## Computational Statistical Physics: A Mathematical Overview

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#### Description of a classical system

- Positions q (configuration), momenta  $p = M\dot{q}$  (M diagonal mass matrix)
- Microscopic description of a classical system (N particles):

$$(q,p) = (q_1, \dots, q_N, p_1, \dots, p_N) \in T^*\mathcal{D}$$

- For instance,  $T^*\mathcal{D}=\mathcal{D} imes\mathbb{R}^{3N}$  with  $\mathcal{D}=\mathbb{R}^{3N}$  or  $\mathbb{T}^{3N}$
- More complicated situations can be considered... (constraints defining submanifolds of the phase space)
- Hamiltonian

$$H(q,p) = \sum_{i=1}^{N} \frac{p_i^2}{2m_i} + V(q_1, \dots, q_N)$$

- ullet All the physics is contained in V
- For instance, pair interactions  $V(q_1, \dots, q_N) = \sum_{1 \le i < j \le N} v(|q_j q_i|)$

#### Extracting macroscopic properties: Statistical physics

- Given the structure and the laws of interaction of the particles, what are the macroscopic properties of the matter composed of these particles?
- Equilibrium thermodynamic properties (pressure,...):

$$\langle A \rangle = \int_{T^*\mathcal{D}} A(q, p) \, \mu(dq \, dp)$$

• Choice of thermodynamic ensemble (probability measure  $d\mu$ ): constrained maximisation of entropy

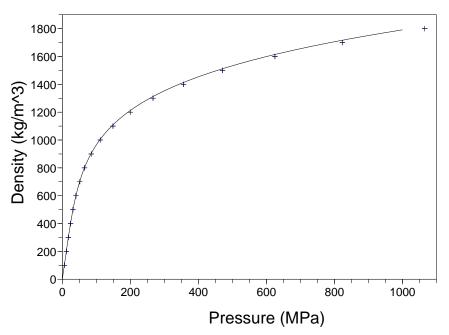
$$S(\rho) = -k_{\rm B} \int \rho \ln \rho,$$

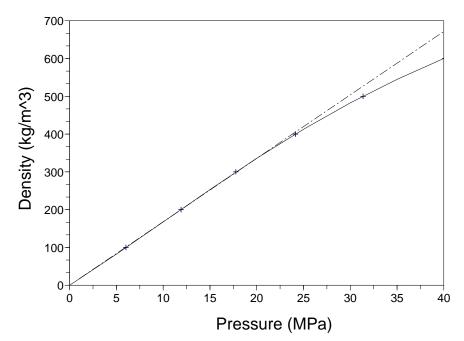
under the constraints  $\rho \geq 0$ ,  $\int \rho = 1$ ,  $\int A_i \rho = A_i$ 

• The choice of the variables and the observables  $A_i$  ( $1 \le i \le m$ ) determine the ensemble

#### An example of macroscopic data

- Pressure observable  $A(q,p)=rac{1}{3|\mathcal{D}|}\sum_{i=1}^{N}\left(rac{p_i^2}{m_i}-q_i\cdot 
  abla_{q_i}V(q)
  ight)$
- Lennard-Jones potential  $v(r) = 4\varepsilon \left[ \left( \frac{\sigma}{r} \right)^{12} \left( \frac{\sigma}{r} \right)^6 \right]$
- Argon:  $\varepsilon/k_{
  m B}$  =120 K,  $\sigma=3.405$  Å



