The Geometry of Sparsity-Inducing Balls

Jean-Philippe Chancelier, Michel De Lara

Cermics, École des Ponts ParisTech, France Antoine Deza McMaster University, Hamilton, Ontario, Canada Lionel Pournin Université Paris 13, Villetaneuse, France

EURO 2024, Copenhaguen, Denmark 30 June – 3 July 2024



▲ロ ▶ ▲周 ▶ ▲ 国 ▶ ▲ 国 ▶ ● の Q @

Support and the ℓ_0 pseudonorm

Let $d \in \mathbb{N}^*$ be a fixed natural number and

$$\llbracket 0, d \rrbracket = \{0, 1, \dots, d\}, \ \llbracket 1, d \rrbracket = \{1, \dots, d\}$$

For any vector $x \in \mathbb{R}^d$, we define

its support by

 $\operatorname{supp}(x) = \left\{ j \in \llbracket 1, d \rrbracket \mid x_j \neq 0 \right\}$

$$\mathrm{supp}((0,*,0,*,*,0))=\{2,4,5\}\subset [\![1,6]\!]$$

• its ℓ_0 pseudonorm(x) by



・ロト ・ 戸 ・ ・ ヨ ・ ・ ヨ ・ ・ つ へ ()

The ℓ_0 pseudonorm is not a norm

The function ℓ_0 pseudonorm : $\mathbb{R}^d \to [\![0, d]\!]$ satisfies 3 out of 4 axioms of a norm

we have
$$\ell_0(x) \ge 0$$
 \(\lambda\)
we have $\left(\ell_0(x) = 0 \iff x = 0 \right)$ \(\lambda\)
we have $\ell_0(x + x') \le \ell_0(x) + \ell_0(x')$ \(\lambda\)
But... instead of 1-homogeneity,

it is 0-homogeneity that holds true

 $\ell_0(\rho x) = \ell_0(x) , \ \forall \rho \neq 0$ $\operatorname{supp}(\rho x) = \operatorname{supp}(x) , \ \forall \rho \neq 0$

Talk outline

Design of sparsity-inducing unit balls [10 min]

What are sparsity-inducing norms/balls? Exposed faces of unit balls with *k*-sparse extreme points Support identification using *k*-sparsity inducing norms

Geometry of sparsity-inducing balls [5 min]

Orthant-strictly monotonicity and Capra-convexity of ℓ_0 [5 min] Orthant-strictly monotonic (OSM) norms OSM norms and hidden convexity in the ℓ_0 pseudonorm Crash course on generalized convexity OSM norms, Capra conjugacies and the ℓ_0 pseudonorm

Conclusion

Outline of the presentation

Design of sparsity-inducing unit balls [10 min]

Geometry of sparsity-inducing balls [5 min]

Orthant-strictly monotonicity and Capra-convexity of ℓ_0 [5 min]

Conclusion

▲□▶ ▲□▶ ▲目▶ ▲目▶ 目 のへで

Outline of the presentation

Design of sparsity-inducing unit balls [10 min] What are sparsity-inducing norms/balls?

Exposed faces of unit balls with *k*-sparse extreme points Support identification using *k*-sparsity inducing norms

Geometry of sparsity-inducing balls [5 min]

Orthant-strictly monotonicity and Capra-convexity of ℓ_0 [5 min] Orthant-strictly monotonic (OSM) norms OSM norms and hidden convexity in the ℓ_0 pseudonorm Crash course on generalized convexity OSM norms, Capra conjugacies and the ℓ_0 pseudonorm

Conclusion

Archetypal sparse optimization problems For $X \subset \mathbb{R}^d$ a nonempty set,

minimal ℓ_0 pseudonorm

 $\min_{x\in X}\ell_0(x)$

is an optimization problem for which any point in X is a local minimizer Jean-Baptiste Hiriart-Urruty and Hai Le. A variational approach of the rank function. *TOP: An Official Journal of the Spanish Society of Statistics and Operations Research*, 21 (2):207–240, 2013.

For $k \in \llbracket 1, d \rrbracket$ and a function $f : \mathbb{R}^d \to \overline{\mathbb{R}}$,

optimal k-sparse vector



A D N A 目 N A E N A E N A B N A C N

• For $\gamma > 0$ and a function $f : \mathbb{R}^d \to \overline{\mathbb{R}}$,

 $\min_{x \in \mathbb{R}^d} \left(f(x) + \underbrace{\gamma \ell_0(x)} \right)$ sparse penalty

The intuition behind lasso

$$\min_{x \in \mathbb{R}^d} \left(f(x) + \gamma \left\| x \right\|_1 \right)$$



$$\min_{x \in \mathbb{R}^d} \left(f(x) + \gamma \left\| x \right\|_2 \right)$$

Comments of [Tibshirani, 1996, Figure 2]

> "The lasso solution is the first place that the contours touch the square, and this will sometimes occur at a corner, corresponding to a zero coefficient. The picture for ridge regression is shown in Fig. 2(b): there are no corners for the contours to hit and hence zero solutions will rarely result."

