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Computation of transport coefficients in molecular dynamics: methods and numerical analysis

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One World Stochastic Numerics and Inverse Problems, July 2021

- **Linear response for steady-state nonequilibrium dynamics**
 - Equilibrium dynamics and their perturbations
 - Definition of transport coefficients
- **Timestep bias for the computation of transport coefficients¹**
 - Linear response approach
 - Green–Kubo formulas
- **Mathematical analysis of a linearization approach²**
 - Motivation for the estimator of the transport coefficient
 - Numerical analysis (timestep and finite time bias, variance)

¹B. Leimkuhler, Ch. Matthews and G. Stoltz, The computation of averages from equilibrium and nonequilibrium Langevin molecular dynamics, *IMA J. Numer. Anal.* (2016)

²P. Plechac, G. S. and T. Wang, Convergence of the likelihood ratio method for linear response of non-equilibrium stationary states, *arXiv preprint 1910.02479* (2019)

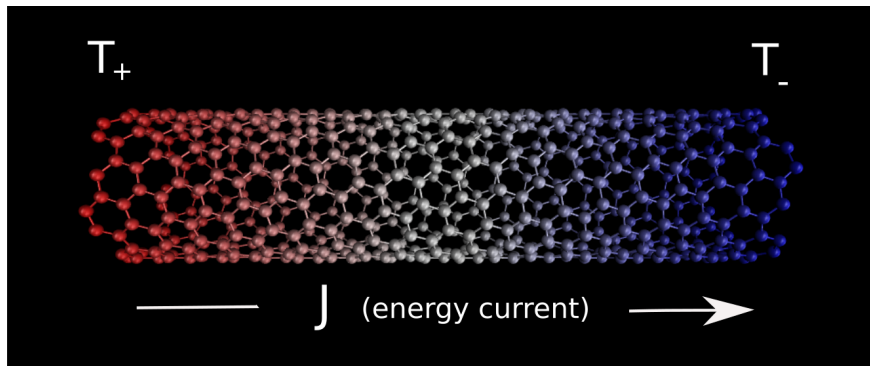
Linear response for steady-state nonequilibrium dynamics

Physical context and motivations

Predicting properties of matter from **atomistic simulations**

Transport coefficients (e.g. thermal conductivity): **quantitative** estimates

$$J = -\kappa \nabla T \quad (\text{Fourier's law})$$



Long computational times to estimate κ (up to several weeks/months)

Reference equilibrium dynamics (1)

Positions $q \in \mathcal{D}$ and momenta $p \in \mathbb{R}^d$, phase-space $\mathcal{E} = \mathcal{D} \times \mathbb{R}^d$

Hamiltonian $H(q, p) = V(q) + \frac{1}{2} p^T M^{-1} p$

Langevin dynamics (for given $\gamma > 0$)

$$\begin{cases} dq_t = M^{-1} p_t dt \\ dp_t = -\nabla V(q_t) dt - \gamma M^{-1} p_t dt + \sqrt{\frac{2\gamma}{\beta}} dW_t \end{cases}$$

Generator $\mathcal{L} = \mathcal{L}_{\text{ham}} + \gamma \mathcal{L}_{\text{FD}}$ with

$$\mathcal{L}_{\text{ham}} = p^T M^{-1} \nabla_q - \nabla V^T \nabla_p, \quad \mathcal{L}_{\text{FD}} = -p^T M^{-1} \nabla_p + \frac{1}{\beta} \Delta_p$$

Unique invariant measure $\mu(dq dp) = Z^{-1} e^{-\beta H(q,p)} dq dp = \nu(dq) \kappa(dp)$

Ergodicity results for Langevin dynamics (1)

Almost-sure convergence³ of **ergodic averages** $\widehat{\varphi}_t = \frac{1}{t} \int_0^t \varphi(q_s, p_s) ds$

Asymptotic variance of ergodic averages (with $\Pi_0\varphi = \varphi - \mathbb{E}_\mu(\varphi)$)

$$\sigma_\varphi^2 = \lim_{t \rightarrow +\infty} t \text{Var} [\widehat{\varphi}_t^2] = 2 \int_{\mathcal{E}} (-\mathcal{L}^{-1} \Pi_0 \varphi) \Pi_0 \varphi d\mu$$

