

(Non)Equilibrium computation of free energy differences using Langevin dynamics

Gabriel STOLTZ

CERMICS & MICMAC project team, Ecole des Ponts ParisTech

<http://cermics.enpc.fr/~stoltz/>

- A brief presentation of methods to compute free energy differences
- Thermodynamic integration using Langevin dynamics
- Nonequilibrium Langevin dynamics

Computing free energy differences

Microscopic description of a classical system

- Positions q (configuration), momenta $p = M\dot{q}$ (M diagonal mass matrix)
- Microscopic description of a classical system (N particles):

$$(q, p) = (q_1, \dots, q_N, p_1, \dots, p_N) \in \mathcal{E}$$

- For instance, $\mathcal{E} = T^*\mathcal{D} = \mathcal{D} \times \mathbb{R}^{3N}$ with $\mathcal{D} = \mathbb{R}^{3N}$ or \mathbb{T}^{3N}
- More complicated situations can be considered... (constraints defining submanifolds of the phase space)

- Hamiltonian $H(q, p) = \sum_{i=1}^N \frac{p_i^2}{2m_i} + V(q_1, \dots, q_N)$

- All the physics is contained in V
- **Canonical** probability measure:

$$\mu(dq dp) = Z^{-1} e^{-\beta H(q,p)} dq dp, \quad \beta = \frac{1}{k_B T}$$

- The aim is to compute an approximation of the **high dimensional** integral

$$\langle A \rangle = \int_{T^* \mathcal{D}} A(q, p) \mu(dq dp)$$

- Restated as a one-dimensional integral using **ergodic** properties of an **irreducible** dynamics for which the canonical measure is **invariant**:

$$\lim_{T \rightarrow +\infty} \frac{1}{T} \int_0^T A(q_t, p_t) dt = \int_{T^* \mathcal{D}} A(q, p) \mu(dq dp) \quad \text{a.s.}$$

- Overdamped Langevin dynamics (momenta trivial to sample)

$$dq_t = -\nabla V(q_t) dt + \sqrt{\frac{2}{\beta}} dW_t$$

- **Zero mass** limit of the Langevin dynamics or the limit of the Langevin dynamics when the **friction goes to infinity** (with suitable time rescaling)

- Stochastic perturbation of the Hamiltonian dynamics

$$\begin{cases} dq_t = M^{-1}p_t dt \\ dp_t = -\nabla V(q_t) dt - \gamma(q_t)M^{-1}p_t dt + \sigma(q_t) dW_t \end{cases}$$

- Fluctuation/dissipation relation $\sigma\sigma^T = \frac{2}{\beta}\gamma$
- Invariance of the canonical measure when it is a stationary solution of the **Fokker-Planck equation** $\partial_t\psi = \mathcal{L}^*\psi$ with

$$\mathcal{L} = \{\cdot, H\} + \frac{e^{\beta H}}{\beta} \operatorname{div}_p (\gamma e^{-\beta H} \nabla_p \cdot)$$

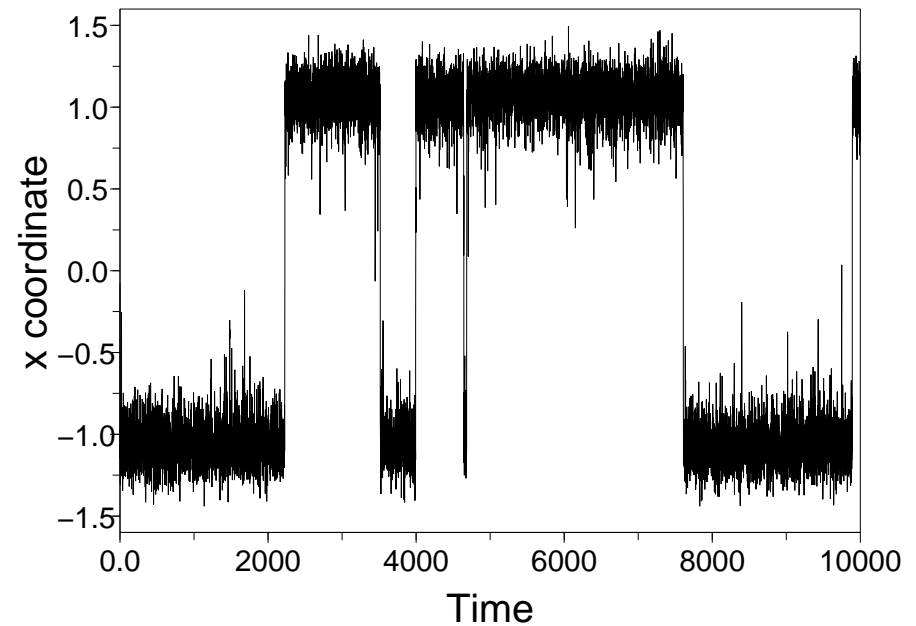
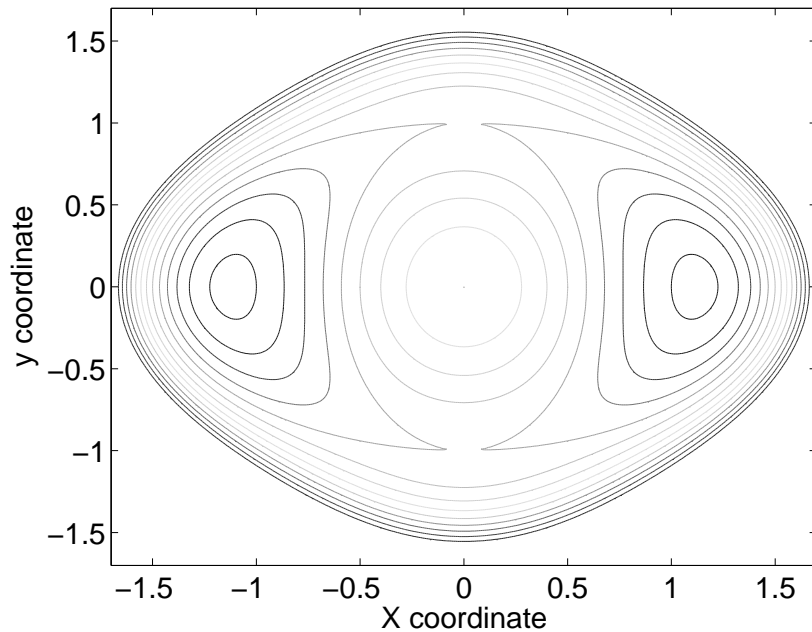
and $\{A_1, A_2\} = (\nabla_q A_1)^T \nabla_p A_2 - (\nabla_p A_1)^T \nabla_q A_2$