Robert Tibshirani. Regression shrinkage and selection via the lasso. Journal of the Royal Statistical Society. Series B (Methodological), 58(1):267–288, 1996

Kinks stand at sparse points



▲□▶▲□▶▲≡▶▲≡▶ ≡ のへ⊙

Geometric (alignment) expression of optimality condition

• We consider an optimal solution $x^* \neq 0$ of

$$\min_{\mathbf{x}\in\mathbb{R}^d}\left(f(\mathbf{x})+\gamma\|\mathbf{x}\|\right)$$

where $f : \mathbb{R}^d \to \mathbb{R}$ is a smooth convex function, $\gamma > 0$ and $\| \cdot \|$ is a norm with unit ball B



▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

We expect that the support of x* can be recovered from dual information −∇f(x*)

Outline of the presentation

Design of sparsity-inducing unit balls [10 min]
What are sparsity-inducing norms/balls?
Exposed faces of unit balls with *k*-sparse extreme points
Support identification using *k*-sparsity inducing norms

Geometry of sparsity-inducing balls [5 min]

Orthant-strictly monotonicity and Capra-convexity of ℓ_0 [5 min] Orthant-strictly monotonic (OSM) norms OSM norms and hidden convexity in the ℓ_0 pseudonorm Crash course on generalized convexity OSM norms, Capra conjugacies and the ℓ_0 pseudonorm

Conclusion

We reformulate sparsity in terms of coordinate subspaces

$$y = (*, *, *, *, *, *) \to \pi_{\{2,4,5\}}(y) = (0, *, 0, *, *, 0) \in \mathcal{R}_{\{2,4,5\}}$$

For any $K \subset [1, d]$, we introduce the (coordinate) subspace

$$\mathcal{R}_{K} = \left\{ y \in \mathbb{R}^{d} \ \middle| \ y_{j} = 0 \ , \ \forall j \notin K
ight\} \subset \mathbb{R}^{d}$$

• The connection with the level sets of the ℓ_0 pseudonorm is

$$\ell_0^{\leq k} = \underbrace{\left\{x \in \mathbb{R}^d \mid \ell_0(x) \leq k\right\}}_{k \text{-sparse vectors}} = \bigcup_{|\mathcal{K}| \leq k} \mathcal{R}_{\mathcal{K}} \ , \ \forall k \in \llbracket 0, d \rrbracket$$

We denote by π_K : ℝ^d → R_K the orthogonal projection For any vector y ∈ ℝ^d, π_K(y) ∈ R_K ⊂ ℝ^d is the vector whose components coincide with those of y, except for those outside of K that vanish Design of unit ball with *k*-sparse extreme points

(for example, 2-sparse points in \mathbb{R}^3)

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三三 - のへぐ

Design of unit ball with k-sparse extreme points

For given sparsity threshold $k \in [\![1, d]\!]$, we consider a source norm $\|\cdot\|$, with unit ball *B*, and we

▶ project *B* onto $\ell_0^{\leq k}$,

form the convex hull and get

$$B_{\star,(k)}^{\top\star} = \operatorname{co}\big(\bigcup_{|K| \le k} \pi_K(B)\big)$$

A D N A 目 N A E N A E N A B N A C N

unit ball of the generalized *k*-support dual norm $\|\cdot\|_{\star,(k)}^{\top \star}$ [Chancelier and De Lara, 2022b]

► the extreme points belong to U_{|K|≤k} R_K = ℓ₀^{≤k}, hence are k-sparse vectors

Generalized top-k and k-support dual norms

Chancelier and De Lara [2022b]. Definition For any source norm $\|\cdot\|$ on \mathbb{R}^d , for any $k \in [\![1,d]\!]$, • the generalized k-support dual norm $\|\cdot\|_{+(k)}^{+\star}$ is the dual norm $\|\cdot\|_{\star,(k)}^{\top\star} = (\|\cdot\|_{\star,(k)}^{\top})_{\star}$ • of the generalized top-k dual norm $\|\cdot\|_{\star,(k)}^{\top}$ defined by k-sparse projection on \mathcal{R}_{κ} $\|y\|_{\star,(k)}^{ op} = \sup_{|\mathcal{K}| \leq k} \| \widetilde{\pi_{\mathcal{K}}(y)} \|_{\star}, \ \forall y \in \mathbb{R}^d$ exploring all k-sparse projections

