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## Fake Brownian motion and calibration of a Regime Switching Local Volatility model

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#### Plan

#### 1 Processes matching given marginals

- Motivation
- Simulation of calibrated LSV models and theoretical results

#### 2 A new fake Brownian motion

- The studied problem
- Main result
- Ideas of proof

#### Existence of Calibrated RSLV models

- The calibrated RSLV model
- Main result

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## Outline

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Motivation

#### Fake Brownian motion

- A fake Brownian motion (X<sub>t</sub>)<sub>t≥0</sub> is a continuous martingale that has the same marginal distributions as the Brownian motion (W<sub>t</sub>)<sub>t≥0</sub> but is not a Brownian motion.
- Examples by Albin (2007) and Oleszkiewicz (2008)
- Hobson (2009): fake exponential Brownian motion and more general martingale diffusions.
- Stochastic processes matching given marginals is a question arising in mathematical finance.

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#### Motivation

## Trying to match marginals

- The market gives the prices of European Calls C(T, K) for T, K > 0 (idealized situation; in practice only  $(C(T_i, K_i))_{1 \le i \le I})$ .
- A model  $(S_t)_{t>0}$  is calibrated to European options if

$$\forall T, K \geq 0, \ C(T, K) = \mathbb{E}\left[e^{-rT}\left(S_T - K\right)^+\right].$$

- By Breeden and Litzenberger (1978), {prices of European Call options for all *T*, *K* > 0} ⇐ {marginal distributions of (*S<sub>t</sub>*)<sub>t>0</sub>}.
- Dupire Local Volatility model (1992), matching market marginals:

$$dS_{t} = rS_{t}dt + \sigma_{Dup}(t, S_{t})S_{t}dW_{t}$$
  
$$\sigma_{Dup}(T, K) = \sqrt{2\frac{\partial_{T}C(T, K) + rK\partial_{K}C(T, K)}{K^{2}\partial_{KK}^{2}C(T, K)}}$$

Processes matching given marginals	A new <i>fake</i> Brownian motion	Existence of Calibrated RSLV models
Motivation		
LSV models		

- Motivation: get processes with richer dynamics (e.g. take into account volatility risk) and satisfying marginal constraints.
- Alexander and Nogueira (2004) and Piterbarg (2006): Local and Stochastic Volatility (LSV) model

$$dS_t = rS_t + f(Y_t)\sigma(t, S_t)S_t dW_t$$

• "Adding uncertainty" to LV models by a random multiplicative factor  $f(Y_t)$ ,  $(Y_t)_{t>0}$  is a stochastic process.

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A new *fake* Brownian motion

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Motivation

#### Calibration of LSV Models

• By Gyongy's theorem (1988), the LSV model is calibrated to  $C(T, K), \forall T, K > 0$  if

$$\mathbb{E}\left[f^{2}(Y_{t})|S_{t}\right]\sigma^{2}(t,S_{t})=\sigma^{2}_{Dup}(t,S_{t})$$

$$\sigma(t, x) = \frac{\sigma_{Dup}(t, x)}{\sqrt{\mathbb{E}\left[f^2(Y_t)|S_t = x\right]}}$$

• The obtained SDE is nonlinear in the sense of McKean:

$$dS_t = rS_t dt + \frac{f(Y_t)}{\sqrt{\mathbb{E}[f^2(Y_t)|S_t]}} \sigma_{Dup}(t, S_t) S_t dW_t.$$

Processes matching given marginals ○○○○●○	A new <i>fake</i> Brownian motion	Existence of Calibrated RSLV models		
Simulation of calibrated LSV models and theoretical results				
Simulation results				

- Madan and Qian, Ren (2007): solve numerically the associated Fokker-Planck PDE, and get the joint-law of (S<sub>t</sub>, Y<sub>t</sub>).
- Guyon and Henry-Labordère (2011): efficient calibration procedure based on kernel approximation of the conditional expectation.

Subsequent extension to stochastic interest rates, stochastic dividends, multidimensional local correlation models,...

• However, calibration errors seem to appear when the range of f(Y) is too large.

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Simulation of calibrated LSV models and theoretical results

#### Theoretical results

- Abergel and Tachet (2010): perturbation of the constant f case (Dupire) → existence for the restriction to a compact spatial domain of the associated Fokker-Planck equation when sup f inf f small.
- Global existence and uniquess to LSV models remain on open problem.

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## Outline

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The studied problem

#### A simpler SDE

• Let Y be a r.v. with values in  $\mathcal{Y} := \{y_1, ..., y_d\}$ .

• We assume 
$$\forall i \in \{1, ..., d\}$$
,  $\alpha_i = \mathbb{P}(Y = y_i) > 0$ .