Central limit theorem⁴ when Poisson equation can be solved in $L^2(\mu)$

$$-\mathcal{L}\Phi = \Pi_0\varphi$$

Well-posedness for \mathcal{L} invertible on subsets of $L_0^2(\mu) = \Pi_0 L^2(\mu)$

$$-\mathcal{L}^{-1} = \int_0^{+\infty} e^{t\mathcal{L}} dt$$

³Kliemann, *Ann. Probab.* **15**(2), 690-707 (1987)

⁴Bhattacharya, *Z. Wahrsch. Verw. Gebiete* **60**, 185-201 (1982)

Ergodicity results for Langevin dynamics (2)

Prove **exponential convergence** of the semigroup $e^{t\mathcal{L}}$ on $E \subset L^2_0(\mu)$

- **Lyapunov** techniques⁵ $L^\infty_W(\mathcal{E}) = \left\{ \varphi \text{ measurable, } \sup \left| \frac{\varphi}{W} \right| < +\infty \right\}$
- standard **hypocoercive**⁶ setup $H^1(\mu)$
- $E = L^2(\mu)$ after hypoelliptic regularization⁷ from $H^1(\mu)$
- Direct transfer from $H^1(\mu)$ to $E = L^2(\mu)$ by spectral argument⁸
- Directly⁹ $E = L^2(\mu)$ (recently(recently¹⁰ Poincaré using $\partial_t - \mathcal{L}_{\text{ham}}$)
- **coupling** arguments¹¹
- Direct estimates on the resolvent using Schur complements¹²

Rate of convergence $\min(\gamma, \gamma^{-1})$ in all cases

⁵Wu ('01); Mattingly/Stuart/Higham ('02); Rey-Bellet ('06); Hairer/Mattingly ('11)

⁶Villani (2009) and before Talay (2002), Eckmann/Hairer (2003), Hérau/Nier (2004),...

⁷F. Hérau, *J. Funct. Anal.* (2007)

⁸G. Deligiannidis, D. Paulin and A. Doucet, *Ann. Appl. Probab.* (2020)

⁹Hérau (2006), Dolbeaut/Mouhot/Schmeiser (2009, 2015)

¹⁰Armstrong/Mourrat (2019), Cao/Lu/Wang (2019)

¹¹A. Eberle, A. Guillin and R. Zimmer, *Ann. Probab.* (2019)

¹²E. Bernard, M. Fathi, A. Levitt, G. Stoltz, *arXiv preprint* **2003.00726**

Definition of transport coefficients (1)

Linear response of **nonequilibrium dynamics**

Example: $\mathcal{D} = (L\mathbb{T})^d$, **non-gradient** force $F \in \mathbb{R}^{3N}$

$$\begin{cases} dq_t = M^{-1} p_t dt \\ dp_t = \left(-\nabla V(q_t) + \eta F \right) dt - \gamma M^{-1} p_t dt + \sqrt{\frac{2\gamma}{\beta}} dW_t \end{cases}$$

Existence and uniqueness of invariant measure (Lyapunov techniques)

Generator $\mathcal{L} + \eta \tilde{\mathcal{L}}$, **invariant measure** $f_\eta \mu$ with $(\mathcal{L}^* + \eta \tilde{\mathcal{L}}^*) f_\eta = 0$

$$f_\eta = \left(\text{Id} + \eta (\tilde{\mathcal{L}} \Pi_0 \mathcal{L}^{-1} \Pi_0)^* \right)^{-1} \mathbf{1} = \left(1 + \sum_{n=1}^{+\infty} (-\eta)^n \left[(\tilde{\mathcal{L}} \Pi_0 \mathcal{L}^{-1} \Pi_0)^* \right]^n \right) \mathbf{1}$$

where adjoints are taken on $L^2(\mu)$ (so that $\mathcal{L}^* = -\mathcal{L}_{\text{ham}} + \gamma \mathcal{L}_{\text{FD}}$)

Definition of transport coefficients (2)