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 三臣 - の々で

Exposed faces characterization

Exposed faces characterization

Theorem

Let $k \in \llbracket 1, d \rrbracket$ Then, for any nonzero dual vector $y \in \mathbb{R}^d \setminus \{0\}$, the exposed face of the unit ball $B_{\star,(k)}^{\top \star}$ is given by

$$F_{\perp}(B_{\star,(k)}^{\top_{\star}}, y) = \overline{\operatorname{co}}\left\{\underbrace{\pi_{K^{\star}}(F_{\perp}(B, \pi_{K^{\star}}y))}_{\substack{\exp \operatorname{osed face}\\ \operatorname{of the original}\\ \operatorname{unit ball}}}: K^{\star} \in \underset{|K| \leq k}{\operatorname{arg\,max}} \|\pi_{K}y\|_{\star}\right\}$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

Exposed faces characterization

Theorem

Let $k \in [\![1,d]\!]$ Suppose that the source norm $\|\cdot\|$ is orthant-strictly monotonic

Then, for any nonzero dual vector $y \in \mathbb{R}^d \setminus \{0\}$, the exposed face of the unit ball $B_{\star,(k)}^{\top \star}$ is given by

$$F_{\perp}(B_{\star,(k)}^{\top\star}, y) = \overline{\operatorname{co}}\left\{\underbrace{F_{\perp}(B, \pi_{K^{*}}y)}_{\text{exposed face}}: K^{*} \in \underset{|K| \leq k}{\operatorname{arg max}} \|\pi_{K}y\|_{\star}\right\}$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

of the original unit ball

Outline of the presentation

Design of sparsity-inducing unit balls [10 min]

What are sparsity-inducing norms/balls? Exposed faces of unit balls with *k*-sparse extreme points Support identification using *k*-sparsity inducing norms

Geometry of sparsity-inducing balls [5 min]

Orthant-strictly monotonicity and Capra-convexity of ℓ_0 [5 min] Orthant-strictly monotonic (OSM) norms OSM norms and hidden convexity in the ℓ_0 pseudonorm Crash course on generalized convexity OSM norms, Capra conjugacies and the ℓ_0 pseudonorm

Conclusion

Support identification: main result



◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 三臣 - のへで

Sparse support identification: corollary

Corollary

Let $f: \mathbb{R}^d \to \mathbb{R}$ be a smooth convex function and $\gamma > 0$

For given sparsity threshold $k \in \llbracket 1, d \rrbracket$, if an optimal solution x^* of

$$\min_{\mathbf{x}\in\mathbb{R}^d}\left(f(\mathbf{x})+\gamma\|\mathbf{x}\|_{\star,(\mathbf{k})}^{\mathsf{T}_{\star}}\right)$$

satisfies

 $\underset{|\mathcal{K}| \leq k}{\arg \max} \|\pi_{\mathcal{K}}(-\nabla f(x^*))\|_{\star} = \mathcal{K}^* \quad \text{is unique}$

then it has support

```
\operatorname{supp}(x^*) \subset K^* with |K^*| \leq k
```

so that the optimal solution x^* is k-sparse

Support identification: Lasso

Corollary

Let $f : \mathbb{R}^d \to \mathbb{R}$ be a smooth convex function, $\gamma > 0$ and $\|\cdot\|_1$ be the ℓ_1 norm

An optimal solution x^* of

 $\min_{x \in \mathbb{R}^d} \left(f(x) + \gamma \|x\|_1 \right)$

has support

 $\operatorname{supp}(x^*) \subset \arg\max_{j \in \llbracket 1,d \rrbracket} |\nabla_j f(x^*)|$

Outline of the presentation

Design of sparsity-inducing unit balls [10 min]

Geometry of sparsity-inducing balls [5 min]

Orthant-strictly monotonicity and Capra-convexity of ℓ_0 [5 min]

Conclusion

▲□▶ ▲□▶ ▲目▶ ▲目▶ 目 のへで

The case of ℓ_p -norms $\|\cdot\|_p$

$$||x||_{\infty} = \sup_{i \in [\![1,d]\!]} |x_i| \text{ and } ||x||_p = \left(\sum_{i=1}^d |x_i|^p\right)^{1/p} \text{ for } p \in [1,\infty[$$

