

Coarse graining dynamics using the Mori-Zwanzig formalism: algorithms to reconstruct the projected dynamics

Rodolphe Vuilleumier

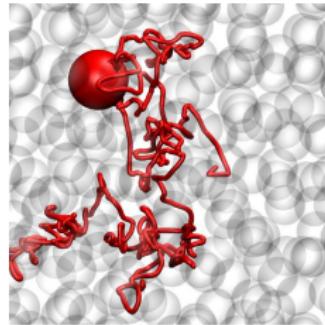
PASTEUR, Département de chimie, École normale supérieure,
PSL University, Sorbonne Université, CNRS, 75005 Paris, France

CECAM-Moser discussion meeting



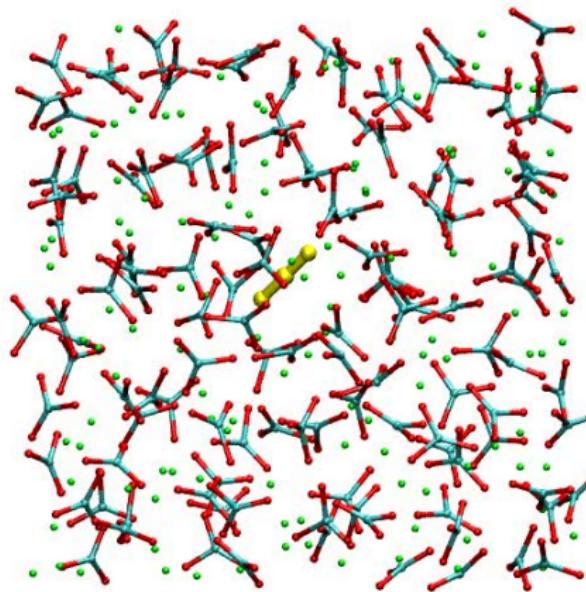
Introduction

- Description of diffusion of a particle in a fluid



- Mechanism, collective variables?
- e.g. proton transport, hops between cages...

Diffusion of CO₂ molecule in molten CaCO₃



D. Corradini, F.-X. Coudert, RV, Nature Chemistry 8 (2016): 454-460.

Introduction

- Mori-Zwanzig formalism for projecting on a slow variable
- Application to the diffusion of a particle in a fluid
- Other slow variables: hydrodynamic modes
- Long-time behaviour of the memory kernel?

Mori-Zwanzig formalism for the diffusion of a tagged particle in a fluid

- Here, we will consider the case of diffusion and consider the velocity \mathbf{v} as relevant variable. The projector of any quantity \mathbf{A} on \mathbf{v} is defined as

$$\mathcal{P}\mathbf{A} = v \frac{\langle \mathbf{v}\mathbf{A} \rangle}{\langle \mathbf{v}^2 \rangle}; \quad \mathcal{Q} = 1 - \mathcal{P}$$

$\langle \bullet \rangle$ is the average over the canonical distribution function at temperature T

- The microscopic dynamics is decomposed in components orthogonal and along the projection space

$$i\mathcal{L} = i\mathcal{P}\mathcal{L} + i\mathcal{Q}\mathcal{L}$$

Generalized Langevin equation for the tagged particle velocity

- GLE

$$m \frac{d\mathbf{v}}{dt}(t) = - \int_0^t K(u) \mathbf{v}(t-u) du + \mathbf{R}(t),$$

- Mori-Zwanzig Memory kernel

$$K(u) = \frac{\langle \mathbf{F} e^{i\mathcal{Q}\mathcal{L}u} \mathbf{F} \rangle}{k_B T} = \frac{\langle \mathbf{F} \mathbf{R}(u) \rangle}{k_B T}$$

- Random force $\mathbf{R}(t) = e^{i\mathcal{Q}\mathcal{L}t} \mathbf{F}$
- Projection operator $\mathcal{P} = 1 - \mathcal{Q}$: $\mathcal{P} \mathbf{A} = \frac{\langle \mathbf{v} \mathbf{A} \rangle}{\langle \mathbf{v}^2 \rangle} \mathbf{v}$

Computation of projected dynamics

We want to compute

$$\mathbf{R}(t) = \exp(i\mathcal{Q}\mathcal{L}t)\mathbf{F}$$

We first note that

$$i\mathcal{Q}\mathcal{L} = i(1 - \mathcal{P})\mathcal{L} = i\mathcal{L} + \mathbf{v} \frac{\langle \mathbf{F} \cdot \bullet \rangle}{\langle \mathbf{v}^2 \rangle}$$

So that the time evolution of \mathbf{R} is

$$\frac{d}{dt}\mathbf{R}(t) = i\mathcal{L}\mathbf{R}(t) + \mathbf{v} \frac{\langle \mathbf{F} \cdot \mathbf{R}(t) \rangle}{\langle \mathbf{v}^2 \rangle}$$