- Irreducibility amounts to controllability (Hörmander condition)
- Numerical schemes obtained by a **splitting strategy** for instance (Verlet scheme + partial randomization of momenta)

Numerical discretization of the overdamped Langevin dynamics:

$$q^{n+1} = q^n - \Delta t \nabla V(q^n) + \sqrt{\frac{2\Delta t}{\beta}} \mathcal{G}^n$$

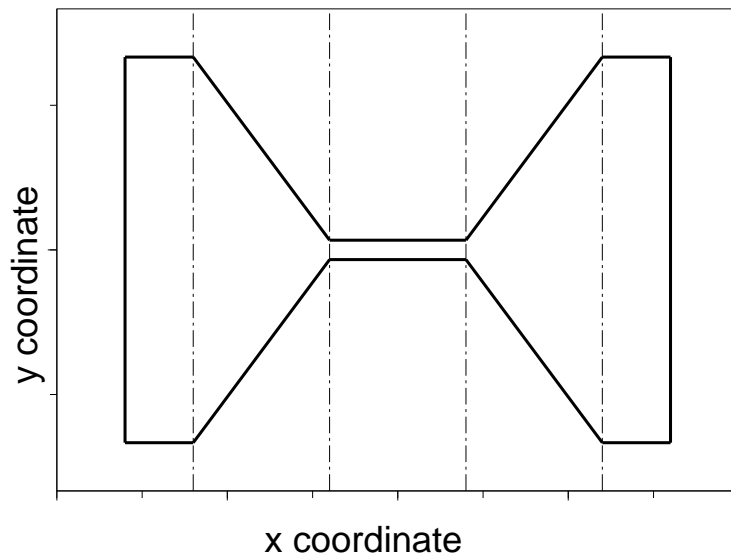
where $\mathcal{G}^n \sim \mathcal{N}(0, \text{Id}_{dN})$ i.i.d.



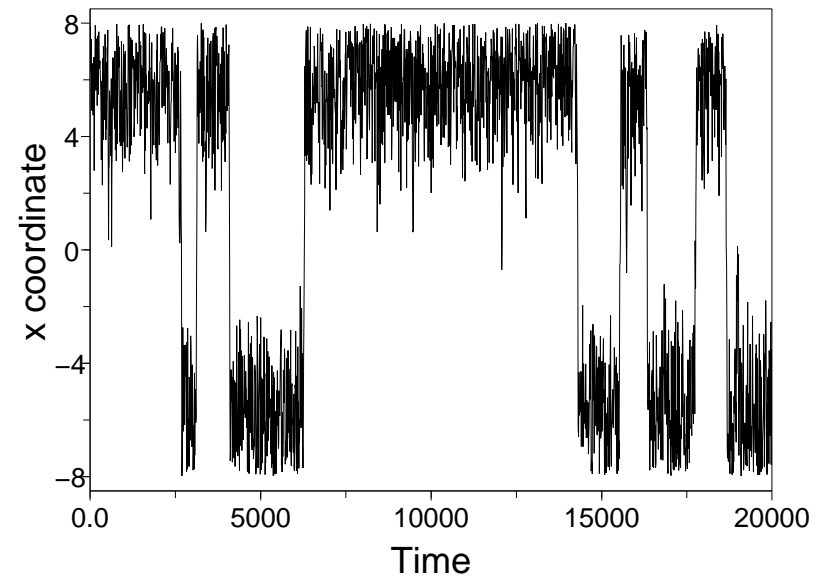
Projected trajectory in the x variable for $\Delta t = 0.01$, $\beta = 8$.

Metastability (2)

- Although the trajectory average converges to the phase-space average, the convergence may be **slow**...
- Slowly evolving macroscopic function of the microscopic degrees of freedom: **reaction coordinate** $\xi(q) \in \mathbb{R}^m$ with $m \ll N$
- Two origins : **energetic** or **entropic** barriers (in fact, **free energy** barriers)



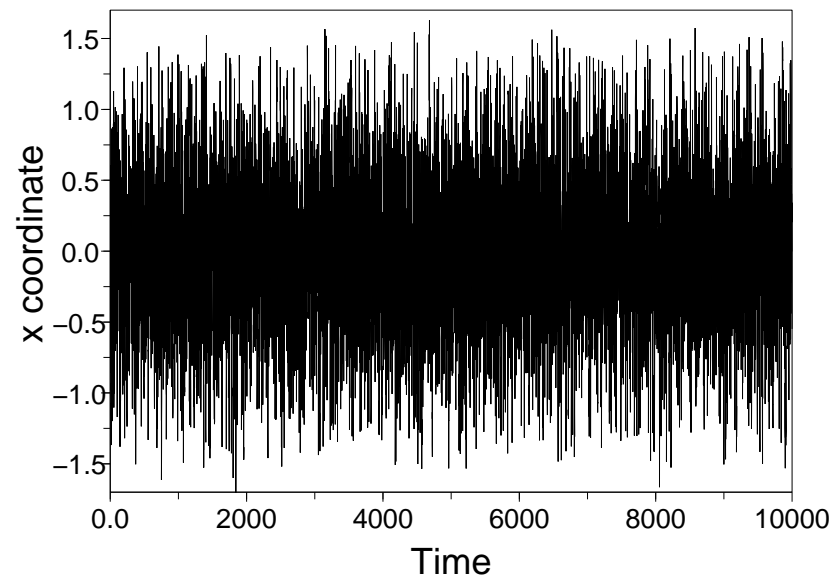
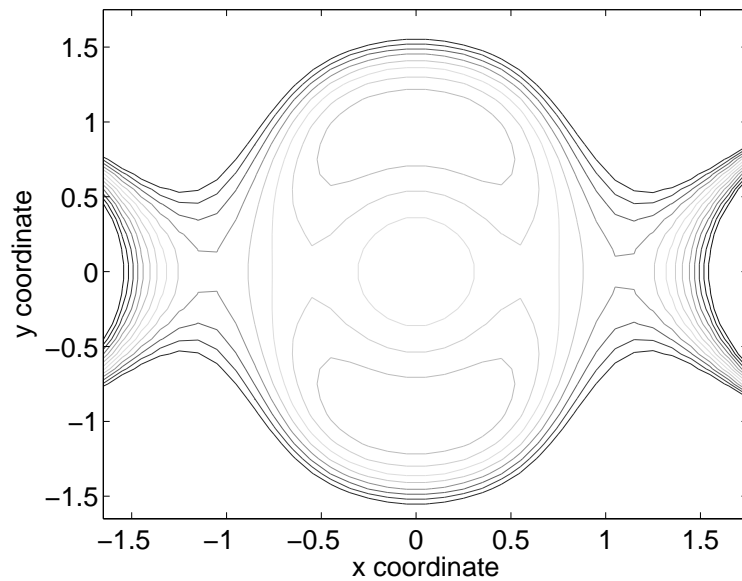
(a) Entropic barrier.