▲□▶ ▲圖▶ ▲≣▶ ▲≣▶ = のへで

source norm $\ \cdot\ $	$\ \cdot\ _{\star,(k)}^{ op},k\in\llbracket 1,d rbracket$	$\ \cdot\ _{\star,(k)}^{ op},k\in\llbracket 1,d rbracket$
· _p	top- (q,k) norm	(p,k)-support norm
	$\ y\ _{q,k}^{\top}$	$\ \mathbf{x}\ _{p,k}^{\top\star}$
	$\ y\ _{q,k}^{\top} = \left(\sum_{l=1}^{k} y_{\nu(l)} ^{q}\right)^{\frac{1}{q}}$	no analytic expression
$\ \cdot\ _1$	top- (∞, k) norm	(1,k)-support norm
	ℓ_{∞} -norm	ℓ_1 -norm
	$\ y\ _{\infty,k}^{ op} = \ y\ _{\infty}, \forall k \in \llbracket 1, d \rrbracket$	$\ x\ _{1,k}^{ op\star} = \ x\ _1$, $\forall k \in \llbracket 1, d rbracket$
$\ \cdot\ _{2}$	top-(2,k) norm	(2,k)-support norm
	$\ y\ _{2,k}^{\top} = \sqrt{\sum_{l=1}^{k} y_{\nu(l)} ^2}$	$ x _{2,k}^{\top \star}$ no analytic expression
	V V=1 (V	(computation [Argyriou et al., 2012, Prop. 2.1])
	$\ y\ _{2,1}^{\top} = \ y\ _{\infty}$	$ x _{2,1}^{\top\star} = x _1$
$\ \cdot\ _{\infty}$	top-(1,k) norm	(∞, k) -support norm
	$\ y\ _{1,k}^{\top} = \sum_{l=1}^{k} y_{\nu(l)} $	$\ x\ _{\infty,k}^{\top_{\star}} = \max\{\frac{\ x\ _1}{k}, \ x\ _{\infty}\}$
	$\ \mathbf{v}\ _{\mathbf{r}}^{\top} = \ \mathbf{v}\ $	$\ x\ _{T^{*}}^{T^{*}} = \ x\ _{T^{*}}$

Table: Examples of generalized top-k and k-support dual norms generated by the ℓ_p source norms $\|\cdot\| = \|\cdot\|_p$ for $p \in [1, \infty]$, where 1/p + 1/q = 1. For $y \in \mathbb{R}^d$, ν denotes a permutation of $\{1, \ldots, d\}$ such that $|y_{\nu(1)}| \ge |y_{\nu(2)}| \ge \cdots \ge |y_{\nu(d)}|$.

When the source norm is the $\ell_\infty\text{-norm}$

Case k = 2 in \mathbb{R}^3 with source norm the ℓ_{∞} -norm



(a) Unit ball $B_{\infty,2}^{\top\star}$ (support norm) (b) Unit ball $B_{1,2}^{\top}$ (top norm)

▲□▶ ▲□▶ ▲ □▶ ▲ □▶ □ のへぐ

When the source norm is the $\ell_2\text{-norm}$

Case k = 2 in \mathbb{R}^3 with source norm the ℓ_2 -norm



(a) Unit ball $B_{2,2}^{\top \star}$ (support norm)



(b) Unit ball $B_{2,2}^{\top}$ (top norm)

▲□▶ ▲□▶ ▲ □▶ ▲ □▶ □ のへぐ

Geometric description

Proposition

For any $k \in [\![1,d]\!]$, all the proper faces of $B_{2,k}^{\top\star}$ are hypersimplices, and the normal fan of $B_{2,k}^{\top\star}$ refines the normal fan of $B_{\infty,k}^{\top\star}$



When the source norm is the $\ell_1\text{-norm}$

Case k = 2 in \mathbb{R}^3 with source norm the ℓ_1 -norm



▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへで

What comes next?

- What are orthant-strictly monotonic norms?
- ▶ In what are they related to the ℓ_0 pseudonorm?

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Background on the original motivation Jean-Philippe Chancelier, Michel De Lara Design of sparsity-inducing unit balls [10 min]

Geometry of sparsity-inducing balls [5 min]

Orthant-strictly monotonicity and Capra-convexity of ℓ_0 [5 min]

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Conclusion

Outline of the presentation

Design of sparsity-inducing unit balls [10 min]
 What are sparsity-inducing norms/balls?
 Exposed faces of unit balls with k-sparse extreme points
 Support identification using k-sparsity inducing norms

Geometry of sparsity-inducing balls [5 min]

Orthant-strictly monotonicity and Capra-convexity of ℓ_0 [5 min] Orthant-strictly monotonic (OSM) norms

OSM norms and hidden convexity in the ℓ_0 pseudonorm Crash course on generalized convexity OSM norms, Capra conjugacies and the ℓ_0 pseudonorm