Projected dynamics along the flow

- Force is transported unchanged backward in the phase-space flow:

$$\frac{d}{dt} \mathbf{F}(t) = i\mathcal{L}\mathbf{F}(t)$$

$$\mathbf{F}(q, p; t + \delta t) = \mathbf{F}(q_{\delta t}, p_{\delta t}; t)$$

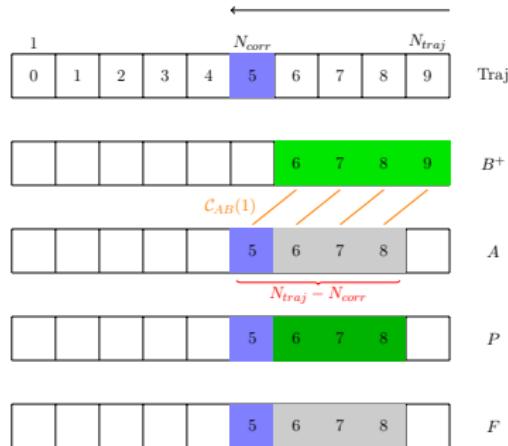
- Total derivative of the random force in the flow is non zero

$$\frac{d}{dt} \mathbf{R}(t) = i\mathcal{L}\mathbf{R}(t) + \mathbf{v} \frac{\langle \mathbf{F} \cdot \mathbf{R}(t) \rangle}{\langle \mathbf{v}^2 \rangle}$$

$$\mathbf{R}(q, p; t + \delta t) = \mathbf{R}(q_{\delta t}, p_{\delta t}; t) + \frac{\langle \mathbf{F} \cdot \mathbf{R}(t) \rangle}{\langle \mathbf{v}^2 \rangle} \mathbf{v}(q_{\delta t}, p_{\delta t}; t)$$

Going backward

$$\mathbf{R}(q, p; t + \delta t) = \mathbf{R}(q_{\delta t}, p_{\delta t}; t) + \frac{\langle \mathbf{F} \cdot \mathbf{R}(t) \rangle}{\langle \mathbf{v}^2 \rangle} \mathbf{v}(q_{\delta t}, p_{\delta t}; t)$$



Order 1: Carof, A.; Vuilleumier, R.; Rotenberg, B. *J. Chem. Phys.* 2014, **140**, 124103.

Order 2: Lesnicki, D.; Vuilleumier, R.; Carof, A.; Rotenberg, B. *Phys. Rev. Lett.* 2016, **116**, 147804.

Illustration: double well potential

- Characteristic function for the products and reactants

$$h(x) = \begin{cases} 1 & \text{if } x > 0 \\ 0 & \text{otherwise} \end{cases}$$

- Reaction rate τ^{-1} :

$$\int_0^{+\infty} K(t) dt = \int_0^{+\infty} \frac{\langle \dot{h} e^{iQ\mathcal{L}t} \dot{h} \rangle}{k_B T} dt = \lim_{t \rightarrow \infty} \frac{\langle \dot{h} e^{iQ\mathcal{L}t} h \rangle}{k_B T} = \tau^{-1}$$

but

$$\int_0^{+\infty} C(t) dt = \int_0^{+\infty} \frac{\langle \dot{h} \dot{h}(t) \rangle}{k_B T} dt = \lim_{t \rightarrow \infty} \frac{\langle \dot{h} h(t) \rangle}{k_B T} = 0$$

Illustration: double well potential

$$h(x) = \begin{cases} 1 & \text{if } x > 0 \\ 0 & \text{otherwise} \end{cases} \quad \int_0^T C(t) dt = \langle \dot{h}(0) h(T) \rangle = \langle \dot{h} e^{i\mathcal{L}T} h \rangle$$