(b) Associated trajectory.

Metastability (3)

- Assume the free energy F associated with the slow direction x has been computed, and **sample the modified potential** $\mathcal{V}(x, y) = V(x, y) - F(x)$.



Projected trajectory in the x variable for $\Delta t = 0.01$, $\beta = 8$.

- Many more transitions! The variable x is **uniformly distributed**.
- Reweighting** with weights $e^{-\beta F(x)}$ to compute canonical averages
- Compute efficiently the free energy?

Computation of free energy differences

- Alchemical transition: indexed by an **external parameter** λ (force field parameter, magnetic field,...)

$$\Delta F = -\beta^{-1} \ln \left(\frac{\int_{T^* \mathcal{D}} e^{-\beta H_1(q,p)} dq dp}{\int_{T^* \mathcal{D}} e^{-\beta H_0(q,p)} dq dp} \right) ;$$

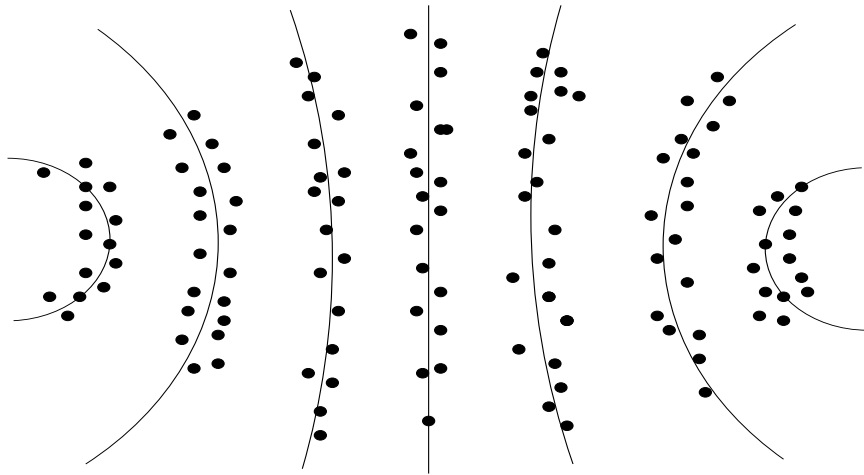
Typically, $H_\lambda = (1 - \lambda)H_0 + \lambda H_1$

- (given) **reaction coordinate** $\xi : \mathbb{R}^{3N} \rightarrow \mathbb{R}^m$ (angle, length,...):

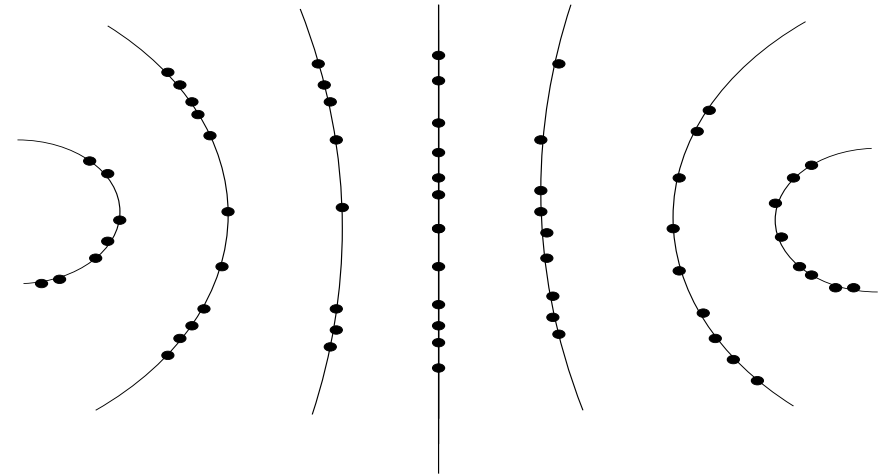
$$\Delta F = -\beta^{-1} \ln \left(\frac{\int_{T^* \Sigma_z} e^{-\beta H(q,p)} \delta_{\xi(q)-z_1}(dq) dp}{\int_{T^* \Sigma_z} e^{-\beta H(q,p)} \delta_{\xi(q)-z_0}(dq) dp} \right) .$$

with $\Sigma_z = \{q \in \mathcal{D} \mid \xi(q) = z\}$. Recall $\delta_{\xi(q)-z} = |\nabla \xi|^{-1} d\sigma_{\Sigma_z}$.

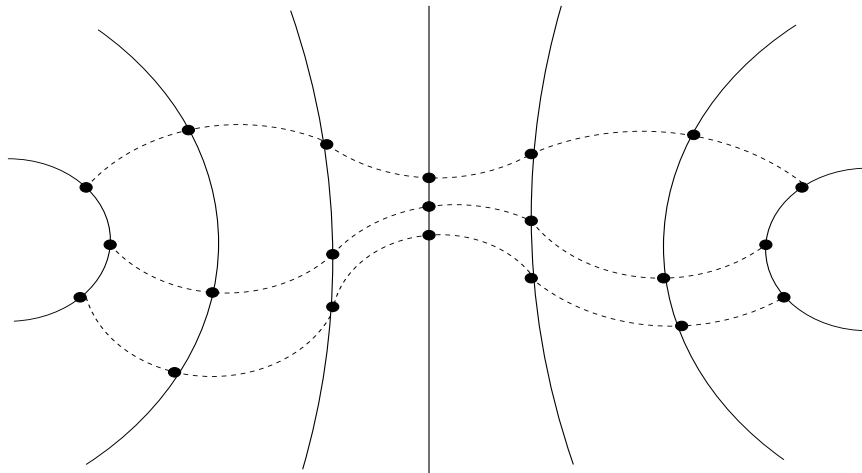
Cartoon comparison of the methods (reaction coordinate case)