Conclusion

Orthant-monotonic norms

For any $x \in \mathbb{R}^d$, we denote by |x|the vector of \mathbb{R}^d with components $|x_i|$, $i \in \llbracket 1, d \rrbracket$

Definition

A norm $\|\cdot\|$ on the space \mathbb{R}^d is called orthant-monotonic [Gries, 1967] if, for all x, x' in \mathbb{R}^d , we have

$$|x| \le |x'|$$
 and $x \circ x' \ge 0 \implies ||x|| \le ||x'||$

where $x \circ x' = (x_1 x'_1, \dots, x_d x'_d)$ is the Hadamard (entrywise) product

and
$$\begin{vmatrix} |x_1| \le |x_1'| \ , \ \dots \ , \ |x_d| \le |x_d'| \\ x_1 x_1' \ge 0 \ , \ \dots \ , \ x_d x_d' \ge 0 \end{vmatrix} \right\} \implies ||x|| \le ||x'||$$

◆□▶ ◆□▶ ◆目▶ ◆目▶ 目 のへぐ

Example of unit sphere of a non orthant-monotonic norm



In the bottom right orthant, consider $|(0,-1)| \leq |(0.5,-1)|$ and $(0, -1) \circ (0.5, -1) > (0, 0)$ but $1 = \|(0, -1)\| > \|(0.5, -1)\|$

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ● □ ● ● ● ●

Orthant-strictly monotonic norms

[Chancelier and De Lara, 2023]

Definition

A norm $\|\cdot\|$ on the space \mathbb{R}^d is called orthant-strictly monotonic if, for all x, x' in \mathbb{R}^d , we have

$$|x| < |x'|$$
 and $x \circ x' \ge 0 \implies ||x|| < ||x'||$

where |x| < |x'| means that there exists $j \in \llbracket 1, d \rrbracket$ such that $|x_i| < |x'_i|$

Intuition: $\epsilon \neq 0 \implies ||(0, *, 0, *, *, 0)|| < ||(0, *, \epsilon, *, *, 0)||$

Examples of orthant-strictly monotonic norms

$$\|x\|_{\infty} = \sup_{i \in \llbracket 1,d \rrbracket} |x_i| \text{ and } \|x\|_p = \left(\sum_{i=1}^d |x_i|^p\right)^{1/p} \text{ for } p \in [1,\infty[$$

with unit ball B_p and unit sphere S_p

All the ℓ_p-norms ||·||_p on the space ℝ^d, for p ∈ [1,∞], are monotonic, hence orthant-monotonic

$$\ell_1, \ell_2, \ell_\infty$$

All the ℓ_p-norms ||·||_p on the space ℝ^d, for p ∈ [1,∞[, are orthant-strictly monotonic

$$\ell_1, \ell_2, \ell_\infty$$

 $|\epsilon| < 1 \implies \|(1,0)\|_{\infty} = 1 = \|(1,\epsilon)\|_{\infty}$

Outline of the presentation

Design of sparsity-inducing unit balls [10 min] What are sparsity-inducing norms/balls? Exposed faces of unit balls with k-sparse extreme points Support identification using k-sparsity inducing norms

Geometry of sparsity-inducing balls [5 min]

Orthant-strictly monotonicity and Capra-convexity of ℓ_0 [5 min] Orthant-strictly monotonic (OSM) norms OSM norms and hidden convexity in the ℓ_0 pseudonorm Crash course on generalized convexity OSM norms, Capra conjugacies and the ℓ_0 pseudonorm

Conclusion

Graph of the Euclidean $\ell_0\text{-}\mathsf{cup}$ function \mathcal{L}_0



▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

Orthant-strictly monotonic norms and hidden convexity in the ℓ_0 pseudonorm

[Chancelier and De Lara, 2022b]

Theorem

If both the norm $\|\cdot\|$ and the dual norm $\|\cdot\|_{\star}$ are orthant-strictly monotonic, there exists a proper convex lsc function \mathcal{L}_0 , the ℓ_0 -cup function, with domain the unit ball B, such that

$$\ell_0(x) = \underbrace{\mathcal{L}_0}_{\substack{\text{convex lsc} \\ \text{function}}} \left(\frac{x}{\|x\|} \right), \ \forall x \in \mathbb{R}^d \setminus \{0\}$$

and, as a consequence, the ℓ_0 pseudonorm coincides, on the unit sphere *S*, with the proper convex lsc function \mathcal{L}_0