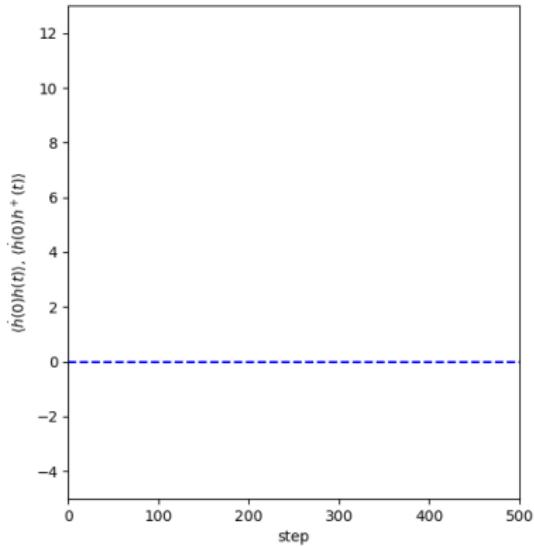
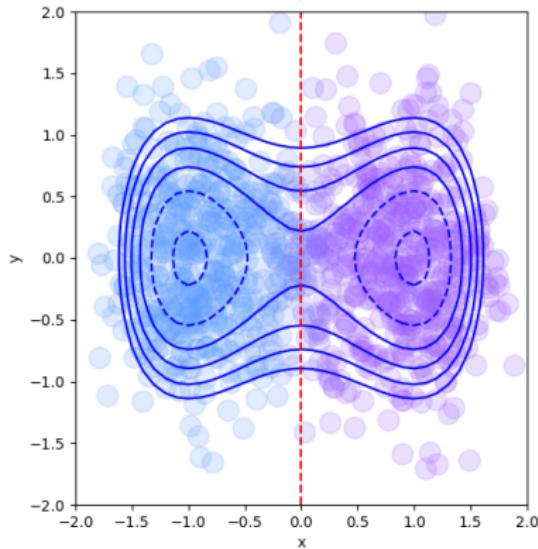
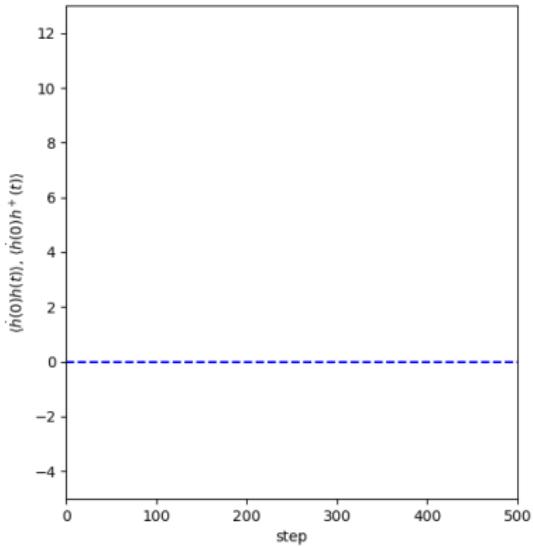
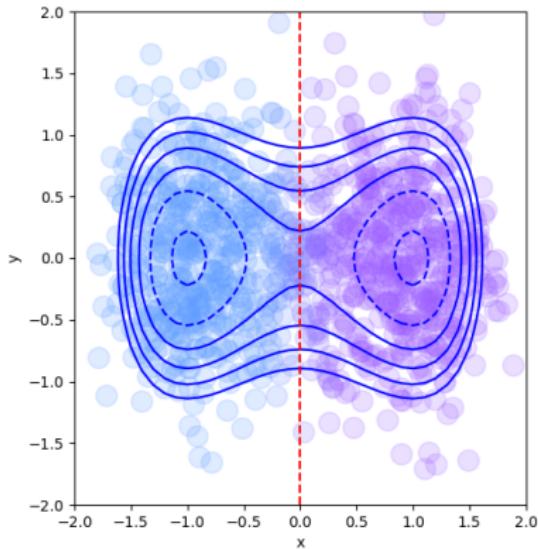


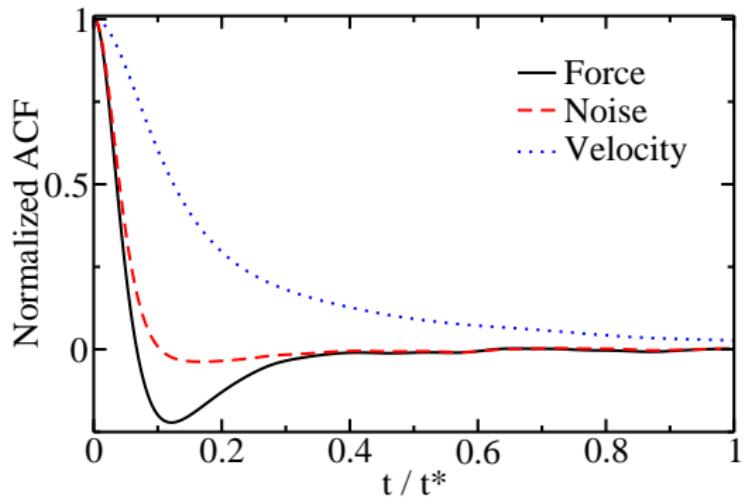
Illustration: double well potential – projection

$$h(x) = \begin{cases} 1 & \text{if } x > 0 \\ 0 & \text{otherwise} \end{cases} \quad \int_0^T K(t) dt = \langle \dot{h} e^{iQ\mathcal{L}T} h \rangle \quad \mathcal{P}\mathbf{A} = \frac{\langle h\mathbf{A} \rangle}{\langle h^2 \rangle} h$$