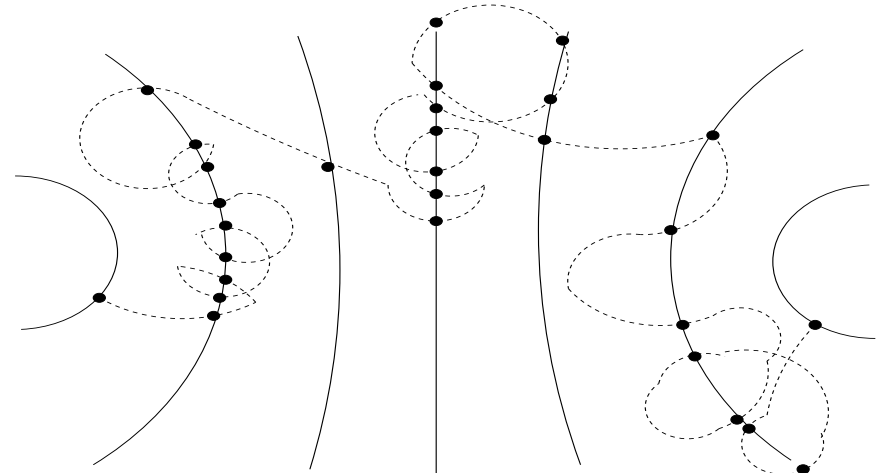
(a) Histogram method



(b) Thermodynamic integration



(c) Nonequilibrium switching dynamics



(d) Adaptive dynamics

Some elements on the scientific landscape

- We focus on the **reaction coordinate** case
- Histogram methods: WHAM (Kumar *et al.*), **MBAR** (Chodera/Shirts)
- Thermodynamic integration in the **Hamiltonian** case (Carter *et al.*, den Otter/Briels, Sprik/Ciccotti, Hartmann/Schütte) or for **overdamped Langevin** dynamics (Ciccotti/Lelièvre/Vanden-Eijnden)
- Nonequilibrium methods: **overdamped case** (Lelièvre/Rousset/Stoltz) or **steered versions** (potentials $V_\lambda(q) = V(q) + K(\xi(q) - \lambda)^2$)
- Adaptive methods: **adaptive biasing force** (Darve/Pohorille, Chipot/Hénin), nonequilibrium metadynamics (Bussi/Laio/Parrinello), **self-healing umbrella sampling** (Marsili *et al.*, Dickson *et al.*)
- Aims of this work:
 - Thermodynamic integration with Langevin dynamics
 - Nonequilibrium Langevin dynamics

Thermodynamic integration with Langevin dynamics

- Consider the following Langevin process:

$$\begin{cases} dq_t = M^{-1} p_t dt, \\ dp_t = -\nabla V(q_t) dt - \gamma(q_t) M^{-1} p_t dt + \sigma(q_t) dW_t + \nabla \xi(q_t) d\lambda_t, \\ \xi(q_t) = z \end{cases}$$

- Standard fluctuation/dissipation relation $\sigma \sigma^T = \frac{2}{\beta} \gamma$
- **Hidden velocity constraint:** $\frac{d\xi(q_t)}{dt} = v_\xi(q_t, p_t) = \nabla \xi(q_t)^T M^{-1} p_t = 0$
- The corresponding phase-space is $\Sigma_{\xi, v_\xi}(z, 0)$ where

$$\Sigma_{\xi, v_\xi}(z, v_z) = \left\{ (q, p) \in \mathbb{R}^{6N} \mid \xi(q) = z, v_\xi(q, p) = v_z \right\}$$

- An **explicit expression of the Lagrange multiplier** can be found by computing the second derivative in time of the constraint

- Reformulation of the constrained Langevin dynamics as

$$\begin{cases} dq_t = M^{-1} p_t dt, \\ dp_t = -\nabla V(q_t) dt + \nabla \xi(q_t) f_{\text{rgd}}^M(q_t, p_t) dt - \gamma_P(q_t) M^{-1} p_t dt + \sigma_P(q_t) dW_t, \end{cases}$$

- Projected fluctuation/dissipation matrices

$$(\sigma_P, \gamma_P) := (P_M \sigma, P_M \gamma P_M^T)$$

where $P_M(q) = \text{Id} - \nabla \xi(q) G_M^{-1}(q) \nabla \xi(q)^T M^{-1}$

- **Constraining force** (projection of the conservative force + centrifugal term)

$$f_{\text{rgd}}^M(q, p) = G_M^{-1}(q) \nabla \xi(q)^T M^{-1} \nabla V(q) - G_M^{-1}(q) \text{Hess}_q(\xi)(M^{-1} p, M^{-1} p)$$

where $G_M(q) = \nabla \xi(q)^T M^{-1} \nabla \xi(q)$

- Generator of the dynamics: $\mathcal{L} = \mathcal{L}^{\text{ham}} + \mathcal{L}^{\text{thm}}$ with

$$\mathcal{L}^{\text{thm}} = \frac{1}{\beta} e^{\beta H} \operatorname{div}_p \left(e^{-\beta H} \gamma_P \nabla_p \cdot \right)$$

- Invariant measure

$$\mu_{\Sigma_{\xi, v_{\xi}}(z, 0)}(dq dp) = Z_{z, 0}^{-1} e^{-\beta H(q, p)} \sigma_{\Sigma_{\xi, v_{\xi}}(z, 0)}(dq dp),$$

where $\sigma_{\Sigma_{\xi, v_{\xi}}(z, v_z)}(dq dp)$ is the phase space Liouville measure of $\Sigma_{\xi, v_{\xi}}(z, v_z)$ induced by the symplectic matrix J

- Reversibility: $\text{Law}(q_t, p_t; 0 \leq t \leq T) = \text{Law}(q_{T-t}, -p_{T-t}; 0 \leq t \leq T)$
- Ergodicity (longtime trajectorial convergence)
- The normalizing constant of this canonical distribution defines a **rigid free energy** (more on this later)

- **Splitting** in a Hamiltonian part + constrained Ornstein-Uhlenbeck process
- Midpoint scheme for the momenta (**reversible** for the canonical measure with constraints)

$$p^{n+1/4} = p^n - \frac{\Delta t}{4} \gamma M^{-1} (p^n + p^{n+1/4}) + \sqrt{\frac{\Delta t}{2}} \sigma \mathcal{G}^n + \nabla \xi(q^n) \lambda^{n+1/4},$$

with the constraint $\nabla \xi(q^n)^T M^{-1} p^{n+1/4} = 0$

- RATTLE scheme (symplectic)

$$\begin{cases} p^{n+1/2} &= p^{n+1/4} - \frac{\Delta t}{2} \nabla V(q^n) + \nabla \xi(q^n) \lambda^{n+1/2}, \\ q^{n+1} &= q^n + \Delta t M^{-1} p^{n+1/2}, \\ p^{n+3/4} &= p^{n+1/2} - \frac{\Delta t}{2} \nabla V(q^{n+1}) + \nabla \xi(q^{n+1}) \lambda^{n+3/4}, \end{cases}$$

with $\xi(q^{n+1}) = z$ and $\nabla \xi(q^{n+1})^T M^{-1} p^{n+3/4} = 0$

- **Metropolization** of the RATTLE part to eliminate the time-step error
- **Overdamped limit** (exact sampling)