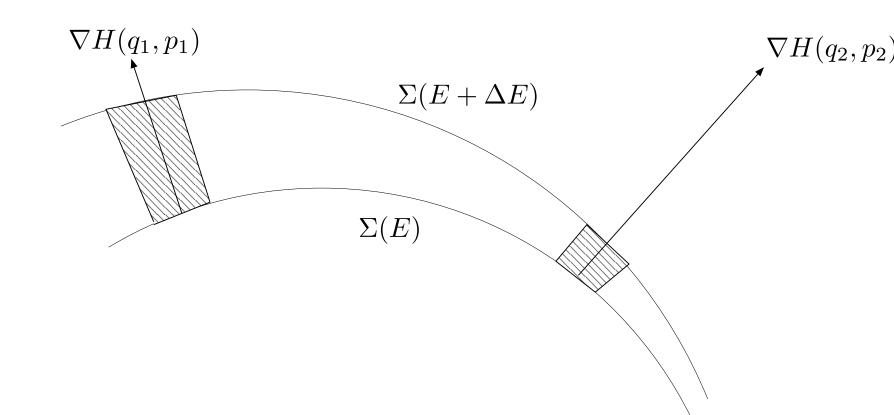


Argon state law at  $T=300~\mathrm{K}.$ 

# Sampling the microcanonical ensemble

#### The microcanonical measure

- Lebesgue measure conditioned to the set  $\Sigma(E) = \{H(q, p) = E\}$
- Measure  $d\mu_{\text{NVE}}(q) = Z_E^{-1} \delta_{H(q,p)-E}(dq \, dp) = Z_E^{-1} \frac{\sigma_{\Sigma(E)}(dq \, dp)}{|\nabla H(q,p)|}$
- The partition function  $Z_E$  is a normalization constant



Mathematical Methods for Ab Initio Quantum Chemistry, Nice, october 2009 - p. 6/29

#### The Hamiltonian dynamics

Evolution of isolated systems (Newton's law)

$$\begin{cases} \frac{dq(t)}{dt} &= \frac{\partial H}{\partial p}(q(t), p(t)) &= M^{-1}p(t) \\ \frac{dp(t)}{dt} &= -\frac{\partial H}{\partial q}(q(t), p(t)) &= -\nabla V(q(t)) \end{cases}$$

- Energy and volume preserving
- Ergodic postulate (on connected components of  $\Sigma(E)$ )

$$\langle A \rangle = \lim_{T \to +\infty} \frac{1}{T} \int_0^T A(q(t), p(t)) dt$$

- Proof for integrable systems and their perturbations (KAM theory)
- Numerically interesting since it allows to replace a high-dimensional integral with an integral in dimension 1

#### Numerical integration of the Hamiltonian dynamics

Verlet scheme<sup>a</sup> (finite difference discretization for the equation on  $\ddot{q}$ )

$$\begin{cases} p^{n+1/2} = p^n - \frac{\Delta t}{2} \nabla V(q^n) \\ q^{n+1} = q^n + \Delta t \ M^{-1} p^{n+1/2} \\ p^{n+1} = p^{n+1/2} - \frac{\Delta t}{2} \nabla V(q^{n+1}) \end{cases}$$
 Estimate the ensemble average as 
$$\frac{1}{N} \sum_{n=1}^N A(q^n)$$

- Symplectic scheme: recall that a map  $(q,p) \mapsto \phi(q,p)$  is symplectic if

$$\nabla \phi(q, p) J \nabla \phi(q, p) = J, \qquad J = \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix}$$

Backward analysis: exact preservation of an approximate energy, hence approximate preservation of the exact energy<sup>b</sup>

<sup>&</sup>lt;sup>a</sup>L. Verlet, *Phys. Rev.* **159**(1) (1967) 98-105.

<sup>&</sup>lt;sup>b</sup> E. Hairer, C. Lubich and G. Wanner (Springer, 2006)

# Sampling the canonical ensemble

#### Classification of the methods

• Computation of  $\langle A \rangle = \int_{T^*\mathcal{D}} A(q,p) \, \mu(dq \, dp)$  with

$$\mu(dq \, dp) = Z_{\mu}^{-1} e^{-\beta H(q,p)} \, dq \, dp, \qquad \beta = \frac{1}{k_{\rm B}T}$$

Actual issue: sampling canonical measure on configurational space

$$\nu(dq) = Z_{\nu}^{-1} e^{-\beta V(q)} dq$$

- Several strategies:
  - (1) Purely stochastic methods (i.i.d sample)
  - (2) Markov chain methods and stochastic differential equations
  - (3) Deterministic methods à la Nosé-Hoover
- Theoretical and numerical comparison: convergence for (1)-(2), in practice (2) is more convenient

