Numerical Simulation of Rhone's Glacier between 1874 and 2100

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Rhône's river



Source : wikipedia

Rhône's river 25 000 years ago



Source : wikipedia













Source : http://www.unifr.ch/geosciences/geographie/glaciers

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Rhône's glacier : comparison at 2000 m



Rhône's glacier in 1860 (M. Funk's reconstruction)



Rhône's glacier in 1970 (M. Funk's reconstruction)



Rhône's glacier in 2050 (M. Funk's prediction)











Numerical prediction from 2007 to 2100



- Median climatic scenario (occh.ch)
 - Temperature trend : +3.8°C
 - Precipitation trend : -6m/year
 - Data from M. Huss and D. Farinotti, ETHZ.
 - Animation

Rhône's glacier in 2100 (3 scenario)



Scenario 1 : cold-wet Scenario 2 : median Scenario 3 : warm-dry

- Starting point : 3D fluid flows with complex free surfaces.
- Model.
- Numerical method.
- Ongoing work : crevasse formation.

Starting Point : 3D fluid flows with complex free surfaces

- Newtonian flows : V. Maronnier, M. Picasso, J. Rappaz (JCP 1999, IJNMF 2003).
 - Broken dam
 - Mould filling
- Newtonian flows and compressible gas and surface tension : A. Caboussat, M. Picasso, J. Rappaz (JCP 2005).
 - Mould filling
- Viscoelastic flows : A. Bonito, M. Picasso, M. Laso (JCP 2006).
 - Jet buckling.
 - Fingering instabilities : experiment, G. McKinley, MIT
 - Fingering instabilities : simulation

The model



- The computational domain is the region inside the dotted line.
- The ice region is defined by the volume fraction of ice φ .

Trift glacier, one picture a day in 2003 Animation

The model (Volume of Fluid)

Climatic input : b.

Unknowns : velocity u and pressure p, volume fraction of ice φ .



$$\begin{split} \rho \frac{\partial u}{\partial t} + \rho(u \cdot \nabla)u - \operatorname{div} \left(2\mu\epsilon(u)\right) + \nabla p &= \rho g, \\ \operatorname{div} u &= 0, \\ \frac{\partial \varphi}{\partial t} + u \cdot \nabla \varphi &= b\delta_{\Gamma}, \end{split}$$
on the ice/air interface $\Gamma : (2\mu\epsilon(u) - pI)n = 0, \\ \operatorname{on the bedrock} : \operatorname{no-slip} \operatorname{or sliding}, \\ \operatorname{Glen's} \operatorname{law for the viscosity.} \end{split}$

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The model (Volume of Fluid)

Climatic input : b.

Unknowns : velocity u and pressure p, volume fraction of ice φ .



$$\begin{aligned} -\operatorname{div} \left(2\mu\epsilon(u) \right) + \nabla p &= \rho g, \\ \operatorname{div} u &= 0, \\ \frac{\partial \varphi}{\partial t} + u \cdot \nabla \varphi &= b\delta_{\Gamma}, \end{aligned}$$
on the ice/air interface Γ : $(2\mu\epsilon(u) - \rho I)n = 0,$
on the bedrock : no-slip or sliding,
Glen's law for the viscosity.

Glen's flow law

• Given $\epsilon(u)$ find μ such that

$$\frac{1}{2\mu} = A\left(\sigma_0^{n-1} + \left(2\mu\sqrt{\frac{1}{2}\epsilon(u):\epsilon(u)}\right)^{n-1}\right)$$

• Viscosity with respect to $s=\sqrt{rac{1}{2}\epsilon(u)}:\epsilon(u)$



 The nonlinear Stokes problem has a solution in W^{1,1+1/n} (minimum of a strictly convex functional), Colinge Rappaz (M2AN 1999), Barrett Liu (NM 1994).

$$u \cdot n = 0 \quad \text{and} \quad (2\mu\varepsilon(u)n) \cdot t_i = -\alpha u \cdot t_i \quad i = 1, 2,$$
$$\alpha = \frac{1}{c^{\frac{1}{3}}} \frac{1}{\left(\sqrt{u^2 + v^2 + w^2} + s_0\right)^{\frac{2}{3}}},$$