Response property $R \in L_0^2(\mu)$, conjugated response $S = \tilde{\mathcal{L}}^* \mathbf{1}$:

$$\alpha = \lim_{\eta \rightarrow 0} \frac{\mathbb{E}_\eta(R)}{\eta} = - \int_{\mathcal{E}} [\mathcal{L}^{-1} R] [\tilde{\mathcal{L}}^* \mathbf{1}] d\mu = \int_0^{+\infty} \mathbb{E}_0 \left(R(q_t, p_t) S(q_0, p_0) \right) dt$$

In practice:

- Identify the **response** function
- Construct a physically meaningful **perturbation**
- Obtain the transport coefficient α (thermal cond., shear viscosity,...)
- Non physical forcings giving same transport coefficient (“synthetic”)

For the previous example, definition of **mobility** with $R(q, p) = F^T M^{-1} p$

$$\lim_{\eta \rightarrow 0} \frac{\mathbb{E}_\eta (F^T M^{-1} p)}{\eta} = \beta F^T D F$$

with **effective diffusion** $D = \int_0^{+\infty} \mathbb{E}_0 \left((M^{-1} p_t) \otimes (M^{-1} p_0) \right) dt$

Timestep bias for the computation of transport coefficients

Practical computation of average properties (1)

Numerical scheme: **Markov chain** characterized by evolution operator

$$P_{\Delta t} \varphi(q, p) = \mathbb{E} \left(\varphi(q^{n+1}, p^{n+1}) \mid (q^n, p^n) = (q, p) \right)$$

Discretization of the Langevin dynamics: **splitting** strategy

$$A = M^{-1} p \cdot \nabla_q, \quad B = -\nabla V(q) \cdot \nabla_p, \quad C = -M^{-1} p \cdot \nabla_p + \frac{1}{\beta} \Delta_p$$

First order splitting schemes: $P_{\Delta t}^{ZYX} = e^{\Delta t Z} e^{\Delta t Y} e^{\Delta t X} \simeq e^{\Delta t \mathcal{L}}$

Example: $P_{\Delta t}^{B,A,\gamma C}$ corresponds to (with $\alpha_{\Delta t} = \exp(-\gamma M^{-1} \Delta t)$)

$$\begin{cases} \tilde{p}^{n+1} = p^n - \Delta t \nabla V(q^n), \\ q^{n+1} = q^n + \Delta t M^{-1} \tilde{p}^{n+1}, \\ p^{n+1} = \alpha_{\Delta t} \tilde{p}^{n+1} + \sqrt{\frac{1 - \alpha_{\Delta t}^2}{\beta}} M G^n, \end{cases} \quad (1)$$

where G^n are i.i.d. standard Gaussian random variables

Practical computation of average properties (2)

Second order splitting $P_{\Delta t}^{ZYXYZ} = e^{\Delta t Z/2} e^{\Delta t Y/2} e^{\Delta t X} e^{\Delta t Y/2} e^{\Delta t Z/2}$

Example: $P_{\Delta t}^{\gamma C, B, A, B, \gamma C}$ (Verlet in the middle)

$$\left\{ \begin{array}{l} \tilde{p}^{n+1/2} = \alpha_{\Delta t/2} p^n + \sqrt{\frac{1 - \alpha_{\Delta t}}{\beta}} M G^n, \\ p^{n+1/2} = \tilde{p}^{n+1/2} - \frac{\Delta t}{2} \nabla V(q^n), \\ q^{n+1} = q^n + \Delta t M^{-1} p^{n+1/2}, \\ \tilde{p}^{n+1} = p^{n+1/2} - \frac{\Delta t}{2} \nabla V(q^{n+1}), \\ p^{n+1} = \alpha_{\Delta t/2} \tilde{p}^{n+1} + \sqrt{\frac{1 - \alpha_{\Delta t}}{\beta}} M G^{n+1/2}, \end{array} \right.$$

Other category: **Geometric Langevin**¹³ algorithms, e.g. $P_{\Delta t}^{\gamma C, A, B, A}$

¹³N. Bou-Rabee and H. Owhadi, *SIAM J. Numer. Anal.* (2010)

Error estimates on average properties

Trajectory ergodicity of splitting schemes (\mathcal{D} bounded):

$$\widehat{\Phi}^{N_{\text{iter}}} = \frac{1}{N_{\text{iter}}} \sum_{n=1}^{N_{\text{iter}}} \varphi(q^n, p^n) \xrightarrow{N_{\text{iter}} \rightarrow +\infty} \int \varphi(q, p) d\mu_{\gamma, \Delta t}(q, p) \quad \text{a.s.}$$