- The free energy can be estimated from constrained samplings as

$$\begin{aligned} F(z) &= -\frac{1}{\beta} \ln \int_{\Sigma(z) \times \mathbb{R}^{3N}} e^{-\beta H(q,p)} \delta_{\xi(q)-z}(dq) dp \\ &= F_{\text{rgd}}^M(z) - \frac{1}{\beta} \ln \int_{T^*\Sigma(z)} (\det G_M)^{-1/2} d\mu_{\Sigma_{\xi, v_{\xi}}(z,0)} + C \end{aligned}$$

with the **rigid free energy** (constraints on both q and p)

$$F_{\text{rgd}}^M(z) = -\frac{1}{\beta} \ln \int_{\Sigma_{\xi, v_{\xi}}(z,0)} e^{-\beta H(q,p)} d\mu_{\Sigma_{\xi, v_{\xi}}(z,0)}$$

- Extension to the case of molecular constraints
- Thermodynamic integration through the computation of the **mean force**

$$\nabla_z F_{\text{rgd}}^M(z) = \int_{\Sigma_{\xi, v_{\xi}}(z,0)} f_{\text{rgd}}^M(q, p) \mu_{\Sigma_{\xi, v_{\xi}}(z,0)}(dq dp)$$

- Longtime (a.s.) convergence

$$\lim_{T \rightarrow +\infty} \frac{1}{T} \int_0^T d\lambda_t = \nabla_z F_{\text{rgd}}^M(z)$$

- **Variance reduction**: keep only the Hamiltonian part of λ_t
- Numerical discretization: approximate the mean force using only the **Lagrange multipliers from the RATTLE part**:

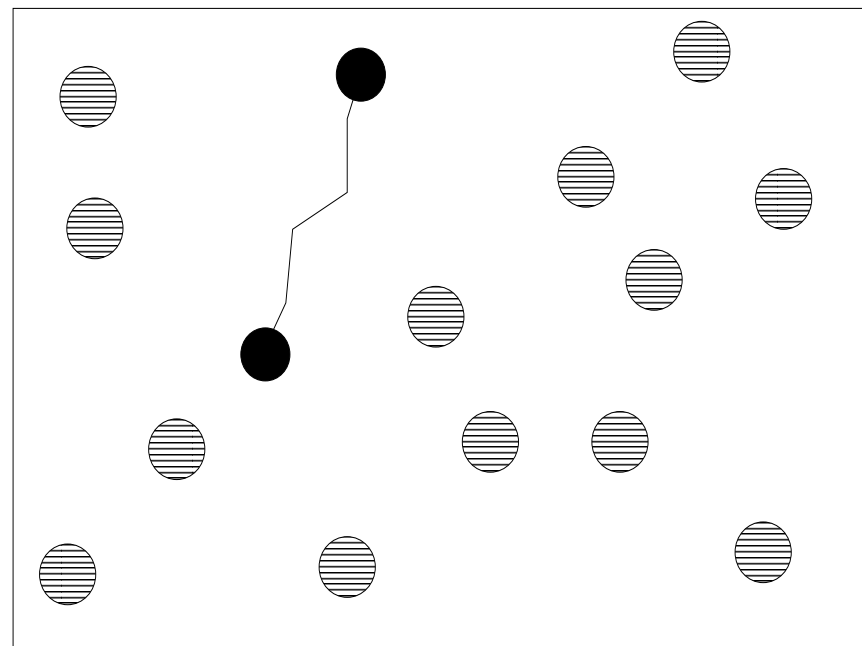
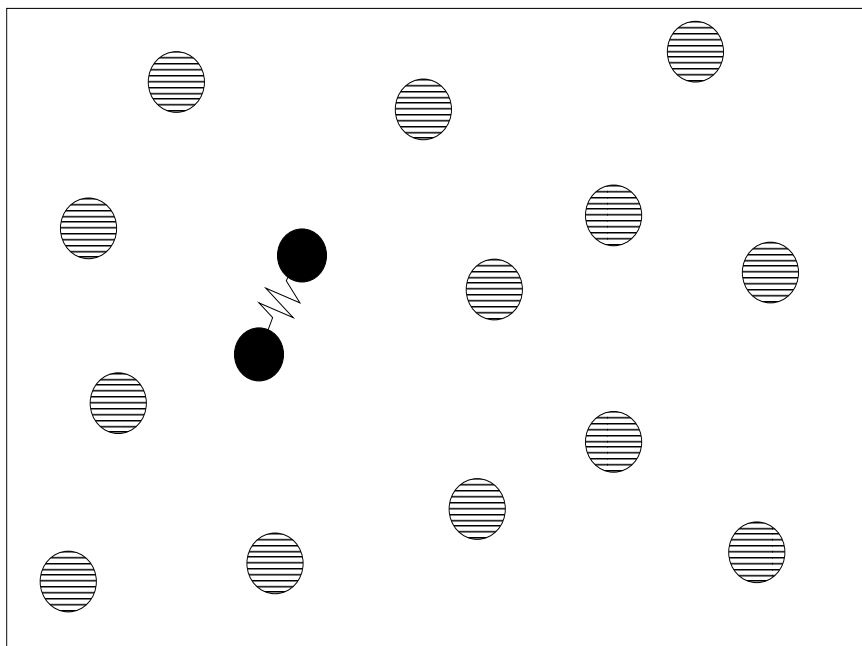
$$\nabla_z F_{\text{rgd}}^M(z) \simeq \frac{1}{N} \sum_{n=0}^{N-1} f_{\text{rgd}}^M(q^n, p^n) \simeq \frac{1}{N\Delta t} \sum_{n=0}^{N-1} (\lambda^{n+1/2} + \lambda^{n+3/4})$$