 $\ell_0(x) = \mathcal{L}_0(x) , \ \forall x \in S$

The ℓ_0 -cup function as a convex envelope

Proposition

The proper convex lsc function \mathcal{L}_0 is the convex envelope of the following piecewise constant function

$$L_0(x) = \begin{cases} 0 & \text{if } x = 0, \\ \ell & \text{if } x \in B_{(\ell)}^{\top_{\star}} \backslash B_{(\ell-1)}^{\top_{\star}} , \ \ell \in \llbracket 1, d \rrbracket \\ +\infty & \text{if } x \notin B_{(n)}^{\top_{\star}} = B \end{cases}$$



The ℓ_0 -cup function as best proper convex lsc lower approximation of the ℓ_0 pseudonorm on the unit ball

Theorem

The ℓ_0 -cup function \mathcal{L}_0 is the best convex lsc lower approximation of the ℓ_0 pseudonorm on the unit ball B

best convex lsc function $\mathcal{L}_0(x) \leq \ell_0(x)$, $\forall x \in B$

and, as seen above, coincides with the ℓ_0 pseudonorm

on the unit sphere S

 $\ell_0(x) = \mathcal{L}_0(x) , \ \forall x \in S_2$

Tightest closed convex function below the ℓ_0 pseudonorm on the ℓ_p -unit balls on \mathbb{R}^2 for $p \in \{1, 1.1, 2, 4, 300, \infty\}$



▲ロト ▲母 ト ▲目 ト ▲目 ト ● ○ ○ ○ ○ ○

Outline of the presentation

Design of sparsity-inducing unit balls [10 min] What are sparsity-inducing norms/balls? Exposed faces of unit balls with k-sparse extreme points Support identification using k-sparsity inducing norms

Geometry of sparsity-inducing balls [5 min]

Orthant-strictly monotonicity and Capra-convexity of ℓ_0 [5 min]

Orthant-strictly monotonic (OSM) norms OSM norms and hidden convexity in the ℓ_0 pseudonorm **Crash course on generalized convexity** OSM norms, Capra conjugacies and the ℓ_0 pseudonorm

Conclusion

Motivation: Legendre transform and Fenchel conjugacy in convex analysis

Definition

Two vector spaces \mathcal{X} and \mathcal{Y} , paired by a bilinear form \langle , \rangle , give rise to the classic Fenchel conjugacy

$$f \in \overline{\mathbb{R}}^{\mathcal{X}} \mapsto f^{\star} \in \overline{\mathbb{R}}^{\mathcal{Y}}$$

given by the Legendre transform

$$f^{\star}(y) = \sup_{x \in \mathcal{X}} \left(\langle x, y \rangle + (-f(x)) \right), \ \forall y \in \mathcal{Y}$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

Coupling function between sets

- Let be given two sets X ("primal") and Y ("dual") not necessarily paired vector spaces (nodes and arcs, etc.)
- We consider a coupling function

 $c: \mathcal{X} \times \mathcal{Y} \to \overline{\mathbb{R}}$

We also use the notation $\mathcal{X} \stackrel{c}{\leftrightarrow} \mathcal{Y}$ for a coupling [Moreau, 1966-1967, 1970]

In duality in convex analysis, one uses the bilinear coupling

$$c(x,y) = \langle x, y \rangle$$

and, on a Hilbert space, the scalar product

$$c(x,y) = \langle x \mid y \rangle$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Constant Along Primal RAys (Capra) coupling

[Chancelier and De Lara, 2021, 2022a]

Definition

On the vector space \mathbb{R}^d , equipped with a (source) norm $\|\cdot\|$, the Capra coupling (Capra) $\mathbb{R}^d \stackrel{\diamond}{\longleftrightarrow} \mathbb{R}^d$ is given by

$$\forall y \in \mathbb{R}^{d} , \begin{cases} \dot{\varphi}(x, y) &= \frac{\langle x \mid y \rangle}{\|x\|} , \ \forall x \in \mathbb{R}^{d} \setminus \{0\} \\ \dot{\varphi}(0, y) &= 0 \end{cases}$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

The coupling Capra has the property of being Constant Along Primal RAys (Capra)

Fenchel-Moreau conjugate of a function

$$f \in \overline{\mathbb{R}}^{\mathcal{X}} \mapsto f^{c} \in \overline{\mathbb{R}}^{\mathcal{Y}}$$

Definition

The *c*-Fenchel-Moreau conjugate $f^c : \mathcal{Y} \to \mathbb{R}$ of a function $f : \mathcal{X} \to \mathbb{R}$ is defined by

$$f^{c}(y) = \sup_{x \in \mathcal{X}} \left(c(x, y) + (-f(x)) \right), \ \forall y \in \mathcal{Y}$$