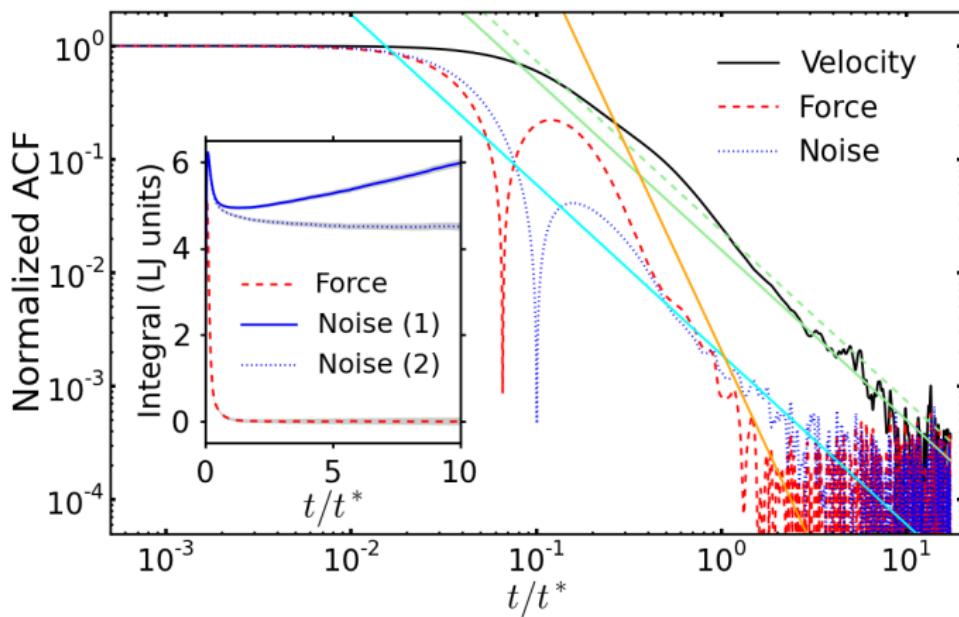


Diffusion in a Lennard-Jones fluid – correlation function

MD simulations of liquid Argon at $T^* = 1.5$, $\rho^* = 0.5$ (10000 particles)



Asymptotic behaviour: MD results



Lesnicki, D.; Vuilleumier, R.; Carof, A.; Rotenberg, B. *Phys. Rev. Lett.* 2016, **116**, 147804.

Hydrodynamic limit ($L \rightarrow +\infty$ then $t \rightarrow +\infty$):

Asta, A. J.; Levesque, M.; Vuilleumier, R.; Rotenberg, B. *Phys. Rev. E* 2017, **95** (6).

Asymptotic behaviour: theory

- Velocity autocorrelation function (Bedeaux and Mazur)

$$Z(t) = \frac{1}{3} \langle \mathbf{v} \cdot \mathbf{v}(t) \rangle \sim \frac{2k_B T}{3\rho m} [4\pi(D + \nu)t]^{-\frac{3}{2}}$$

- Force autocorrelation function

$$\langle F(t)F(0) \rangle = \frac{d^2}{dt^2} Z(t) \sim t^{-\frac{7}{2}}$$

- Random force autocorrelation function: Corngold (PRA 1972)

$$K(t) \sim -\frac{\xi^2}{k_B T} Z(t) \sim -\frac{2\xi^2}{3\rho m} [4\pi(D + \nu)t]^{-\frac{3}{2}}$$

Retrieving the hydrodynamic solution: Basset-Boussinesq force

- Integrating by parts the GLE (for long times t)

$$\begin{aligned} m \frac{d\mathbf{v}}{dt}(t) &= - \int_0^t K(u) \mathbf{v}(t-u) du + \mathbf{R}(t) \\ &= -\xi \mathbf{v}(t) - \int_0^t L(u) \dot{\mathbf{v}}(t-u) du \end{aligned}$$

with

$$L(u) = \int_u^{+\infty} K(\tau) d\tau$$

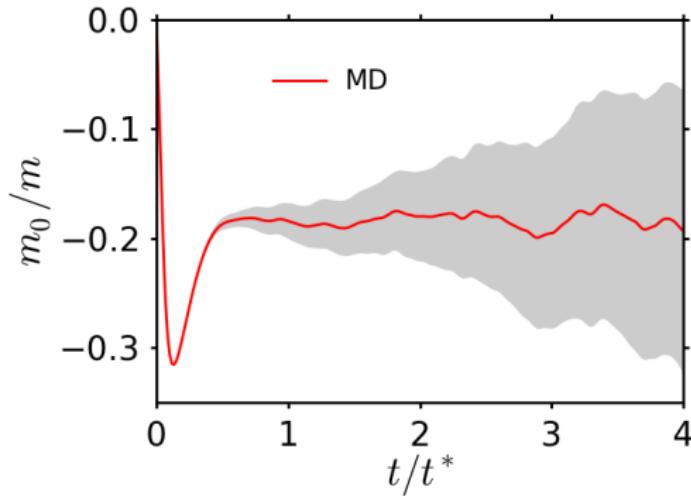
- Generalized friction force

$$m \dot{\bar{v}}(t) = f_\epsilon(t) - \xi \bar{v}(t) - m_0 \dot{\bar{v}}(t) - \alpha \pi^{-1/2} \int_0^t (t-u)^{-\frac{1}{2}} \dot{\bar{v}}(u) du$$