- Consistency result

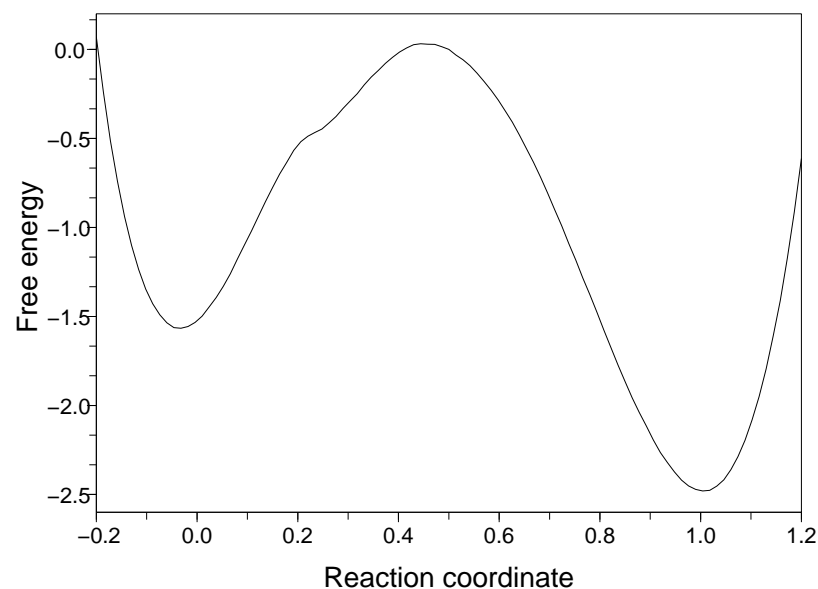
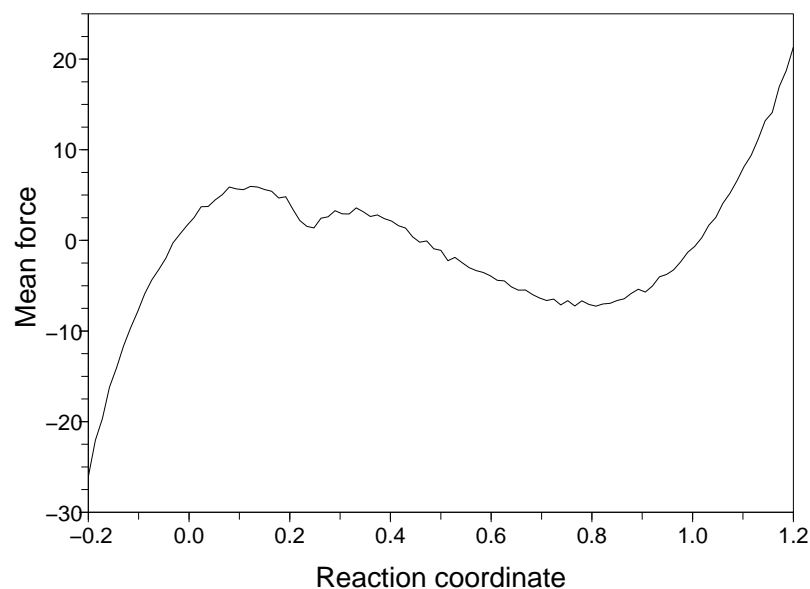
$$\lambda^{n+1/2} + \lambda^{n+3/4} = \frac{\Delta t}{2} \left(f_{\text{rgd}}^M(q^n, p^{n+1/2}) + f_{\text{rgd}}^M(q^{n+1}, p^{n+1/2}) \right) + O(\Delta t^3)$$

Application: Solvation effects on conformational changes (1)

- Two particles (q_1, q_2) interacting through $V_S(r) = h \left[1 - \frac{(r - r_0 - w)^2}{w^2} \right]^2$
- Solvent: particles interacting through the purely repulsive potential $V_{\text{WCA}}(r) = 4\epsilon \left[\left(\frac{\sigma}{r} \right)^{12} - \left(\frac{\sigma}{r} \right)^6 \right] + \epsilon$ if $r \leq r_0$, 0 if $r > r_0$
- Reaction coordinate $\xi(q) = \frac{|q_1 - q_2| - r_0}{2w}$, compact state $\xi^{-1}(0)$, stretched state $\xi^{-1}(1)$



Application: Solvation effects on conformational changes (2)



Left: Estimated **mean force**. Right: Corresponding **potential of mean force**.

Parameters: $\beta = 1$, $N = 100$ particles, solvent density $\rho = 0.436$, WCA interactions $\sigma = 1$ and $\varepsilon = 1$, dimer $w = 2$ and $h = 2$. Mean force estimated at the values $z_i = z_{\min} + i\Delta z$, with $z_{\min} = -0.2$, $z_{\max} = 1.2$ and $\Delta z = 0.014$, by ergodic averages obtained with the projected dynamics with Metropolis correction (time $T = 2 \times 10^4$, step size $\Delta t = 0.02$, scalar friction $\gamma = 1$).

Nonequilibrium Langevin dynamics

Presentation of the dynamics (1)

- Idea: **start at equilibrium** and **perform a switching** from the initial to the final state in a finite time T
- Schedule $z(t)$ for $t \in [0, T]$ and dynamics

$$\begin{cases} dq_t &= M^{-1} p_t dt, \\ dp_t &= -\nabla V(q_t) dt - \gamma_P(q_t) M^{-1} p_t dt + \sigma_P(q_t) dW_t + \nabla \xi(q_t) d\lambda_t, \\ \xi(q_t) &= z(t), \end{cases} \quad (C_q(t))$$

with initial conditions $(q_0, p_0) \sim \mu_{\Sigma_{\xi, v_{\xi}}(z(0), \dot{z}(0))}(dq dp)$

- **Projected** fluctuation/dissipation relation $(\sigma_P, \gamma_P) := (P_M \sigma, P_M \gamma P_M^T)$ so that the noise act only in the direction orthogonal to $\nabla \xi$
- Hidden constraint on the reaction coordinate velocity $v_{\xi}(q, p) = \dot{z}(t)$

Presentation of the dynamics (2)

- **Backward dynamics:** start at equilibrium for the final value of the schedule, switching with a time-reversed schedule $t' \mapsto z(T - t')$
- Initial conditions $(q_0^b, p_0^b) \sim \mu_{\Sigma_{\xi, v_{\xi}}}(z(T), \dot{z}(T))(dq dp)$ and evolution

$$\begin{cases} dq_{t'}^b = -M^{-1}p_{t'}^b dt', \\ dp_{t'}^b = \nabla V(q_{t'}^b) dt' - \gamma_P(q_{t'}^b)M^{-1}p_{t'}^b dt' + \sigma_P(q_{t'}^b) dW_{t'}^b + \nabla \xi(q_{t'}^b) d\lambda_{t'}^b, \\ \xi(q_{t'}^b) = z(T - t') \end{cases}$$

- The generator of the forward dynamics is (Gram matrix $\Gamma = \{\Xi, \Xi\}$, $\zeta = (z, \dot{z})$)

$$\mathcal{L}_t^f = \{\cdot, H\}_{\Xi} + \mathcal{L}_{\Xi}^{\text{thm}} + \{\cdot, \Xi\} \Gamma^{-1} \dot{\zeta}(t)$$

while the generator of the backward dynamics is $\mathcal{L}_{t'}^b = \mathcal{R} \mathcal{L}_{T-t'}^f \mathcal{R}$ (where $\mathcal{R} : \phi \mapsto \phi \circ S$ is the momentum flip operator with $S(q, p) = (q, -p)$)