<sup>&</sup>lt;sup>a</sup>E. Cancès, F. Legoll et G. Stoltz, M2AN, 2007

#### Metropolis-Hastings algorithm

- Markov chain method (Metropolis et al. (1953), Hastings (1970))
- Given a current configuration  $q^n$ , propose  $\tilde{q}^{n+1}$  according to a transition probability  $T(q^n, \tilde{q})$ 
  - Gaussian displacement  $\tilde{q}^{n+1}=q^n+\sigma\,G^n$  with  $G^n\sim\mathcal{N}(0,\mathrm{Id})$ , in which case  $T(q,\tilde{q})=\left(\sigma\sqrt{2\pi}\right)^{-3N}\,\exp\left(-\frac{|\tilde{q}-q|^2}{2\sigma^2}\right)$
  - $\text{ Biased random walk } \tilde{q}^{n+1} = q^n \alpha \nabla V(q^n) + \sqrt{\frac{2\alpha}{\beta}} \, G^n \text{, in which case }$   $T(q,\tilde{q}) = \left(\frac{\beta}{4\pi\alpha}\right)^{3N/2} \exp\left(-\beta \frac{|\tilde{q}-q+\alpha\nabla V(q)|^2}{4\alpha}\right)$
- Accept the proposition with probability

$$\min\left(1, \frac{T(\tilde{q}^{n+1}, q^n) \nu(\tilde{q}^{n+1})}{T(q^n, \tilde{q}^{n+1}) \pi(q^n)}\right),\,$$

and set in this case  $q^{n+1} = \tilde{q}^{n+1}$ ; otherwise, set  $q^{n+1} = q^n$ .

#### Convergence

Transition kernel

$$P(q, dq') = \min\left(1, r(q, q')\right) T(q, q') dq' + \left(1 - \alpha(q)\right) \delta_q(dq'),$$

where  $\alpha(q) \in [0,1]$  is the probability to accept a move starting from q:

$$\alpha(q) = \int \min \left(1, r(q, q')\right) T(q, q') dq'.$$

• The canonical measure is reversible with respect to  $\nu$ , hence invariant:

$$P(q, dq')\nu(dq) = P(q', dq)\nu(dq')$$

- Show irreducibility (properties of the proposition function): defining the n-step transition probability as  $P^n(q,dq') = \int_{x \in \mathcal{D}} P(q,dx) \, P^{n-1}(x,dq')$ , the condition is that, for almost all  $q_0$  and any set A of positive measure, there exists  $n_0$  such that  $P^n(q_0,A) > 0$  when  $n \geq n_0$
- Pathwise ergodicity  $\lim_{N\to+\infty}\frac{1}{N}\sum_{n=1}^N A(q^n)=\int_{\mathcal{D}}A(q)\,\nu(dq)$

#### Error estimates

Under additional assumptions, the pathwise convergence result can be refined to a central limit theorem for Markov chains:

$$\sqrt{N} \left| \frac{1}{N} \sum_{n=1}^{N} A(q^n) - \int_{\mathcal{D}} A(q) \, \nu(dq) \right| \longrightarrow \mathcal{N}(0, \sigma^2),$$

• The asymptotic variance  $\sigma^2$  takes into account the correlations:

$$\sigma^2 = \operatorname{Var}_{\nu}(A) + 2 \sum_{n=1}^{+\infty} \mathbb{E}_{\nu} \left[ \left( A(q^0) - \mathbb{E}_{\nu}(A) \right) \left( A(q^n) - \mathbb{E}_{\nu}(A) \right) \right]$$

- Numerical efficiency: trade-off between acceptance and sufficiently large moves in space (rejection rate around 0.5), the aim being to reduce the sample autocorrelation
- Practical computation of error bars (confidence intervals): independent realizations or block averaging

### Hybrid Monte Carlo

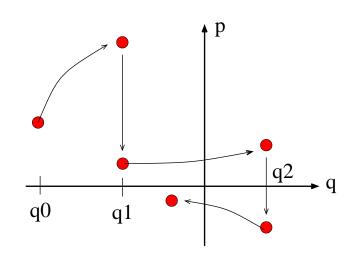
Markov chain in the configuration space (Duane et al. (1987), Schuette et al. (1999)). Starting from  $q^n$ :