We use the Moreau lower and upper additions on $\overline{\mathbb{R}}$ that extend the usual addition with

$$(+\infty) \div (-\infty) = (-\infty) \div (+\infty) = -\infty$$
$$(+\infty) \div (-\infty) = (-\infty) \div (+\infty) = +\infty$$

▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへの

Capra-conjugate of the ℓ_0 pseudonorm

[Chancelier and De Lara, 2021, 2022a]

 ℓ_0^{c}

$$\begin{aligned} (\mathbf{y}) &= \sup_{x \in \mathbb{R}^d} \left\{ \dot{\mathbf{c}}(x, y) + (-\ell_0(x)) \right\} \\ &= \sup \left\{ 0, \sup_{x \neq 0} \left\{ \frac{\langle x \mid y \rangle}{\|x\|} - \ell_0(x) \right\} \right\} \\ &= \sup \left\{ 0, \sup_{s \in S} \left\{ \langle s \mid y \rangle - \ell_0(s) \right\} \right\} \\ &\text{where } \mathbf{S} \subset \mathbb{R}^d \text{ is the unit sphere} \\ &= \sup \left\{ 0, \sup_{j \in \llbracket 1, d \rrbracket} \left\{ \sup_{\substack{s \in S \\ \ell_0(s) = j \\ \text{coordinate-}j \text{ norm } \lVert \mathbf{y} \rVert_{(j)}^{\mathcal{R}} \right\} \end{aligned}$$

▲□▶ ▲□▶ ▲ □▶ ▲ □▶ □ のへぐ

$$= \sup_{j \in \llbracket 1,d \rrbracket} \left[\|y\|_{(j)}^{\mathcal{R}} - j \right]_{+}$$

Wrap-up on generalized/abstract convexity

Generalized convexity coupling function between two sets $c: \mathcal{X} \times \mathcal{V} \to \overline{\mathbb{R}}$ conjugacy and biconjugacy $f \in \overline{\mathbb{R}}^{\mathcal{X}} \mapsto f^{c} \in \overline{\mathbb{R}}^{\mathcal{Y}} \mapsto f^{cc'} \in \overline{\mathbb{R}}^{\mathcal{X}}$ generalized convex functions $f = f^{cc'}$ subdifferential $\partial^{c} f(x) \subset \mathcal{Y}$ Abstract convexity set of elementary functions abstract convex envelope: supremum of lower elementary functions abstract convex function: equal to its abstract convex envelope subdifferential: tight lower elementary functions

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

Outline of the presentation

Design of sparsity-inducing unit balls [10 min] What are sparsity-inducing norms/balls? Exposed faces of unit balls with k-sparse extreme points Support identification using k-sparsity inducing norms

Geometry of sparsity-inducing balls [5 min]

Orthant-strictly monotonicity and Capra-convexity of ℓ_0 [5 min]

Orthant-strictly monotonic (OSM) norms OSM norms and hidden convexity in the ℓ_0 pseudonorm Crash course on generalized convexity

OSM norms, Capra conjugacies and the ℓ_0 pseudonorm

Conclusion

Capra = Fenchel coupling after primal normalization

• We define the primal radial projection ϱ as

$$\varrho: \mathbb{R}^d \to S \cup \{0\} , \ \varrho(x) = \begin{cases} \frac{x}{\|x\|} & \text{if } x \neq 0 \\ \\ \frac{0}{0} = 0 & \text{if } x = 0 \end{cases}$$

so that the coupling Capra

$$c(x,y) = \langle \varrho(x) \mid y \rangle \ , \ \forall x \in \mathbb{R}^d \ , \ \forall y \in \mathbb{R}^d$$

appears as the Fenchel coupling after primal normalization (and the coupling Capra is one-sided linear)

The Capra conjugacy shares properties with the Fenchel conjugacy

Proposition

For any function $f : \mathbb{R}^d \to \overline{\mathbb{R}}$, the \diamond -Fenchel-Moreau conjugate is given by

$$f^{\mathbb{C}} = \left(\inf \left[f \mid \varrho\right]\right)^{*} \quad \text{where}$$
$$\inf \left[f \mid \varrho\right](x) = \begin{cases} \inf_{\rho > 0} f(\rho x) & \text{if } x \in S \cup \{0\} \\ +\infty & \text{if } x \notin S \cup \{0\} \end{cases}$$

 For any function g : ℝ^d → ℝ, the ¢'-Fenchel-Moreau conjugate is given by

$$g^{c'} = g^{\star'} \circ \varrho$$

The Capra-convex functions are 0-homogeneous and coincide, on the unit sphere, with a closed convex function