- Hydrodynamic added mass $m_0^{BB} = \frac{2}{3}\pi R^3 \rho_0$

Added mass

$$m_0 \equiv - \int_0^{+\infty} \left(K(t) + \frac{1}{2} \alpha \pi^{-1/2} t^{-3/2} \right) t \, dt$$



$$m_0 = -0.18$$

Interpretation of the negative contribution to the added mass

- Retarded force

$$m\dot{\bar{v}}(t) = f_\epsilon(t) - \xi_E \bar{v}(t - \tau_0) = f_\epsilon(t) - \xi_E \bar{v}(t) + \xi_E \times \tau_0 \times \dot{\bar{v}}(t)$$

- Short-time decay of the memory kernel

$$K(t) = \frac{\xi_E}{\tau_0} e^{-t/\tau_0}$$

- Enskog contribution to the added mass

$$m_0^E = -\xi_E \tau_0 \approx -0.29 \text{ m},$$

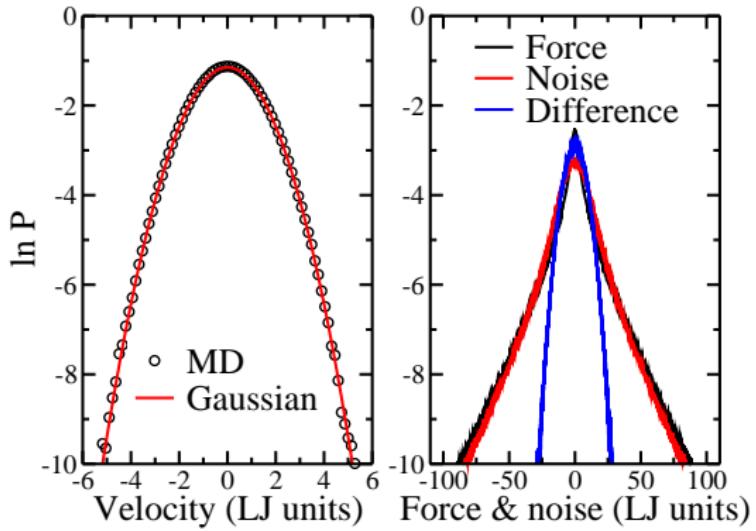
with $\tau_0 \sim 0.05 \text{ t}^*$ and $\xi_E \approx 5.8$

- Sum of contributions

$$m_0 = m_0^E + m_0^{BB} \approx -0.16 \text{ m}$$

Random force distribution

MD simulations of liquid Argon at $T^* = 1.5$, $\rho^* = 0.5$ (10000 particles)



Eigenfunctions of $i\mathcal{QL}$ for the double well potential

- $i\mathcal{QL}$ has a non-trivial eigenfunction with zero eigenvalue
- On the left:

$$h(i\mathcal{QL}) = 0$$

since $\mathcal{Q}h = 0$

- On the right:

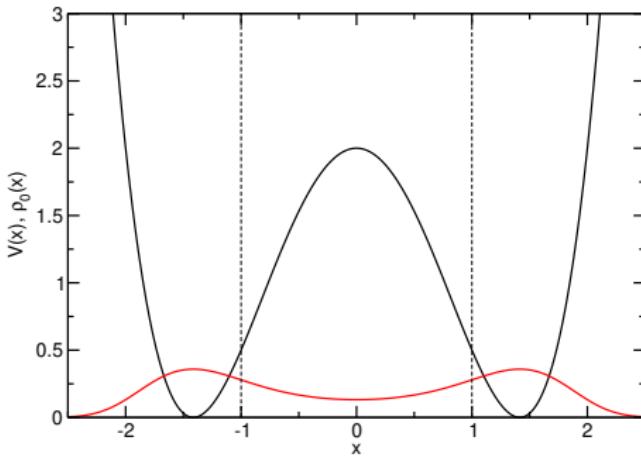
$$i\mathcal{QL}\tau_h = 0 \quad \Rightarrow \quad i\mathcal{L}\tau_h \propto h$$

Formally,

$$\tau_h = \frac{1}{i\mathcal{L}}h = \int_0^\infty e^{i\mathcal{L}t} h dt = \int_0^\infty h(t) dt$$