- ullet generate momenta  $p^n$  according to  $Z_p^{-1} \ {
  m e}^{-eta p^2/2m} dp$
- compute (an approximation of) the flow  $\Phi_{\tau}(q^n, p^n) = (\tilde{q}^{n+1}, \tilde{p}^{n+1})$  of Newton's equations, *i.e.* integrate

$$\dot{q}_i = \frac{p_i}{m_i}, \quad \dot{p}_i = -\nabla_{q_i} V(q) \tag{1}$$

on a time  $\tau$  starting from  $(q^n, p^n)$ .

• accept  $\tilde{q}^{n+1}$  and set  $q^{n+1}=\tilde{q}^{n+1}$  with a probability  $\min\left(1,\exp-\beta(\tilde{E}-E_n)\right)$ ; otherwise set  $q^{n+1}=q^n$ .



Two parameters : au and  $\Delta t$ .

Extensions: correlated momenta, random times  $\tau$ , constrained dynamics, ...

#### Overdamped Langevin dynamics

SDE on the configurational part only (momenta trivial to sample)

$$dq_t = -\nabla V(q_t) dt + \sigma dW_t,$$

where  $(W_t)_{t>0}$  is a standard Wiener process of dimension dN

- Numerical scheme:  $q^{n+1} = q^n \Delta t \nabla V(q^n) + \sigma \sqrt{\Delta t} G^n$
- Invariance of the canonical measure  $\nu(dq)$  when  $\sigma = (2/\beta)^{1/2}$
- Evolution PDE for the law of the process at time t:

$$\partial_t \psi = \operatorname{div}\left(\psi_\infty \nabla\left(\frac{\psi}{\psi_\infty}\right)\right), \quad \psi_\infty = Z^{-1} \exp(-\beta V)$$

Invariance + irreducibility (elliptic process):

$$\lim_{T o\infty}rac{1}{T}\int_0^T A(q_t)\,dt = \int_{\mathcal{D}} A(q)\,
u(dq)$$
 a.s

• Numerical scheme samples an approximate measure  $u_{\Delta t}(dq)$ 

#### Convergence of the Overdamped Langevin dynamics

- Several notions of convergence: here, longtime convergence in law
- Relative entropy  $\mathcal{H}(\psi(t,\cdot) \mid \psi_{\infty}) = \int \ln \left(\frac{\psi(t,\cdot)}{\psi_{\infty}}\right) \psi_{\infty}$
- It holds  $\|\psi(t,\cdot)-\psi_\infty\|_{L^1} \leq \sqrt{2\mathcal{H}(\psi(t,\cdot)\,|\,\psi_\infty)}$
- Fisher information  $I(\psi(t,\cdot)\,|\,\psi_\infty) = \int \left|\nabla \ln\left(\frac{\psi(t,\cdot)}{\psi_\infty}\right)\right|^2 \psi_\infty$
- A simple computation shows  $\dfrac{d}{dt}H(\psi(t,\cdot)\,|\,\psi_\infty) = -\beta^{-1}I(\psi(t,\cdot)\,|\,\psi_\infty)$
- When a Logarithmic Sobolev Inequality holds for  $\psi_{\infty}$ , namely  $H(\phi|\psi_{\infty}) \leq \frac{1}{2R}I(\phi|\psi_{\infty})$ , then, by Gronwall's lemma, the relative entropy converges exponentially fast to 0, as well as the total variation distance
- Obtaining LSI: Bakry-Emery criterion (convexity), Gross (tensorization),
   Holley-Stroock's perturbation result

#### Langevin dynamics

Stochastic perturbation of the Hamiltonian dynamics

$$\begin{cases} dq_t = M^{-1}p_t dt \\ dp_t = -\nabla V(q_t) dt - \gamma M^{-1}p_t dt + \sigma dW_t \end{cases}$$

