A spatial version of the Itô-Stratonovich correction

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Joint work with Martin Hairer and Hendrik Weber

General question

How to deal with spatially rough stochastic PDEs?

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We study equations of the form

$$\partial_t u = \partial_x^2 u + g(u)\partial_x u + \xi$$

where

- $u = u(x, t) \in \mathbb{R}^n$, $x \in [0, 1]$, $t \ge 0$, periodic boundary conditions.
- $g: \mathbb{R}^n \to \mathbb{R}^{n \times n}$ smooth
- ξ : space-time white noise: Gaussian process with covariance

$$\mathbb{E}\xi(x,t)\xi(y,s) = \delta(x-y)\delta(t-s)$$

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Remark

- We can deal with an reaction term f(u) as well. (Easy)
- We can treat multiplicative noise as well. (Not so easy)

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Motivation

- Natural extensions of Burgers equation (g(u) = -u).
- Path-sampling problems for stochastic ODEs
- Spatial regularity is at the borderline where 'classical' techniques break down. Techniques apply to even rougher equations (KPZ).

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Structure of the talk

- Part I: g = DG is a gradient
 - Existence & Uniqueness: well-known (Da Prato & Debussche & Temam '94; Gyöngy '98)
 - Approximations: (Hairer & M.)
- Part II: g is not a gradient
 - Existence & Uniqueness: (Hairer; Hairer & Weber)
 - Approximations: (Hairer & M. & Weber)

Part I: g = DG

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How to solve this equation? First look at the linearised equation:

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- Intuition: $u \sim \psi$ in terms of regularity.
- Problem: how to make sense of the nonlinearity $g(u)\partial_x u$?

Definition

u is a mild solution if it satisfies the 'variation of constants formula':

$$u(\cdot,t) = e^{t\Delta}u_0 + \int_0^t \frac{e^{(t-s)\Delta}}{g(u(\cdot,s))\partial_x u(\cdot,s)} ds + \int_0^t e^{(t-s)\Delta} dW(s)$$

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Standard trick: Decompose $u = \psi + v$, so that

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at.

• Moral: After fixing ψ , the equation for v becomes deterministic;

• \rightsquigarrow can be solved pathwise by a standard fixed-point argument in C^1 .

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where
$$\partial_t \bar{u} = \partial_x^2 \bar{u} + g(\bar{u}) \partial_x \bar{u} - C (\nabla \cdot g)(\bar{u}) + \xi$$
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Theorem (Hairer - M. '10)

$$\lim_{\varepsilon\to 0}\mathbb{P}\Big(\sup_{t\leq \tau_\varepsilon}\|u^\varepsilon(t)-\bar{u}(t)\|_{L^\infty}>\varepsilon^{\frac{1}{6}-\kappa}\Big)=0\qquad \forall \kappa>0.$$

Remarks

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- It is exactly the local cross-variation in space: d[g(u), u] (kind of Itô-Stratonovich correction).

Part II: g is not a gradient

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Need to make sense of $\int_0^1 p_{t-s}(x-y) \Big[g(u(y,s)) \partial_x \psi(y,s) \Big] dy$, where $p_t(x)$ denotes the heat kernel.

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- But: Stochastic calculus does not apply (no arrow of time)
- Solution (following Hairer, Weber): use Lyons' Rough Paths Theory.

1-Slide Crash course in Rough Paths Theory

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Goal

Making sense of $\int_{y}^{z} Y(x) dX(x)$ for suitable $X, Y \in C^{\alpha}$ with $\alpha < \frac{1}{2}$. Problem: different Riemann sum approximations \rightarrow different limits.

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Rough Path Theory (Lyons, Gubinelli)

• Postulate the value of 'area process'

$$\int_y^z X(x) - X(y) \, \mathrm{d} X(x) := \mathbf{X}(y, z)$$

• If Y is 'controlled' by X, i.e.,

$$Y(y) - Y(x) = Y'(x) (X(y) - X(x)) + \{smooth\},$$

one can define $\int_{y} Y(x) dX(x)$ by 'second order Riemann sum approximation' involving **X**.

• Note: the value of $\int_{y}^{z} Y(x) dX(x)$ depends on the choice of **X**!

Back to the SPDE... (following Hairer '11)

Agenda:

- **(**) Construct an area process Ψ for the linearised solution ψ .
- Ø Make sense of mild solutions using rough integrals.
- Source of the solutions using a fixed point argument.
- Prove convergence of approximations.

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Theorem (Friz & Victoir '05; Hairer '10)

Let ψ be the solution to the stochastic heat equation. For fixed t there is a "canonical" area process Ψ such that $(\psi(t, \cdot), \Psi(t, \cdot, \cdot))$ is a rough path.

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Note however: $\tilde{\Psi}(t, x, y) := \Psi(t, x, y) + c(y - x)$ would be admissible as well (for any $c \in \mathbb{R}$)!

Making sense of weak solutions

Let ψ be the solution to the stochastic heat equation.

Definition

A continuous stochastic process u is a solution to (SPDE) if $v := u - \psi$ belongs to C^1 (in space) and satisfies

$$\begin{aligned} v(\cdot,t) &= \int_0^t \int_0^1 p_{t-s}(x-y) \Big[g\big(u(y,s)\big) \partial_x v(\cdot,s) \Big] \, \mathrm{d}y \, \mathrm{d}s \\ &+ \int_0^t \int_0^1 p_{t-s}(x-y) \Big[g\big(u(y,s)\big) \Big] \, \mathrm{d}_y \psi(y,s) \, \mathrm{d}s. \end{aligned}$$

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Remarks

- Notion of solution depends on the choice of the area process Ψ !
- Once Ψ has been fixed, everything is deterministic!

Existence and uniqueness (Hairer; Hairer & Weber)

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 ∂_tu = ∂_x²u + g(u)∂_xu + c (∇ ⋅ g)(u) + ξ with canonical area process Ψ
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 $\partial_t u = \partial_x^2 u + g(u)\partial_x u + \xi$ with area process $\Psi(x, y) + c(y - x)$

• Old interpretation: Approximations converge to SPDEs with the "wrong" nonlinearity.

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- Existence & uniqueness of solutions.
- Extension to multiplicative noise (nontrivial!)
- If g = DG, then solutions coincide with "classical solutions", provided Ψ is the canonical area process.

Further results (Hairer & M. & Weber)

- Extension of the approximation results to the non-gradient case.
- Solutions to the corrected equation

 $\partial_t u = \partial_x^2 u + g(u)\partial_x u + c(\nabla \cdot g)(u) + \xi$ with canonical area process Ψ coincide with solutions to

 $\partial_t u = \partial_x^2 u + g(u)\partial_x u + \xi$ with area process $\Psi(x, y) + c(y - x)$

• New interpretation: Approximations converge to SPDEs with the right nonlinearity, but with a different area process.

References



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Thank you!