Numerical analysis: statistical errors vs. systematic errors (**bias**):

- Central Limit Theorem and asymptotic variance: from analysis for Green–Kubo formulas,¹⁴

$$\text{Var} \left(\widehat{\Phi}^{N_{\text{iter}}} \right) = \frac{2}{\Delta t} \int_{\mathcal{E}} (-\mathcal{L}^{-1} \Pi_0 \varphi) \Pi_0 \varphi d\mu + O(1)$$

- Finite time integration error¹⁵
- **Timestep discretization** error¹⁶

¹⁴Leimkuhler/Matthews/Stoltz, *IMA J. Numer. Anal.* (2016); Lelièvre/Stoltz, *Acta Numerica* (2016); Duncan/Zygalakis/Pavliotis, *arXiv preprint 1701.04247*

¹⁵J.C. Mattingly, A.M. Stuart and M.V. Tretyakov, *SIAM J. Numer. Anal.* (2010)

¹⁶Talay/Tubaro, *Stoch. Proc. Appl.* (1990); Talay, *Stoch. Proc. Appl.* (2002); Debussche/Faou, *SIAM J. Numer. Anal.* (2012); Abdulle/Vilmart/Zygalakis (2015)

Timestep discretization error (1)

Weak order α for the splitting scheme ($P_{\Delta t} = e^{\Delta t \mathcal{L}} + O(\Delta t^{\alpha+1})$)

$$\int_{\mathcal{E}} \varphi d\mu_{\gamma, \Delta t} = \int_{\mathcal{E}} \varphi d\mu + \Delta t^{\alpha} \int_{\mathcal{E}} \varphi f_{\alpha, \gamma} d\mu + O(\Delta t^{\alpha+1})$$

with correction function solution of $\mathcal{L}^* f_{\alpha, \gamma} = g_{\gamma}$

Example: $g_{\gamma} = -\frac{1}{2} S_1^* \mathbf{1}$ with $S_1 = [C, A + B] + [B, A]$ for $P_{\Delta t}^{\gamma C, B, A}$

Use [BCH formula](#) to write $P_{\Delta t}^{\gamma C, B, A} = \text{Id} + \Delta t \mathcal{L} + \frac{\Delta t^2}{2} (\mathcal{L}^2 + S_1) + \Delta t^3 R_{1, \Delta t}$

Proof: approximation of characterization of invariance of $\mu_{\gamma, \Delta t}$

$$\int_{\mathcal{E}} \left[\left(\frac{\text{Id} - P_{\Delta t}}{\Delta t} \right) \phi \right] d\mu_{\gamma, \Delta t} = 0$$

Timestep discretization error (2)

Correction function $f_{1,\gamma}$ chosen so that

$$\int_{\mathcal{E}} \left[\left(\frac{\text{Id} - P_{\Delta t}^{\gamma C, B, A}}{\Delta t} \right) \phi \right] (1 + \Delta t f_{1,\gamma}) d\mu = O(\Delta t^2)$$

This requirement can be rewritten as

$$0 = \int_{\mathcal{E}} \left(\frac{1}{2} S_1 \phi + (\mathcal{L}\phi) f_{1,\gamma} \right) d\mu = \int_{\mathcal{E}} \varphi \left[\frac{1}{2} S_1^* \mathbf{1} + \mathcal{L}^* f_{1,\gamma} \right] d\mu,$$

Replace ϕ by $\left(\frac{\text{Id} - P_{\Delta t}^{\gamma C, B, A}}{\Delta t} \right)^{-1} \varphi$? No control on the **derivatives**...