- Fluctuation/dissipation relation  $\sigma^2=2\gamma k_{\mathrm{B}}T=2\gamma/\beta$
- Invariance of the canonical measure (stationary solution of the Fokker-Planck equation)
- Convergence of the trajectorial average, starting from a given  $(q^0, p^0)$ :

$$\lim_{T \to +\infty} \frac{1}{T} \int_0^T A(q_t, p_t) dt = \frac{\int_{T^*\mathcal{D}} A(q, p) e^{-\beta H(q, p)} dq dp}{\int_{T^*\mathcal{D}} e^{-\beta H(q, p)} dq dp} \quad \text{a.s.}$$

 Numerical schemes obtained by a splitting strategy for instance (Verlet scheme + partial randomization of momenta)

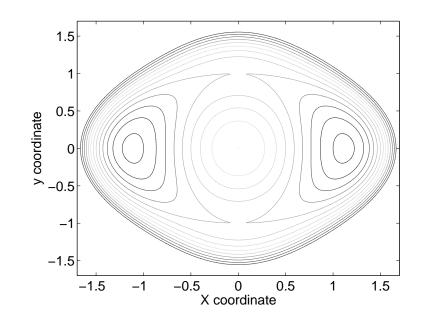
# Free energy biased dynamics

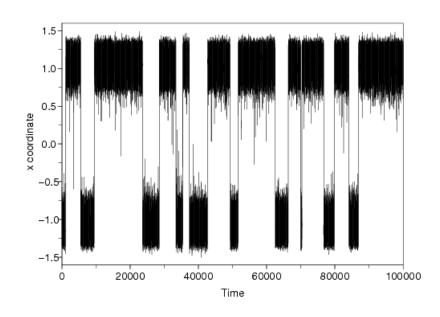
#### Metastability (1)

Numerical discretization of the overdamped Langevin dynamics:

$$q^{n+1} = q^n - \Delta t \,\nabla V(q^n) + \sigma \sqrt{\Delta t} \,G^n$$

where  $G^n \sim \mathcal{N}(0,1)$  i.i.d.

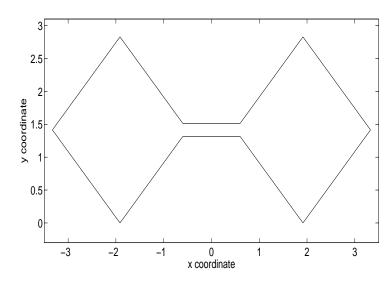




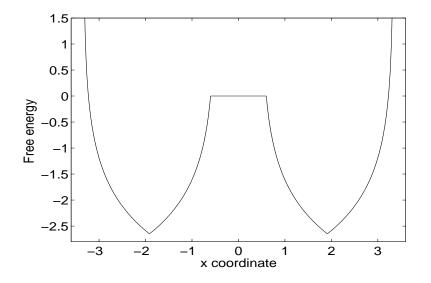
Projected trajectory in the x variable for  $\Delta t = 0.01$ ,  $\beta = 8$ .

#### Metastability (2)

- Although the trajectorial average converges to the phase-space average, the convergence may be slow...
- Slowly evolving macroscopic function of the microscopic degrees of freedom
- Two origins: energetic or entropic barriers (in fact, free energy barrier)



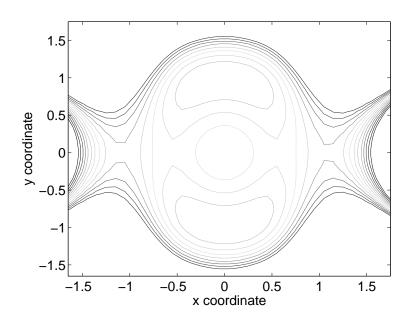
(a) Entropic barrier.

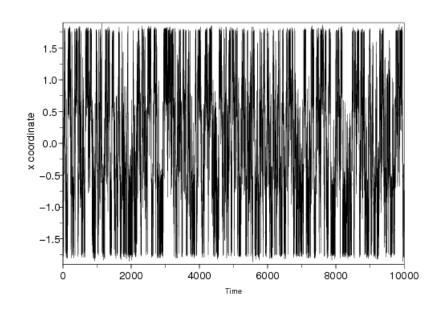


(b) Associated free energy.