Proposition

¢-convexity of the function $h : \mathbb{R}^d \to \overline{\mathbb{R}}$ $\iff h = h^{cc'}$ $\iff h = \underbrace{\left(h^{c}\right)^{\star'}}_{\bullet} \circ \varrho$ convex lsc function \iff hidden convexity in the function $h : \mathbb{R}^d \to \overline{\mathbb{R}}$ there exists a closed convex function $f : \mathbb{R}^d \to \overline{\mathbb{R}}$ such that $h = f \circ \varrho$, that is, $h(x) = f\left(\frac{x}{\|x\|}\right)$

[Chancelier and De Lara, 2022b]

Theorem

If both the norm $\|\cdot\|$ and the dual norm $\|\cdot\|_*$ are orthant-strictly monotonic, we have that

$$\partial_{\dot{\mathbb{C}}}\ell_0(x) \neq \emptyset , \ \forall x \in \mathbb{R}^d ,$$

and, as a consequence,

$$\ell_0^{\dot C\dot C'}=\ell_0$$

and thus

$$\ell_{0} = \ell_{0}^{\dot{\varphi}\dot{\varphi}'} = \ell_{0}^{\dot{\varphi}\star'} \circ \varrho = \underbrace{\left(\ell_{0}^{\dot{\varphi}}\right)^{\star'}}_{\substack{\text{convex lsc} \\ \text{function } \mathcal{L}_{0}}} \circ \underbrace{\rho}^{\text{radial}}_{\varrho}$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

Variational formulas for the ℓ_0 pseudonorm

Proposition $\ell_{0}(x) = \frac{1}{\|x\|} \min_{\substack{x^{(1)} \in \mathbb{R}^{d}, \dots, x^{(d)} \in \mathbb{R}^{d} \\ \sum_{\ell=1}^{d} \|x^{(\ell)}\|_{(\ell)}^{\top_{*}} \le \|x\|}} \sum_{\ell=1}^{d} \ell \|x^{(\ell)}\|_{(\ell)}^{\top_{*}}, \ \forall x \in \mathbb{R}^{d}$ $\sum_{\ell=1}^{d} x^{(\ell)} = x$

$$\ell_0(x) = \sup_{y \in \mathbb{R}^d} \inf_{\ell \in \llbracket 1, d \rrbracket} \left(\frac{\langle x + y \rangle}{\|x\|} - \left\lfloor \|y\|_{(\ell)}^{\perp} - \ell \right\rfloor_+ \right), \ \forall x \in \mathbb{R}^d \setminus \{0\}$$

Conclusion

- We have proposed systematic ways to design unit balls that enhance sparsity at a given threshold
- ► The corresponding norms originally appeared related to generalized Capra-convexity of the ℓ₀ pseudonorm, as well as the property of orthant-strict monotonicity

► For classic l_∞, l₂ and l₁ source norms, we have a complete description of the corresponding sparsity-inducing unit balls

- Andreas Argyriou, Rina Foygel, and Nathan Srebro. Sparse prediction with the k-support norm. In Proceedings of the 25th International Conference on Neural Information Processing Systems - Volume 1, NIPS'12, pages 1457–1465, USA, 2012. Curran Associates Inc.
- Jean-Philippe Chancelier and Michel De Lara. Hidden convexity in the I₀ pseudonorm. Journal of Convex Analysis, 28(1):203–236, 2021.
- Jean-Philippe Chancelier and Michel De Lara. Constant along primal rays conjugacies and the I₀ pseudonorm. Optimization, 71(2):355–386, 2022a. doi: 10.1080/02331934.2020.1822836.
- Jean-Philippe Chancelier and Michel De Lara. Capra-convexity, convex factorization and variational formulations for the I₀ pseudonorm. *Set-Valued and Variational Analysis*, 30:597–619, 2022b.
- Jean-Philippe Chancelier and Michel De Lara. Orthant-strictly monotonic norms, generalized top-k and k-support norms and the I0 pseudonorm. Journal of Convex Analysis, (3):743–769, 2023.
- D. Gries. Characterization of certain classes of norms. Numerische Mathematik, 10:30-41, 1967.
- J. J. Moreau. Fonctionnelles convexes. Séminaire Jean Leray, 2:1-108, 1966-1967.
- Jean Jacques Moreau. Inf-convolution, sous-additivité, convexité des fonctions numériques. J. Math. Pures Appl. (9), 49:109–154, 1970.
- Robert Tibshirani. Regression shrinkage and selection via the lasso. Journal of the Royal Statistical Society. Series B (Methodological), 58(1):267–288, 1996. ISSN 00359246. URL http://www.jstor.org/stable/2346178.

Thank you :-)







▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●