Rely on the “nice” properties of the continuous dynamics, *i.e.* functional estimates¹⁷ on \mathcal{L}^{-1} to use pseudo-inverses

$$Q_{1,\Delta t} = -\mathcal{L}^{-1} + \frac{\Delta t}{2} (\text{Id} + \mathcal{L}^{-1} S_1 \mathcal{L}^{-1})$$

¹⁷D. Talay, Stoch. Proc. Appl. (2002); M. Kopec (2015)

Error estimates on the Green-Kubo formula (1)

Assume $\frac{P_{\Delta t} - \text{Id}}{\Delta t} = \mathcal{L} + \Delta t S_1 + \dots + \Delta t^{\alpha-1} S_{\alpha-1} + \Delta t^\alpha \tilde{R}_{\alpha, \Delta t}$ and

$$\|P_{\Delta t}^n\|_{\mathcal{B}(B_{W, \Delta t}^\infty)} \leq C e^{-\kappa n \Delta t}, \quad \int_{\mathcal{E}} \phi d\mu_{\Delta t} = \int_{\mathcal{E}} \phi d\mu + \Delta t^\alpha r_{\phi, \Delta t}$$

Uniform-in-time convergence follows from Lyapunov condition (with W) and **uniform minorization**¹⁸

$$P_{\Delta t}^{\lceil T/\Delta t \rceil}(X_0, dX) \geq a m(dX)$$

• Issues with Green-Kubo formula:

- Truncature of time (exponential convergence of $e^{t\mathcal{L}}$)
- The **statistical error** for correlations increases a lot with time lag
- **Timestep bias and quadrature formula**

¹⁸A. Durmus, A. Enfroy, E. Moulines, G. Stoltz (2021)

Error estimates on the Green-Kubo formula (2)

Formulated for generic stochastic dynamics

For R, S with average 0 w.r.t. μ ,

$$\int_0^{+\infty} \mathbb{E} \left(R(X_t) S(X_0) \right) dt = \Delta t \sum_{n=0}^{+\infty} \mathbb{E}_{\Delta t} \left(\tilde{R}_{\Delta t} (X^n) S(X^0) \right) + O(\Delta t^\alpha)$$

with $\tilde{R}_{\Delta t} = \left(\text{Id} + \Delta t S_1 \mathcal{L}^{-1} + \dots + \Delta t^{\alpha-1} S_{\alpha-1} \mathcal{L}^{-1} \right) R - \mu_{\Delta t}(\dots)$

Reduces to **trapezoidal** rule for **second** order schemes

B. Leimkuhler, Ch. Matthews and G. Stoltz, The computation of averages from equilibrium and nonequilibrium Langevin molecular dynamics, *IMA J. Numer. Anal.* **36**(1), 13-79 (2016)

T. Lelièvre and G. Stoltz, Partial differential equations and stochastic methods in molecular dynamics, *Acta Numerica* **25** (2016)

Error estimates on linear response (1)

Splitting schemes obtained by replacing B with $B_\eta = B + \eta F \cdot \nabla_p$

For instance, $P_{\Delta t}^{A, B + \eta \tilde{\mathcal{L}}, \gamma C}$ for

$$\begin{cases} q^{n+1} = q^n + \Delta t p^n, \\ \tilde{p}^{n+1} = p^n + \Delta t \left(-\nabla V(q^{n+1}) + \eta F \right), \\ p^{n+1} = \alpha_{\Delta t} \tilde{p}^{n+1} + \sqrt{\frac{1 - \alpha_{\Delta t}^2}{\beta}} G^n \end{cases}$$

Issues with linear response methods: $\alpha \simeq \frac{1}{\eta N_{\text{iter}}} \sum_{n=1}^{N_{\text{iter}}} R(q^n, p^n)$

- Statistical error with **asymptotic variance** $O(\eta^{-2})$
- Bias due to $\eta \neq 0$
- Bias from finite integration time
- **Timestep discretization bias**

Error estimates on the mobility (2)

Invariant measure $\mu_{\gamma,\eta,\Delta t}$ of the numerical scheme

$$\int_{\mathcal{E}} R d\mu_{\gamma,\eta,\Delta t} = \int_{\mathcal{E}} R \left(1 + \eta f_{0,1,\gamma} + \Delta t^\alpha f_{\alpha,0,\gamma} + \eta \Delta t^\alpha f_{\alpha,1,\gamma} \right) d\mu + r_{\varphi,\gamma,\eta,\Delta t},$$

where the remainder is compatible with linear response

$$|r_{\varphi,\gamma,\eta,\Delta t}| \leq K(\eta^2 + \Delta t^{\alpha+1}), \quad |r_{\varphi,\gamma,\eta,\Delta t} - r_{\varphi,\gamma,0,\Delta t}| \leq K\eta(\eta + \Delta t^{\alpha+1})$$