#### Metastability (3)

• Assume the free energy F associated with the slow direction x has been computed, and sample the modified potential  $\mathcal{V}(x,y) = V(x,y) - F(x)$ .





Projected trajectory in the x variable for  $\Delta t = 0.01$ ,  $\beta = 8$ .

- Many more transitions! The variable x is uniformly distributed.
- Estimate canonical averages through reweighting:  $\frac{\sum_{n=1}^{N} A(x^n) e^{-\beta F(x^n)}}{\sum_{n=1}^{N} e^{-\beta F(x^n)}}$

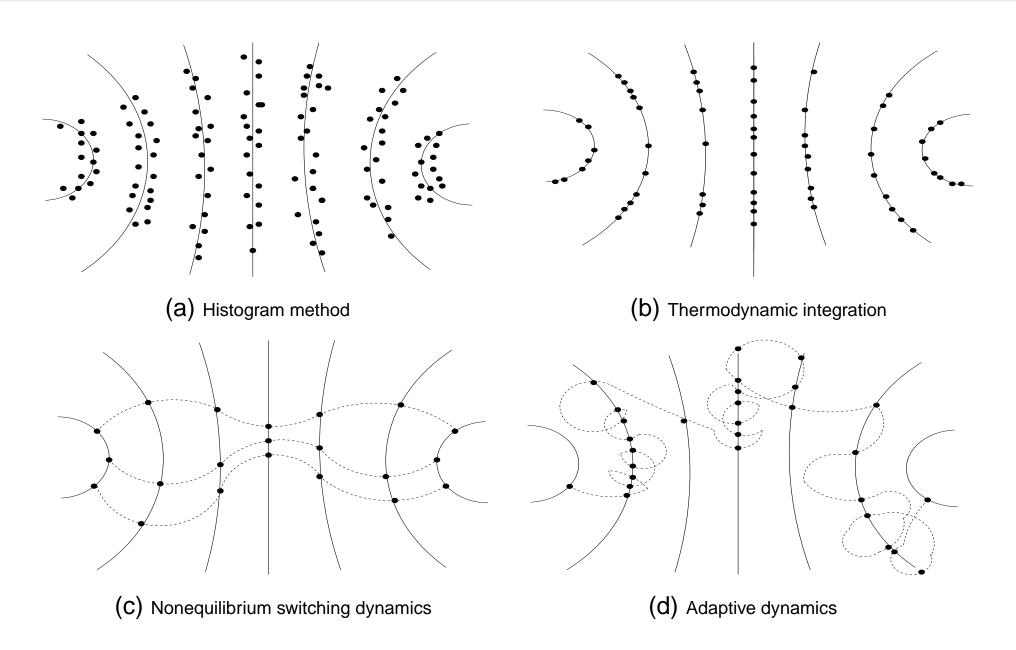
### Computation of free energy differences (1)

- Absolute free energy  $F = -\frac{1}{\beta} \ln \int_{T^*\mathcal{D}} \mathrm{e}^{-\beta H(q,p)} \, dq \, dp$
- Motivation (Gibbs, 1902):
  - canonical measure  $\mu(q,p) = Z^{-1} \exp(-\beta H(q,p))$
  - start from the thermodynamic identity F = U TS
  - average energy  $U = \int H\mu$
  - entropy  $S=-k_{\mathrm{B}}\int\mu\ln\mu$
- (given) reaction coordinate  $\xi : \mathbb{R}^{3N} \to \mathbb{R}^m$  (angle, length,...):

$$\Delta F = -\beta^{-1} \ln \left( \frac{\int_{T^*\mathcal{D}} e^{-\beta H(q,p)} \, \delta_{\xi(q)-z_1} \, dq \, dp}{\int_{T^*\mathcal{D}} e^{-\beta H(q,p)} \, \delta_{\xi(q)-z_0} \, dq \, dp} \right).$$

Recall  $\delta_{\xi(q)-z} = |\nabla \xi|^{-1} d\sigma_{\Sigma_z}$  supported on  $\Sigma_z = \{\xi(q) = z\}$ 

