$, the ζ -Fenchel-Moreau conjugate is given by

$$f^{\zeta} = (\inf [f \mid \varrho])^* \quad \text{where}$$

$$\inf [f \mid \varrho](x) = \begin{cases} \inf_{\rho > 0} f(\rho x) & \text{if } x \in S \cup \{0\} \\ +\infty & \text{if } x \notin S \cup \{0\} \end{cases}$$

- ▶ For any function $g : \mathbb{R}^d \rightarrow \overline{\mathbb{R}}$, the ζ' -Fenchel-Moreau conjugate is given by

$$g^{\zeta'} = g^{*'} \circ \varrho$$

The Capra-convex functions are 0-homogeneous and coincide, on the unit sphere, with a closed convex function

Proposition

ζ -convexity of the function $h : \mathbb{R}^d \rightarrow \overline{\mathbb{R}}$

$$\iff h = h^{\zeta\zeta'}$$

$$\iff h = \underbrace{(h^{\zeta})^{\star'}}_{\text{convex lsc function}} \circ \varrho$$

\iff **hidden convexity** in the function $h : \mathbb{R}^d \rightarrow \overline{\mathbb{R}}$

there exists a **closed convex function** $f : \mathbb{R}^d \rightarrow \overline{\mathbb{R}}$

such that $h = f \circ \varrho$, that is, $h(x) = f\left(\frac{x}{\|x\|}\right)$

[Chancelier and De Lara, 2022b]

Theorem

If **both** the **norm** $\|\cdot\|$ and the **dual norm** $\|\cdot\|_*$ are **orthant-strictly monotonic**, we have that

$$\partial_{\dot{C}} l_0(x) \neq \emptyset, \quad \forall x \in \mathbb{R}^d,$$

and, as a consequence,

$$l_0^{\dot{C}\dot{C}'} = l_0$$

and thus

$$l_0 = l_0^{\dot{C}\dot{C}'} = l_0^{\dot{C}*'} \circ \varrho = \underbrace{(l_0^{\dot{C}})^{*'}}_{\text{convex lsc function } \mathcal{L}_0} \circ \underbrace{\varrho}_{\text{radial projection}}$$

Variational formulas for the ℓ_0 pseudonorm

Proposition

$$\ell_0(x) = \frac{1}{\|x\|} \min_{\substack{x^{(1)} \in \mathbb{R}^d, \dots, x^{(d)} \in \mathbb{R}^d \\ \sum_{\ell=1}^d \|x^{(\ell)}\|_{(\ell)}^{\top\star} \leq \|x\| \\ \sum_{\ell=1}^d x^{(\ell)} = x}} \sum_{\ell=1}^d \ell \|x^{(\ell)}\|_{(\ell)}^{\top\star}, \quad \forall x \in \mathbb{R}^d$$

$$\ell_0(x) = \sup_{y \in \mathbb{R}^d} \inf_{\ell \in [1, d]} \left(\frac{\langle x | y \rangle}{\|x\|} - \left[\|y\|_{(\ell)}^{\top} - \ell \right]_+ \right), \quad \forall x \in \mathbb{R}^d \setminus \{0\}$$

Conclusion

- ▶ We have proposed systematic ways to design **unit balls** that **enhance sparsity** at a given **threshold**
- ▶ The corresponding norms originally appeared related to **Capra-convexity** of the ℓ_0 pseudonorm, as well as the property of **orthant-strict monotonicity**
- ▶ For classic ℓ_∞ , ℓ_2 and ℓ_1 source norms, we have a **complete description** of the corresponding **sparsity-inducing unit balls**

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Thank you :-)