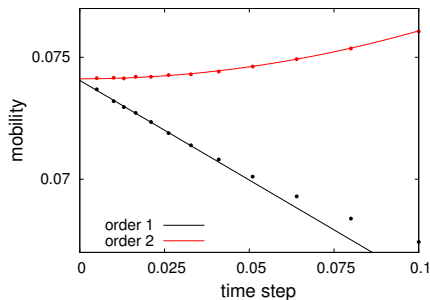
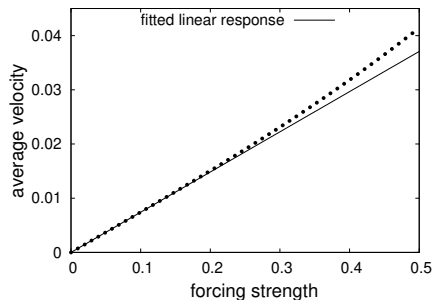
Corollary: error estimates on the **numerically computed mobility**

$$\begin{aligned} \nu_{F,\gamma,\Delta t} &= \lim_{\eta \rightarrow 0} \frac{1}{\eta} \left(\int_{\mathcal{E}} F^T M^{-1} p \mu_{\gamma,\eta,\Delta t}(dq dp) - \int_{\mathcal{E}} F^T M^{-1} p \mu_{\gamma,0,\Delta t}(dq dp) \right) \\ &= \nu_{F,\gamma} + \Delta t^\alpha \int_{\mathcal{E}} F^T M^{-1} p f_{\alpha,1,\gamma} d\mu + \Delta t^{\alpha+1} r_{\gamma,\Delta t} \end{aligned}$$

Results in the **overdamped** limit

B. Leimkuhler, Ch. Matthews and G. Stoltz, The computation of averages from equilibrium and nonequilibrium Langevin molecular dynamics, *IMA J. Numer. Anal.* **36**(1), 13-79 (2016)

Numerical results



Left: Linear response of the average velocity as a function of η for the scheme associated with $P_{\Delta t}^{\gamma C, B_\eta, A, B_\eta, \gamma C}$ and $\Delta t = 0.01, \gamma = 1$.

Right: Scaling of the mobility $\nu_{F, \gamma, \Delta t}$ for the first order scheme $P_{\Delta t}^{A, B_\eta, \gamma C}$ and the second order scheme $P_{\Delta t}^{\gamma C, B_\eta, A, B_\eta, \gamma C}$.

Mathematical analysis of a linearization approach

Sensitivity estimator: motivation

General non-degenerate stochastic dynamics on $\mathcal{D} = \mathbb{T}^d$

- **Reference dynamics** $dX_t^0 = b(X_t^0) dt + \sigma(X_t^0) dW_t$
- **Perturbed dynamics** $dX_t^\eta = (b(X_t^\eta) + \eta F(X_t^\eta)) dt + \sigma(X_t^\eta) dW_t$
- Assume $\sigma\sigma^T$ positive definite \rightarrow unique invariant measure ν_η

Estimator of the linear response

$$\alpha = \lim_{\eta \rightarrow 0} \frac{\nu_\eta(R) - \nu_0(R)}{\eta} = \lim_{t \rightarrow \infty} \mathbb{E}_0 \left\{ \left(\frac{1}{t} \int_0^t (R(X_s^0) - \nu_0(R)) ds \right) Z_t \right\}$$

with $Z_t = \int_0^t U(X_s^0)^T dW_s$ and $\sigma U = F$

Motivation: Girsanov theorem, linearization, and longtime limit (formal)

$$\mathbb{E}_\eta \left[\frac{1}{t} \int_0^t R(X_s^\eta) ds \right] = \mathbb{E}_0 \left[\left(\frac{1}{t} \int_0^t R(X_s^0) ds \right) \exp \left(\eta \int_0^t U(X_s^0)^T dW_s - \frac{\eta^2}{2} \int_0^t |U(X_s^0)|^2 ds \right) \right]$$