## Cartoon comparison of the methods



#### Adaptive dynamics (1)

• Simplified setting: q=(x,y) and  $\xi(q)=x\in\mathbb{R}$  so that

$$F(x_2) - F(x_1) = -\beta^{-1} \ln \left( \frac{\overline{\psi}_{eq}(x_2)}{\overline{\psi}_{eq}(x_1)} \right), \quad \overline{\psi}_{eq}(x) = \int e^{-\beta V(x,y)} dy$$

- Notice that the mean force  $F'(x) = \frac{\int \partial_x V(x,y) \, \mathrm{e}^{-\beta V(x,y)} \, dy}{\int \mathrm{e}^{-\beta V(x,y)} \, dy}$
- The dynamics  $dq_t = -\nabla V(q_t)\,dt + \sqrt{\frac{2}{\beta}}\,dW_t$  is metastable, contrarily to

$$\begin{cases} dq_t = -\nabla \left( V(q_t) - F(\xi(q_t)) \right) dt + \sqrt{\frac{2}{\beta}} dW_t \\ F'(x) = \mathbb{E}_{\mu} \left( \partial_x V(q) \, \middle| \, \xi(q) = x \right) \end{cases}$$

• Replace equilibrium expectation with  $F'(t,x) = \mathbb{E}\Big(\partial_x V(q_t)\,\Big|\,\xi(q_t) = x\Big)$ 

#### Adaptive dynamics: numerical implementation

Adaptive Biasing Force method<sup>a</sup>

$$\begin{cases} dq_t = -\nabla \left( V(q_t) - F(t, \xi(q_t)) \right) dt + \sqrt{\frac{2}{\beta}} dW_t \\ F'(t, x) = \mathbb{E} \left( \partial_x V(q) \, \middle| \, \xi(q_t) = x \right) \end{cases}$$

- Can be proved to converge as  $t \to +\infty^b$
- Replace the conditional expectation by a time-average:

$$\mathbb{E}\Big(\partial_x V(q_t) \,\Big|\, \xi(q_t) = x\Big) \simeq \frac{1}{t} \int_0^t \partial_x V(q_s) \,\mathbf{1}_{\xi(q_s) - x} \,ds$$

- Possibly use several replicas of the system, driven by independent noises and contributing to the same biasing potential
- Selection strategy<sup>c</sup> to enhance the diffusion

<sup>&</sup>lt;sup>a</sup>See the works by Darve, Pohorille, Chipot, Hénin, ...

<sup>&</sup>lt;sup>b</sup> T. Lelièvre, M. Rousset and G. Stoltz, Nonlinearity 21 (2008) 1155-1181

<sup>&</sup>lt;sup>c</sup>T. Lelièvre, M. Rousset and G. Stoltz, *J. Chem. Phys.* **126** (2007) 134111

#### Adaptive dynamics: convergence

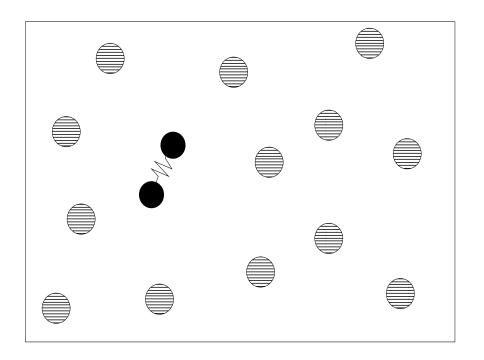
• Nonlinear PDE on the law  $\psi(t,q)$ :

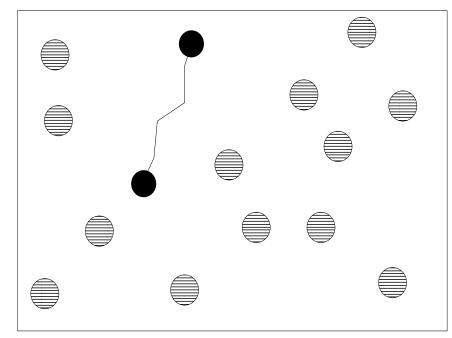
$$\begin{cases} \partial_t \psi = \operatorname{div} \left[ \nabla \left( V - F_{\text{bias}}(t, x) \right) \psi + \beta^{-1} \nabla \psi \right], \\ F'_{\text{bias}}(t, x) = \frac{\int \partial_x V(x, y) \psi(t, x, y) \, dy}{\int \psi(t, x, y) \, dy}. \end{cases}$$