• We study the SDE (FBM), with f > 0:

$$dX_t = \frac{f(Y)}{\sqrt{\mathbb{E}\left[f^2(Y)|X_t\right]}}dW_t$$
  
$$X_0 \sim \mu.$$

•  $X_0$ , Y,  $(W_t)_{t>0}$  are independent.

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The studied problem

## Fake Brownian Motion

#### Lemma

If the positive function f is not constant on  $\mathcal{Y},$  then any solution to the SDE

$$dX_t = \frac{f(Y)}{\sqrt{\mathbb{E}\left[f^2(Y)|X_t\right]}}dW_t, X_0 = 0$$

with Y and  $(W_t)_{t\geq 0}$  indep. is a fake Brownian motion.

If  $(X_t)_{t\geq 0}$  is a Brownian motion then a.s.  $\forall t \geq 0, < X >_t = t$  i.e. ds a.e.  $\frac{f^2(Y)}{\mathbb{E}[f^2(Y)|X_s]} = 1 = \frac{f(Y)}{\sqrt{\mathbb{E}[f^2(Y)|X_s]}}$  so that a.s.  $\forall t \geq 0,$   $X_t = W_t.$ Therefore  $X_t \perp Y$ ,  $\mathbb{E}[f^2(Y)|X_t] = \mathbb{E}[f^2(Y)]$  and  $f^2(Y) = \mathbb{E}[f^2(Y)]$  is constant.

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Main result

#### Existence to SDE (FBM) and fake Brownian motion

We define for 
$$i \in \{1, ..., d\}$$
,  $\lambda_i := f^2(y_i)$ ,  
 $\lambda_{\min} := \min_i \lambda_i$ ,  $\lambda_{\max} := \max_i \lambda_i$ .

#### Theorem

Under Condition (C):

$$(C) : \sum_{i} \left( \frac{\lambda_{i}}{\lambda_{max}} + \frac{\lambda_{max}}{\lambda_{i}} \right) \vee \sum_{i} \left( \frac{\lambda_{i}}{\lambda_{min}} + \frac{\lambda_{min}}{\lambda_{i}} \right) < 2d + 4.$$

there exists a weak solution to the SDE (FBM) on [0, T].

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Main result

#### The associated Fokker Planck system

- For  $i \in \{1, ..., d\}$ , define  $p_i$  s.t., for  $\phi \ge 0$  and measurable,  $\mathbb{E}\left[\phi(X_t) \mathbf{1}_{\{Y=y_i\}}\right] = \int_{\mathbb{R}} \phi(x) p_i(t, x) dx.$
- The associated Fokker-Planck system is:

$$\forall i \in \{1, ..., d\}, \partial_t p_i = \frac{1}{2} \partial_{xx}^2 \left( \frac{\sum_j p_j}{\sum_j \lambda_j p_j} \lambda_i p_i \right)$$
$$p_i(0) = \alpha_i \mu$$

•  $\sum_{i} p_{j}$  is solution to the heat equation.

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Ideas of proof

#### Rewriting into divergence form

The system can be rewritten in divergence form:

$$\begin{pmatrix} \partial_t p_1 \\ \cdot \\ \cdot \\ \partial_t p_d \end{pmatrix} = \frac{1}{2} \partial_x \begin{pmatrix} (I_d + M(p)) \begin{pmatrix} \partial_x p_1 \\ \cdot \\ \cdot \\ \partial_x p_d \end{pmatrix} \end{pmatrix}$$

$$M_{ii}(p) = \frac{\sum_{j \neq i} \lambda_j p_j \sum_j (\lambda_i - \lambda_j) p_j}{\left(\sum_j \lambda_j p_j\right)^2},$$
  
$$M_{ik}(p) = \frac{\lambda_i p_i \sum_j (\lambda_j - \lambda_k) p_j}{\left(\sum_j \lambda_j p_j\right)^2}, i \neq k.$$

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Ideas of proof

#### Computing standard energy estimates (S.E.E)

• Multiply the system by  $(p_1, ..., p_d)$ , and integrate in x:

$$\frac{1}{2}\partial_t \left( \int_{\mathbb{R}} \sum_{i=1}^d p_i^2 dx \right) = -\frac{1}{2} \int_{\mathbb{R}} \left( \partial_x p_1, \dots, \partial_x p_d \right) \left( I_d + M(p) \right) \begin{pmatrix} \partial_x p_1 \\ \vdots \\ \partial_x p_d \end{pmatrix} dx.$$

- Goal : S.E.E. in  $L^{2}([0, T], H^{1}(\mathbb{R})) \cap L^{\infty}([0, T], L^{2}(\mathbb{R})).$
- We want (coercivity property): for  $(\mathbb{R}^d_+)^* = \mathbb{R}^d_+ \setminus \{(0, ..., 0)\}$  $\exists \epsilon > 0 \ s.t. \ \forall \rho \in (\mathbb{R}^d_+)^*, \ \forall y \in \mathbb{R}^d, \ y^* M(\rho) y \ge (\epsilon - 1) \ |y|^2.$