Sensitivity estimator: proof

Proof of consistency: Generator $\mathcal{L} + \eta\tilde{\mathcal{L}}$, Poisson equation $-\mathcal{L}\hat{R} = \Pi_0 R$
(well posed)

Rewrite the time integral as a martingale, up to remainder terms

$$\int_0^t \Pi_0 R(X_s^0) ds = M_t + \hat{R}(X_0^0) - \hat{R}(X_t^0), \quad M_t = \int_0^t \nabla \hat{R}(X_s)^T \sigma(X_s^0) dW_s$$

and use Itô isometry to write $\frac{1}{t} \mathbb{E}(M_t Z_t)$ as

$$\frac{1}{t} \int_0^t \mathbb{E} \left(U(X_s^0)^T \sigma(X_s^0)^T \nabla \hat{R}(X_s^0) \right) ds \xrightarrow[t \rightarrow +\infty]{} \int_{\mathcal{D}} F^T \nabla \hat{R} d\nu_0 = \alpha$$

Variance uniformly bounded in time: by similar manipulations,

$$\forall t > 0, \quad \text{Var} \left\{ \left(\frac{1}{t} \int_0^t (R(X_s^0) - \nu_0(R)) ds \right) Z_t \right\} \leq C$$

Sensitivity estimator: discretization

Euler–Maruyama scheme $X^{n+1} = X^n + \Delta t b(X^n) + \sqrt{\Delta t} \sigma(X^n) G^n$

Assume again **uniform-in-time minorization** condition $P_{\Delta t}^{\lceil T/\Delta t \rceil} \geq a m(dx)$

Discrete sensinty estimator (slightly idealized)

$$\mathcal{M}_{\Delta t, N_{\text{iter}}}^{[1]}(R) = \frac{1}{N_{\text{iter}}} \sum_{n=0}^{N_{\text{iter}}-1} (R(X^n) - \mathbb{E}_{\Delta t}(R)) Z^{N_{\text{iter}}}$$

with $Z^{N_{\text{iter}}} = \sum_{n=0}^{N_{\text{iter}}-1} (\sigma(X^n)^{-1} F(X^n))^T G^n$

$$\left| \mathbb{E}_{\Delta t} \left\{ \mathcal{M}_{\Delta t, N_{\text{iter}}}^{[1]}(R) \right\} - \alpha \right| \leq C \left(\Delta t + \frac{1}{\sqrt{N_{\text{iter}} \Delta t}} \right)$$
$$\text{Var}_{\Delta t} \left\{ \mathcal{M}_{\Delta t, N_{\text{iter}}}^{[1]}(R) \right\} \leq C_1 + C_2 \left(\Delta t + \frac{1}{N_{\text{iter}} \Delta t} \right)$$

Finite-time bias $O(\text{time}^{-1/2})$ (time^{-1} for standard time averages)

Discretized sensitivity estimator: proofs

Elements of proofs: $\frac{\text{Id} - P_{\Delta t}}{\Delta t} \widehat{R}_{\Delta t} = \Pi_{\Delta t} R$ with $\Pi_{\Delta t} \varphi = \varphi - \mathbb{E}_{\Delta t}(\varphi)$

Manipulations at the discrete level mimicking the ones for SDEs:

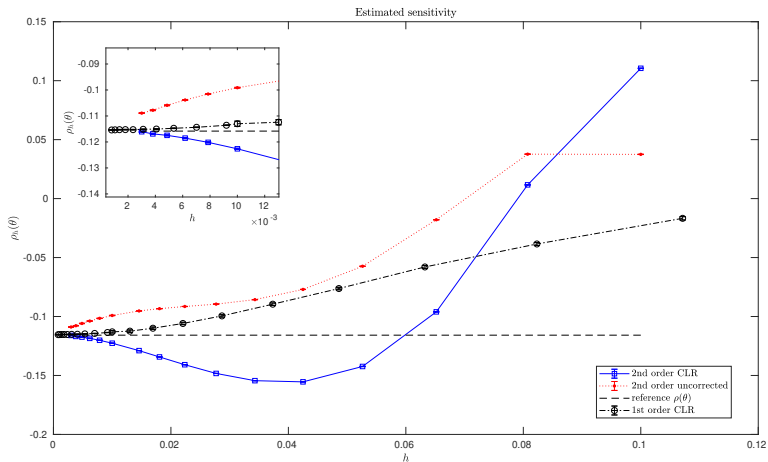
$$\begin{aligned} \mathbb{E}_{\Delta t} \left\{ \mathcal{M}_{\Delta t, N_{\text{iter}}}^{[1]}(R) \right\} &= \frac{1}{N_{\text{iter}} \Delta t} \sum_{n=0}^{N_{\text{iter}}-1} \mathbb{E}_{\Delta t} \left\{ (\text{Id} - P_{\Delta t}) \widehat{R}_{\Delta t}(X^n) Z^{N_{\text{iter}}} \right\}, \\ &= \frac{1}{N_{\text{iter}} \Delta t} \sum_{n=0}^{N_{\text{iter}}-1} \mathbb{E}_{\Delta t} \left\{ M_{\Delta t}^n (Z^{n+1} - Z^n) \right\} + \mathcal{O} \left(\Delta t^{3/2}, \frac{1}{\sqrt{N_{\text{iter}} \Delta t}} \right) \end{aligned}$$