- **Rigid** free energy $F_{\text{rgd}}^M(z, v_z) = -\frac{1}{\beta} \ln \int_{\Sigma_{\xi, v_{\xi}}(z, v_z)} e^{-\beta H(q, p)} d\mu_{\Sigma_{\xi, v_{\xi}}(z, v_z)}$
- Actual free energy recovered from the difference $F(z) - F_{\text{rgd}}^{\xi, v_{\xi}}(z, v_z)$, which equals, up to an unimportant additive constant:

$$-\frac{1}{\beta} \ln \int_{\Sigma_{\xi, v_{\xi}}(z, v_z)} (\det G_M(q))^{-1/2} \exp\left(\frac{\beta}{2} v_z^T G_M^{-1}(q) v_z\right) \mu_{\Sigma_{\xi, v_{\xi}}(z, v_z)}(dq dp)$$

- **Work** performed during the switching: several expressions

- **Force times displacement:** $\mathcal{W}_{0,T}(\{q_t, p_t\}_{0 \leq t \leq T}) = \int_0^T \dot{z}(t)^T d\lambda_t$

- **Energy variations:** $\mathcal{W}_{0,T}(\{q_t, p_t\}_{0 \leq t \leq T}) = \int_0^T w(t, q_t, p_t) dt$ where

$$w(t, q, p) = \dot{\zeta}(t)^T \Gamma^{-1} \{\Xi, H\}(q, p) = \left(\frac{d}{dh} H \circ \Phi_{t, t+h} \right) \Big|_{h=0}(q, p) \text{ with } \Phi$$

the flow of the switched Hamiltonian dynamics

- For any bounded path functional $\varphi_{[0,T]}$,

$$\frac{Z_{z(T),\dot{z}(T)}}{Z_{z(0),\dot{z}(0)}} = \frac{\mathbb{E} \left(\varphi_{[0,T]} \left(\{q_t, p_t\}_{0 \leq t \leq T} \right) e^{-\beta \mathcal{W}_{0,T}(\{q_t, p_t\}_{t \in [0,T]})} \right)}{\mathbb{E} \left(\varphi_{[0,T]}^r \left(\{q_{t'}^b, p_{t'}^b\}_{0 \leq t' \leq T} \right) \right)}$$

where $(\cdot)^r$ denotes the composition with the operation of time reversal of paths:

$$\varphi_{[0,T]}^r \left(\{q_{t'}^b, p_{t'}^b\}_{0 \leq t' \leq T} \right) = \varphi_{[0,T]} \left(\{q_{T-t}^b, p_{T-t}^b\}_{0 \leq t \leq T} \right)$$

- This leads in particular to the following **free energy estimator**

$$F(z(T)) - F(z(0)) = -\frac{1}{\beta} \ln \frac{\mathbb{E} \left(e^{-\beta [\mathcal{W}_{0,T}(\{q_t, p_t\}_{t \in [0,T]}) + C(T, q_T)]} \right)}{\mathbb{E} \left(e^{-\beta C(0, q_0)} \right)}$$

with the **corrector** $C(t, q) = \frac{1}{2\beta} \ln \left(\det G_M(q) \right) - \frac{1}{2} \dot{z}(t)^T G_M^{-1}(q) \dot{z}(t)$

- Standard methods can then be used (bridge estimators, etc)

- The proof relies on the following balance condition

$$\begin{aligned} & \int_{\Sigma_{\xi, v_{\xi}}(z(t), \dot{z}(t))} (\varphi_1 \mathcal{L}_t^f(\varphi_2) - \varphi_2 \mathcal{L}_{T-t}^b(\varphi_1)) e^{-\beta H} d\sigma_{\Sigma_{\xi, v_{\xi}}(z(t), \dot{z}(t))} \\ &= \int_{\Sigma_{\xi, v_{\xi}}(z(t), \dot{z}(t))} \beta w(t, \cdot) \varphi_1 \varphi_2 e^{-\beta H} d\sigma_{\Sigma_{\xi, v_{\xi}}(z(t), \dot{z}(t))} \\ & \quad + \frac{d}{dt} \left(\int_{\Sigma_{\xi, v_{\xi}}(z(t), \dot{z}(t))} \varphi_1 \varphi_2 e^{-\beta H} d\sigma_{\Sigma_{\xi, v_{\xi}}(z(t), \dot{z}(t))} \right) \end{aligned}$$

- Left-hand side: detailed balance contribution
- Right-hand side: evolution of the measure and work correction

- Fluctuation/dissipation part (no Lagrange multiplier needed)

$$p^{n+1/4} = p^n - \frac{\Delta t}{4} \gamma_P(q^n) M^{-1} (p^{n+1/4} + p^n) + \sqrt{\frac{\Delta t}{2}} \sigma_P(q^n) \mathcal{G}^n$$

- Hamiltonian part for the forward evolution

$$\left\{ \begin{array}{l} p^{n+1/2} = p^{n+1/4} - \frac{\Delta t}{2} \nabla V(q^n) + \nabla \xi(q^n) \lambda^{n+1/2}, \\ q^{n+1} = q^n + \Delta t M^{-1} p^{n+1/2}, \\ \xi(q^{n+1}) = z(t_{n+1}), \\ p^{n+3/4} = p^{n+1/2} - \frac{\Delta t}{2} \nabla V(q^{n+1}) + \nabla \xi(q^{n+1}) \lambda^{n+3/4}, \\ \nabla \xi(q^{n+1})^T M^{-1} p^{n+3/4} = \frac{z(t_{n+2}) - z(t_{n+1})}{\Delta t}, \end{array} \right. \quad (C_q)$$

$$\quad \quad \quad (C_p)$$

which defines a **symplectic map**

$$\Phi^n : \Sigma_{\xi, v_\xi} \left(z(t_n), \frac{z(t_{n+1}) - z(t_n)}{\Delta t} \right) \rightarrow \Sigma_{\xi, v_\xi} \left(z(t_{n+1}), \frac{z(t_{n+2}) - z(t_{n+1})}{\Delta t} \right)$$