Committor time

1D model

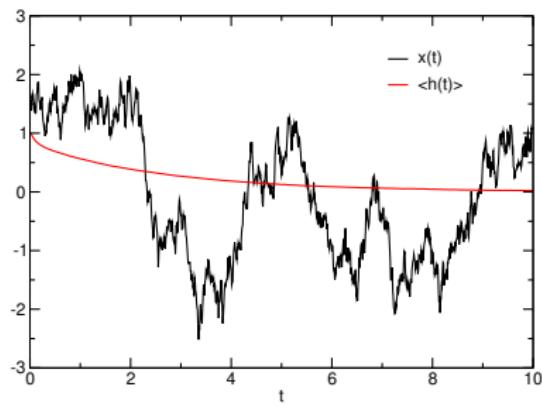


Overdamped dynamics: $i\mathcal{L} = -\frac{D}{kT} \frac{\partial V}{\partial x} \frac{\partial}{\partial x} + D \frac{\partial^2}{\partial x^2}$

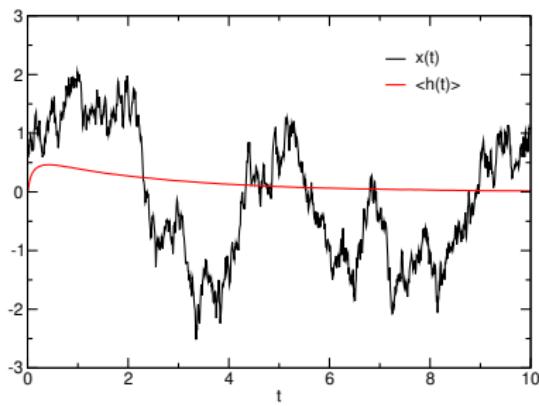
$$D = 1, kT = 2$$

$\tau_h = t_A - t_B$: committor time

1D model



$$x(0) = 1.5$$

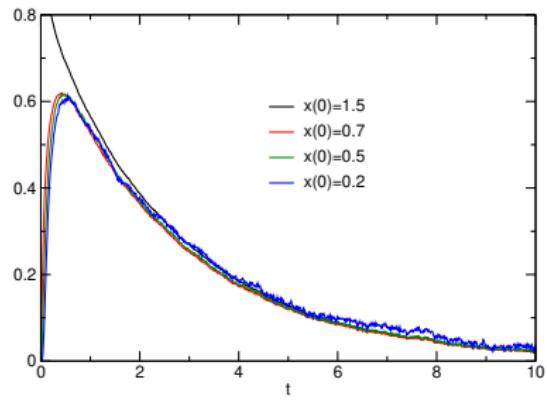
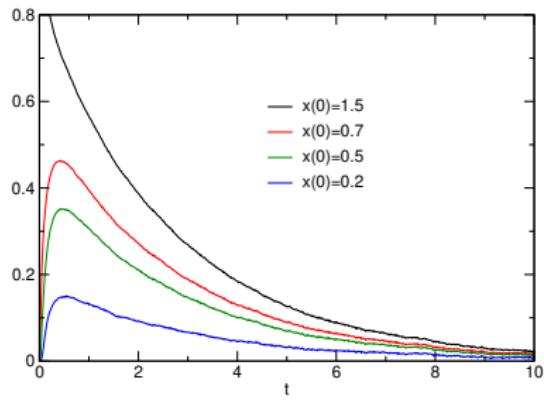


$$x(0) = 0.7$$

Relation between τ_h and p_c

Committer p_c

Rescaling $\langle h(t) \rangle$ by p_c :



$\tau_h \approx \tau_0 \times p_c$, with τ_0 the reaction time

Equation for τ_h and p_c

- τ_h satisfies

$$\left(-\frac{D}{kT} \frac{\partial V}{\partial x} \frac{\partial}{\partial x} + D \frac{\partial^2}{\partial x^2} \right) \tau_h = -h$$

A : source, B : sink; $\tau_h \rho_0$ stationary state

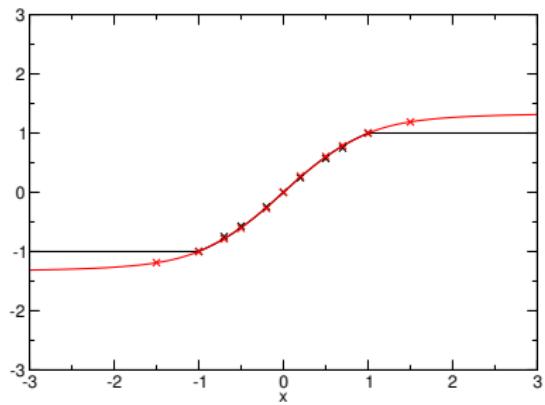
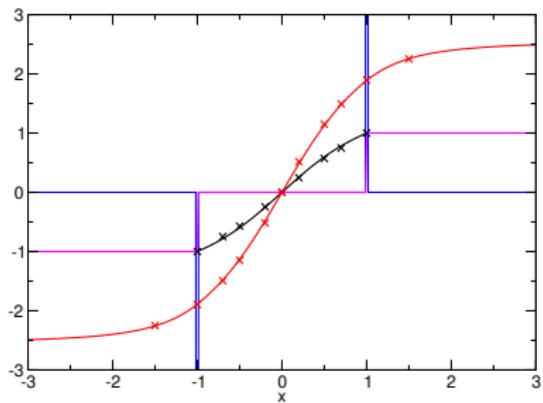
- p_c satisfies