with $M_{\Delta t}^n = \widehat{R}_{\Delta t}(X^{n+1}) - (P_{\Delta t} \widehat{R}_{\Delta t})(X^n) \simeq \nabla \widehat{R}_{\Delta t}(X^n)^T \sigma(X^n) G^n$ and discrete Itô isometry

BUT $\widehat{R}_{\Delta t}$ is a priori not smooth (use pseudo inverses and control remainders/approximations uniformly everywhere...)

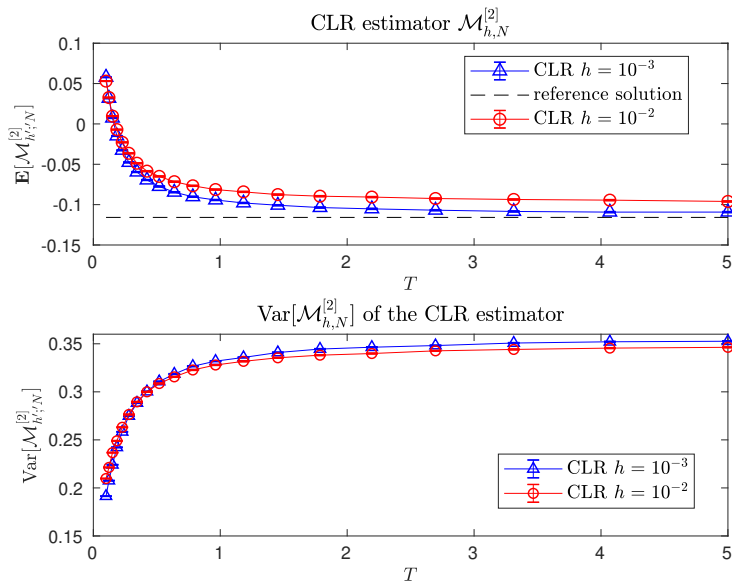
Second order schemes: bias $\mathcal{O}(\Delta t^2)$ with “martingale product” approach

Discretized sensitivity estimator: numerical results (1)



Estimation of α for various values of the timestep Δt . Reference value computed by numerical quadrature (one-dimensional example)

Discretized sensitivity estimator: numerical results (2)



Extensions and future work

Several year workplan!

- **Sensitivity estimator** (with P. Plechac and T. Wang, “short term”)
 - **Degenerate noise**: Langevin dynamics, thermal transport in chains
 - Compare performance with Green–Kubo type methods
- **Alternative approaches**, possibly with some **blending**
 - Rely on tangent dynamics¹⁹
 - Resort to efficient coupling methods such as sticky coupling²⁰
 - Optimize synthetic forcings²¹

¹⁹R. Assaraf, B. Jourdain, T. Lelièvre, and R. Roux, Computation of sensitivities for the invariant measure of a parameter dependent diffusion, *Stoch. Partial Differ. Equ. Anal. Comput.* (2018)

²⁰Eberle/Zimmer (2019); Durmus/Eberle/Enfroy/Guillin/Monmarché (2021)

²¹D. J. Evans and G. P. Morriss, *Statistical Mechanics of Nonequilibrium Liquids* (Cambridge University Press, 2008)