- Stationary solution  $\psi_{\infty} \propto \mathrm{e}^{-\beta(V-F\circ\xi)}$
- Simple diffusion for the marginals  $\;\partial_t\overline{\psi}=\partial_{xx}\,\overline{\psi}\;$
- Decomposition of the total entropy  $H(\psi \,|\, \psi_\infty) = \int_{\mathcal{D}} \ln\left(\frac{\psi}{\psi_\infty}\right) \psi$  into a macroscopic contribution (marginals in x) and a microscopic one (conditioned measures)
- Convergence of the microscopic entropy provided some uniform logarithmic Sobolev inequality holds for the conditioned measures

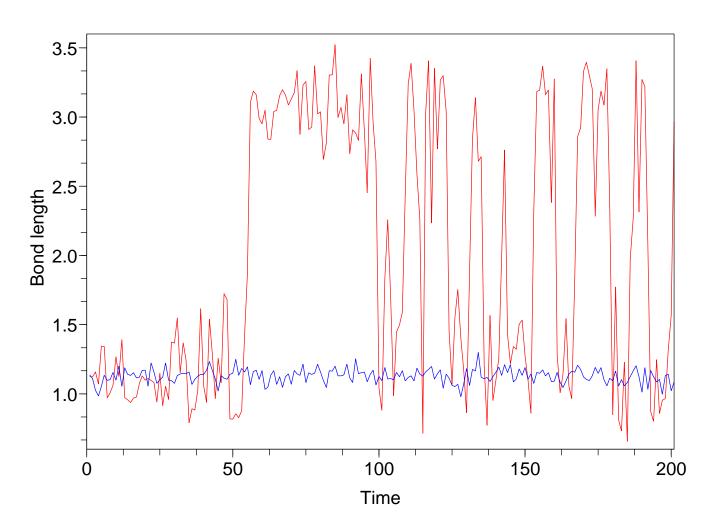
## Application: Solvatation effects on conformational changes (1)

- ullet Two particules  $(q_1,q_2)$  interacting through  $V_{
  m S}(r)=h\left[1-rac{(r-r_0-w)^2}{w^2}
  ight]^2$
- Solvent: particules interacting through the purely repulsive potential  $V_{\text{WCA}}(r) = 4\epsilon \left[ \left( \frac{\sigma}{r} \right)^{12} \left( \frac{\sigma}{r} \right)^{6} \right] + \epsilon \text{ if } r \leq r_0, \ 0 \text{ if } r > r_0$
- Reaction coordinate  $\xi(q)=\frac{|q_1-q_2|-r_0}{2w}$ , compact state  $\xi^{-1}(0)$ , stretched state  $\xi^{-1}(1)$





#### Application: Solvatation effects on conformational changes (2)



Blue: without biasing term. Red: adaptive biasing force.

Parameters: h=10, density  $\rho=0.25\,\sigma^{-2}$ , w=1,  $\beta=3$ ,  $\epsilon=1$ ,  $\tau=0.1$ 

#### Conclusion – Mathematical classification (september 2009)

Free energy perturbation  $\rightarrow$  Homogeneous MCs and SDEs

Thermodynamic integration  $\rightarrow$  Projected MCs and SDEs

Nonequilibrium dynamics  $\rightarrow$  Nonhomogenous MCs and SDEs

Adaptive dynamics  $\rightarrow$  Nonlinear SDEs and MCs

Selection procedures  $\rightarrow$  Particle systems and jump processes

- Which method is the most efficient in practice...?
- Some advertisement for a book to appear this year:

T. Lelièvre, M. Rousset and G. Stoltz *Free energy computations: A Mathematical Perspective*, Imperial College Press.