$$\left(-\frac{D}{kT} \frac{\partial V}{\partial x} \frac{\partial}{\partial x} + D \frac{\partial^2}{\partial x^2} \right) p_c = 0; \quad p_c(\partial A) = 1, \quad p_c(\partial B) = -1$$

Can be solved using Lagrange multipliers

$$\left(-\frac{D}{kT} \frac{\partial V}{\partial x} \frac{\partial}{\partial x} + D \frac{\partial^2}{\partial x^2} \right) p_c = \lambda(x)$$

1D model



in 1D: $\tau_h = \tau_0 \times p_c$ outside A and B

Inspection of $\lim_{T \rightarrow \infty} e^{i\mathcal{Q}\mathcal{L}T} \mathbf{v}$

- Taking limits in the GLE
- It can be shown with some algebra that

$$\int_{-\infty}^0 \langle \mathbf{v}(t) \mathbf{B} \rangle dt = \frac{\int_0^{+\infty} \langle \mathbf{v} \mathbf{v}(t) \rangle dt}{\langle \mathbf{v}^2 \rangle} \times \lim_{T \rightarrow +\infty} \langle \mathbf{B} e^{-i\mathcal{Q}\mathcal{L}T} \mathbf{v} \rangle$$

- in the sense of a density, we can say that

$$\lim_{T \rightarrow +\infty} e^{-i\mathcal{Q}\mathcal{L}T} \mathbf{v} = \int_{-\infty}^0 \mathbf{v}(t) dt = \lim_{T \rightarrow +\infty} (\mathbf{r}(0) - \mathbf{r}(-T))$$

Comparison with linear response

Infinitesimal force

force f applied on particle 1 since $t = -\infty$ along x

Averages of observables

$$\begin{aligned}\langle A \rangle_f &\approx \langle A \rangle_0 + \beta f \int_{-\infty}^0 dt \langle v_{1,x}(t) A \rangle_0 \\ &\approx \langle A \rangle_0 + f \times \beta \langle \Delta r_{1,x} A \rangle_0\end{aligned}$$

$\Delta r_{1,x}$: displacement along x of particle 1 from $t = -\infty$ to $t = 0$

$A \equiv v_1$: $\beta \langle \Delta r_{1,x} v_1 \rangle_0$ is the mobility

Observables **B**

Induced local structure

- Particle density:

$$\rho(\mathbf{r}) = \sum_i m_i \delta^3(\mathbf{r} - \mathbf{r}_i)$$

Induced flow around the diffusing particle

- Momentum density:

$$\rho \mathbf{v}(\mathbf{r}) = \sum_i m_i (\mathbf{v}_i - \mathbf{v}_1) \delta^3(\mathbf{r} - \mathbf{r}_i)$$

$$\mathbf{v}(\mathbf{r}) = \frac{\rho \mathbf{v}(\mathbf{r})}{\rho(\mathbf{r}) \mathcal{U}}$$