Climatic input : b (m of ice per year)



Climatic input : b (m of ice per year)

- Based on 150 years of measurements.
- b = P M.
- P : solid precipitations (snow)

$$P(x, y, z, t) = P_{ws}(t) \left(1 + \frac{dP}{dz}(z - z_{ws})\right) C_{prec} DIST(x, y, z).$$

• *M* : ice melting

$$M(x, y, z, t) = \begin{cases} (F_M + r_{ice/snow}I(x, y, z)T(z, t) & \text{if } T(z, t) > 0, \\ 0 & \text{else.} \end{cases}$$

•
$$T(z,t) = T_{ws}(t) - 0.006(z - z_{ws}).$$

• The coefficients F_M , r_{ice} , r_{snow} , C_{prec} , dP/dz are tuned so that

$$\int_{1874}^{2007} \int_{\rm ice} (b - b_{meas})^2 dV dt$$

is minimum.

Time discretization : a decoupling scheme



$$\frac{\partial \varphi}{\partial t} + u^{n-1} \cdot \nabla \varphi = b \delta_{\Gamma}.$$

Time discretization : a decoupling scheme



$$\label{eq:constraint} \begin{split} & {\rm div} \ u = 0, \\ & {\rm on \ the \ ice/air \ interface \ } \Gamma \ : \ (2\mu\epsilon(u) - pI)n = 0, \\ & {\rm on \ the \ bedrock} \ : \ {\rm no-slip \ or \ sliding}. \end{split}$$

Space discretization : structured cells and finite elements



- Shape computation (transport + ice accumulation/melting) : small structured cells
- Velocity computation (nonlinear Stokes) : unstructured finite elements
- To avoid numerical diffusion :

$$\frac{\text{FE spacing}}{\text{cells spacing}} \simeq 5.$$

The 3D finite element mesh





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The 3D finite element mesh



Shape computation : transport + ice accumulation/melting (1/3)

• Solve between
$$t = t^{n-1}$$
 and $t = t^n$

$$\frac{\partial \varphi}{\partial t} + u^{n-1} \cdot \nabla \varphi = b \delta_{\Gamma}.$$

• Forward characteristics method :

$$\varphi^n(x + \Delta t \ u^{n-1}(x)) = \varphi^{n-1}(x).$$



Shape computation : transport + ice accumulation/melting (2/3)

- SLIC Postprocessing (Simple Line Interface Calculation), see for instance Scardovelli Zaleski Ann. Rev. Fluid Mech. 1999.
- Without SLIC.



time t^{n+1}

time t^n

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time t^{n+2}

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Shape computation : transport + ice accumulation/melting (3/3)

• Solve between $t = t^{n-1}$ and $t = t^n$

$$\frac{\partial \varphi}{\partial t} + u^{n-1} \cdot \nabla \varphi = b \delta_{\Gamma}.$$



- Given the climatic input *b*, we can simulate the motion of a glacier.
- Optimization problem : observed moraines \rightarrow climatic input *b*.
- Crevasse formation : rupture of hanging glaciers, calving glaciers → mechanics of damage.

Rupture of hanging glaciers : Argentière



Calving glaciers : Rhone Glacier



Damage modelling

- Microcracks can be modeled at macroscopic level by introducing a state variable D(x, t) called damage : A. Pralong and M. Funk, Annals of Glaciology, 2003.
- Isotropic damage : D is a scalar field, D = 0 no damage, D = 1 full damage.
- Momentum equation :

$$\rho \frac{\partial u}{\partial t} + \rho(u \cdot \nabla)u - \operatorname{div} (2\mu(1-D)\epsilon(u)) + \nabla p = \rho g,$$

• Damage nonlinear transport equation :

$$\frac{\partial D}{\partial t} + u \cdot \nabla D = f(D, \epsilon(u), p).$$

• Simulation of crevasse formation : Eiger Gruben.