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#### Ideas of proof

 $M(\rho)$  as a convex combination

• 
$$\overline{\lambda} := \frac{\sum_{j} \lambda_{j} \rho_{j}}{\sum_{j} \rho_{j}}, w_{j} := \frac{\lambda_{j} \rho_{j}}{\sum_{k} \lambda_{k} \rho_{k}}, \sum_{j=1}^{d} w_{j} = 1.$$
  
•  $M_{ii}(\rho) = \sum_{j \neq i} w_{j} \left(\frac{\lambda_{i}}{\lambda} - 1\right), \text{ and if } j \neq k, M_{jk}(\rho) = w_{j} \left(1 - \frac{\lambda_{k}}{\lambda}\right).$ 

• Then  $M(\rho) = \sum_{j=1}^{d} w_j M_j(\lambda)$ , where

$$M_{j}(\overline{\lambda}) := \begin{pmatrix} \left(\frac{\lambda_{1}}{\overline{\lambda}} - 1\right) & & & & \\ & \cdot & & & \\ & & \left(\frac{\lambda_{j-1}}{\overline{\lambda}} - 1\right) & & \\ \left(1 - \frac{\lambda_{1}}{\overline{\lambda}}\right) & \cdot & \left(1 - \frac{\lambda_{j-1}}{\overline{\lambda}}\right) & 0 & \left(1 - \frac{\lambda_{j+1}}{\overline{\lambda}}\right) & \cdot & \left(1 - \frac{\lambda_{d}}{\overline{\lambda}}\right) \\ & & & \left(\frac{\lambda_{j+1}}{\overline{\lambda}} - 1\right) & & \\ & & & & \cdot & \\ & & & & \left(\frac{\lambda_{d}}{\overline{\lambda}} - 1\right) \end{pmatrix} \leftarrow \operatorname{row} j.$$

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Ideas of proof

# How to have $\forall \rho \in (\mathbb{R}^d_+)^*$ , $\forall y \in \mathbb{R}^d$ , $y^*M(\rho)y \ge -|y|^2$ ?

Sufficient condition

$$\forall j, \forall \overline{\lambda} \in [\lambda_{\min}, \lambda_{\max}], \ y^* M_j(\overline{\lambda}) y \ge -|y|^2$$

• 
$$a_i := \left(\frac{\lambda_i}{\overline{\lambda}} - 1\right) > -1$$
  
•  $y^* M_i(\overline{\lambda}) y = \sum_{i \neq i} a_i \left(y_i^2 - y_i y_i\right)$ 

•  $y^* M_j(\overline{\lambda}) y = \sum_{i \neq j} a_i (y_i^2 - y_i y_j)$ • Young's inequality :  $-a_i y_i y_j \ge -(1 + a_i) y_i^2 - \frac{a_i^2}{4(1 + a_i)} y_j^2$ 

• 
$$y^* M_j(\overline{\lambda}) y \ge -\left(\sum_{i \neq j} y_i^2\right) - \left(\sum_{i \neq j} \frac{\left(\lambda_i - \overline{\lambda}\right)^2}{4\lambda_i \overline{\lambda}}\right) y_j^2$$

Sufficient condition:

$$\max_{j} \max_{\overline{\lambda} \in [\lambda_{\min}, \lambda_{\max}]} \left( \sum_{i \neq j} \frac{\left(\lambda_i - \overline{\lambda}\right)^2}{4\lambda_i \overline{\lambda}} \right) \leq 1.$$

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Ideas of proof

## How to have $\forall \rho \in (\mathbb{R}^d_+)^*$ , $\forall y \in \mathbb{R}^d$ , $y^*M(\rho)y \ge -|y|^2$ ?

• Equivalent formulation:

$$\max_{j} \max_{\overline{\lambda} \in [\lambda_{\min}, \lambda_{\max}]} \sum_{i \neq j} \left( \frac{\lambda_i}{\overline{\lambda}} + \frac{\overline{\lambda}}{\lambda_i} \right) \leq 2d + 2.$$

• Convexity of 
$$\overline{\lambda} \to \frac{\lambda_i}{\overline{\lambda}} + \frac{\overline{\lambda}}{\lambda_i}$$
 on  $[\lambda_{\min}, \lambda_{\max}]$ :

$$\max_{j} \sum_{i \neq j} \left( \frac{\lambda_{i}}{\lambda_{\min}} + \frac{\lambda_{\min}}{\lambda_{i}} \right) \vee \max_{j} \sum_{i \neq j} \left( \frac{\lambda_{i}}{\lambda_{\max}} + \frac{\lambda_{\max}}{\lambda_{i}} \right) \leq 2d + 2.$$