Use of symmetries

- Density

$$\delta\rho(\mathbf{r}) = \gamma_1(r) \cos\theta$$

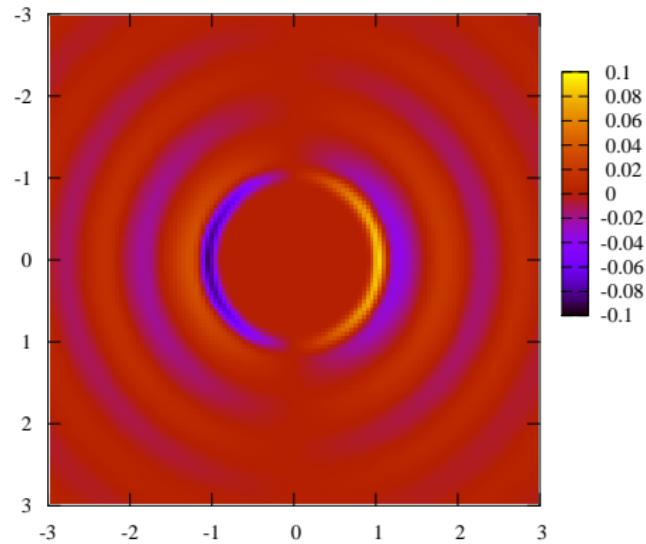
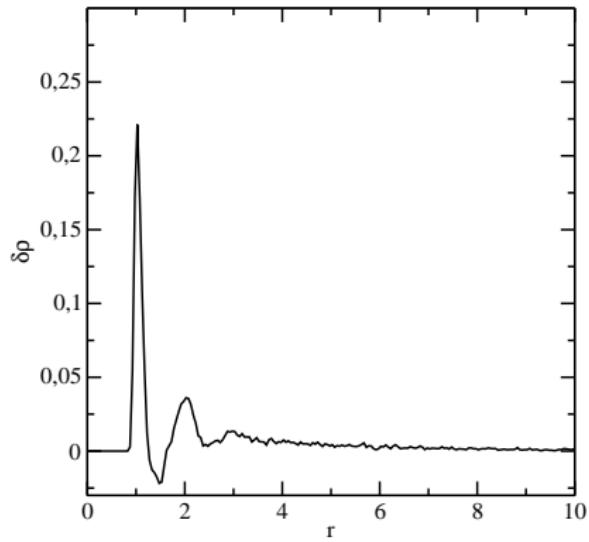
- Momentum density

$$\rho\mathbf{v}(\mathbf{r}) = \Theta_L(r) \cos\theta \mathbf{u}_r + \Theta_T(r) \sin\theta \mathbf{u}_\theta$$

Same symmetries as Stokes flow!

Density map

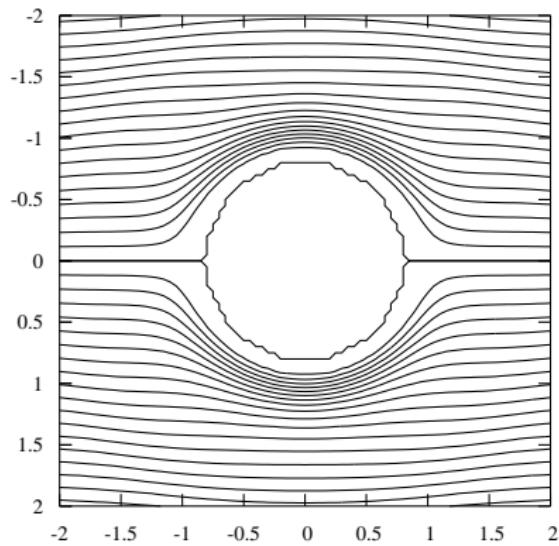
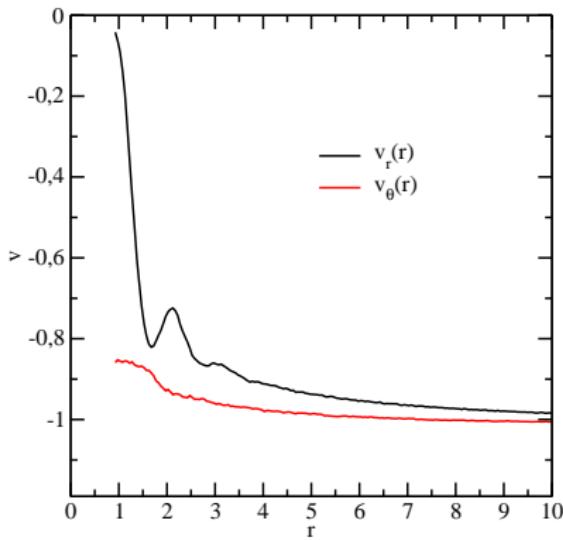
$$\delta\rho(\mathbf{r}) = \beta\langle\Delta r_{1,x} \delta(\mathbf{r} - \mathbf{r}_{1i})\rangle = h(r) \cos\theta$$



Force felt by the particle = applied force

Velocity field: diffusing particle frame

$$\rho \mathbf{v}(\mathbf{r}) = \beta \langle \Delta r_{1,x} (\mathbf{v}_i - \mathbf{v}_1) \delta(\mathbf{r} - \mathbf{r}_{1i}) \rangle = f(r) \cos \theta \cdot \mathbf{e}_r + g(r) \sin \theta \cdot \mathbf{e}_\theta$$



Lesnicki, D.; Vuilleumier, R. *J. Chem. Phys.* 2017, **147**, 094502.

Summary

- An algorithm to compute accurately projected correlation function and random noise from equilibrium MD simulations
- We found the expected long-time behaviour of the projected correlation function
- Extraction of an added mass
- Determination of molecular flow
- Extension to collective variables to describe diffusion mechanism of diffusion?
- Proton transport,...

Acknowledgements

Dominika Lesnicki

Antoine Carof

Benjamin Rotenberg