Discrete Jarzynski-Crooks equality: Alchemical case

- Idea in the alchemical case
- Discrete schedule $\{\lambda(0), \dots, \lambda(t_{N_T})\}$ with $N_T \Delta t = T$
- Initial conditions $(q^0, p^0) \sim \mu_0(dq dp) = Z_0^{-1} \exp(-\beta H_{\lambda(0)}(q, p)) dq dp$
- Successive updates of the parameter and the configuration:
 - Change the parameter from $\lambda(n\Delta t)$ to $\lambda((n+1)\Delta t)$
 - Update work: $\mathcal{W}^{n+1/2} = \mathcal{W}^n + H_{\lambda((n+1)\Delta t)}(q^n, p^n) - H_{\lambda(n\Delta t)}(q^n, p^n)$
 - Update the configuration using the Verlet map Φ^{n+1} associated with the Hamiltonian $H_{\lambda((n+1)\Delta t)}$
 - $\mathcal{W}^{n+1} = \mathcal{W}^{n+1/2} + H_{\lambda((n+1)\Delta t)}(q^{n+1}, p^{n+1}) - H_{\lambda((n+1)\Delta t)}(q^n, p^n)$
- Total work: $\mathcal{W}^n = H_{\lambda(n\Delta t)}(q^n, p^n) - H_{\lambda(0)}(q^0, p^0)$
- It can be checked that $\mathbb{E} \left(e^{-\beta \mathcal{W}^n} \right) = \frac{Z_n}{Z_0}$ for any value of Δt such that the Verlet scheme is stable
- Extension to path functionals

Discrete Jarzynski-Crooks equality: The reaction coordinate case

- Discrete schedule $\{z(0), \dots, z(t_{N_T})\}$
- Initial conditions $(q^0, p^0) \sim \mu_{\Sigma_\xi, v_\xi} \left(z(t_0), \frac{z(t_1) - z(t_0)}{\Delta t} \right) (dq dp)$ and $(q^{b,0}, p^{b,0}) \sim \mu_{\Sigma_\xi, v_\xi} \left(z(t_{N_T}), \frac{z(t_{N_T+1}) - z(t_{N_T})}{\Delta t} \right) (dq dp)$
- Initial work $\mathcal{W}^0 = 0$, and **work update**

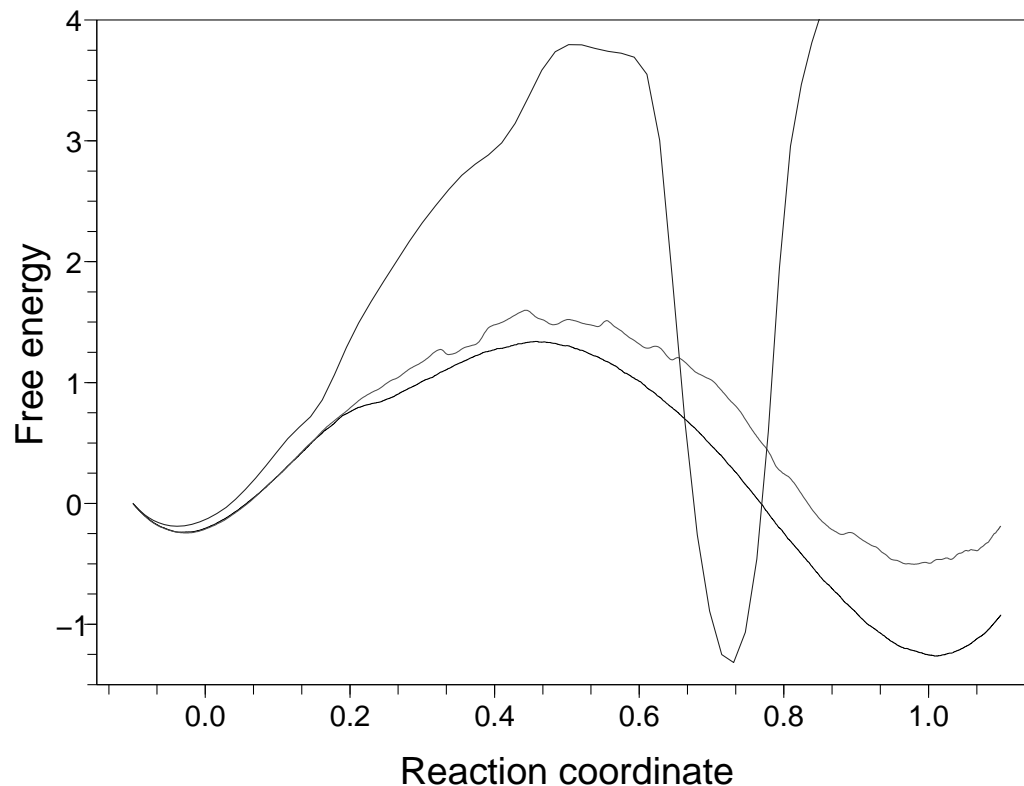
$$\mathcal{W}^{n+1} = \mathcal{W}^n + H(q^{n+1}, p^{n+3/4}) - H(q^n, p^{n+1/4})$$

- **Time-step error free** estimator of the free energy difference:

$$\frac{Z_{z(t_{N_T}), \frac{z(t_{N_T+1}) - z(t_{N_T})}{\Delta t}}}{Z_{z(t_0), \frac{z(t_1) - z(t_0)}{\Delta t}}} = \frac{\mathbb{E} \left(\varphi_{[0, N_T]} (\{q^n, p^n\}_{0 \leq n \leq N_T}) e^{-\beta \mathcal{W}^{N_T}} \right)}{\mathbb{E} \left(\varphi_{[0, N_T]}^r (\{q^{b, n'}, p^{b, n'}\}_{0 \leq n' \leq N_T}) \right)}$$

- **Overdamped limit** $\frac{\Delta t}{4} \gamma = M = \frac{\Delta t}{2} \text{Id}$: no bias due to the finite time-step in the estimator

Application: Solvation effects on conformational changes



Estimated free energy profiles for $T = 1$ with $M = 10^5$ (top curve), $T = 10$ with $M = 10^4$ and $T = 100$ with $M = 10^3$ (smoothest curve).

Same parameters as before, except $\Delta t = 0.01$. Schedule $z(t) = z_{\min} + (z_{\max} - z_{\min}) \frac{t}{T}$ with $z_{\min} = -0.1$ and $z_{\max} = 1.1$.

References

- The main references for this work:

T. LELIÈVRE, M. ROUSSET AND G. STOLTZ, Langevin dynamics with constraints and computation of free energy differences, *preprint* (2010) T. LELIÈVRE, M. ROUSSET AND G. STOLTZ *Free energy computations: A Mathematical Perspective*, Imperial College Press.
- Other recent works on adaptive computation of free energy differences
 - N. CHOPIN, T. LELIÈVRE AND G. STOLTZ, Free energy methods for efficient exploration of mixture posterior densities, *HAL preprint 00460914* (2010)
 - B. DICKSON, F. LEGOLL, T. LELIÈVRE, G. STOLTZ, P. FLEURAT-LESSARD, Free energy calculations: An efficient adaptive biasing potential method, *J. Phys. Chem. B* **114**(17), 5823-5830 (2010)
- Workshop “Simulation of hybrid dynamical systems and applications to molecular dynamics” (IHP, Paris, September 27-30th)