• Sufficient condition:

$$\sum_{i} \left( \frac{\lambda_{i}}{\lambda_{\min}} + \frac{\lambda_{\min}}{\lambda_{i}} \right) \vee \sum_{i} \left( \frac{\lambda_{i}}{\lambda_{\max}} + \frac{\lambda_{\max}}{\lambda_{i}} \right) \leq 2d + 4.$$

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Ideas of proof



#### Lemma

The coercivity property:

 $\exists \varepsilon > 0 \text{ s.t. } \forall \rho \in (\mathbb{R}^d_+)^*, \ \forall y \in \mathbb{R}^d, \ y^* M(\rho) y \geq (\varepsilon - 1) \ |y|^2.$ 

is satisfied iff

$$(C) : \sum_{i} \left( \frac{\lambda_{i}}{\lambda_{max}} + \frac{\lambda_{max}}{\lambda_{i}} \right) \vee \sum_{i} \left( \frac{\lambda_{i}}{\lambda_{min}} + \frac{\lambda_{min}}{\lambda_{i}} \right) < 2d + 4.$$

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#### Ideas of proof

# Step 1/3: Existence to an approximate PDS when $\mu \in L^2(\mathbb{R})$

- Assume that  $\mu(dx) = p_0(x)dx$ ,  $p_0 \in L^2(\mathbb{R})$ .
- For  $\epsilon > 0$ , use Galerkin's method to solve an approximate PDE:

$$\begin{pmatrix} \partial_t p_1^{\epsilon} \\ \cdot \\ \cdot \\ \partial_t p_d^{\epsilon} \end{pmatrix} = \frac{1}{2} \partial_x \begin{pmatrix} (I_d + M^{\epsilon}(p)) \begin{pmatrix} \cdot \\ \cdot \\ \cdot \\ \partial_x p_d^{\epsilon} \end{pmatrix} \end{pmatrix}$$
$$(p_1^{\epsilon}(0), \dots, p_d^{\epsilon}(0)) = (\alpha_1, \dots, \alpha_d) p_0$$

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#### Ideas of proof

# Step 1/3: Existence to an approximate PDS when $\mu \in L^2(\mathbb{R})$

$$M_{ii}^{\epsilon}(\rho) = \frac{\sum_{j \neq i} \lambda_j \rho_j^+ \sum_j (\lambda_i - \lambda_I) \rho_I^+}{\left(\epsilon \vee \sum_j \lambda_j \rho_j^+\right)^2},$$
$$M_{ik}^{\epsilon}(\rho) = \frac{\lambda_i \rho_i^+ \sum_j (\lambda_j - \lambda_k) \rho_j^+}{\left(\epsilon \vee \sum_j \lambda_j \rho_j^+\right)^2}, \ i \neq k$$

- $\rho \mapsto M^{\epsilon}(\rho)$  locally Lipschitz and bounded  $\rightarrow \exists !$  solution  $p_m^{\epsilon}$  to a projection of the equation in dimension m.
- coercivity uniform in *e* under (C) : ∃ solution *p<sup>e</sup>* satisfying uniform in *e* SEE by taking the limit *m* → ∞.
- Taking  $p_{\epsilon}^{-}$  as test function, we show that  $p_{\epsilon} \geq 0$ .
- $\forall \epsilon, \forall i, \sum_j M_{ji}^{\epsilon} = 0 \implies \sum_j p_j^{\epsilon}$  solves the heat equation  $\longrightarrow$  lower bound uniform in  $\epsilon$  (but not t, x) for  $\sum_j \lambda_j p_j^{\epsilon}$ .
- $\epsilon \to 0$ , existence of a solution to the original PDS.

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Ideas of proof

## Step 2/3: Existence to the PDS when $\mu \in \mathcal{P}(\mathbb{R})$

- By mollification of  $\mu$ , we use the results of Step 1 to extract a solution to the PDS when  $\mu \in \mathcal{P}(\mathbb{R})$ .
- We use the fact that  $\sum_{j} p_{j}$  is solution to the heat equation to control the rate of explosion of  $t \mapsto \int_{\mathbb{R}} \sum_{i=1}^{d} p_{i}^{2}(t, x) dx$  as  $t \to 0$  uniformly in the mollification parameter.

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Ideas of proof

#### Step 3/3: Existence of a weak the SDE (FBM)

#### Theorem (Figalli (2008))

For  $a: [0, T] \times \mathbb{R} \to \mathbb{R}_+$  and  $b: [0, T] \times \mathbb{R} \to \mathbb{R}$  meas. and bounded let  $L_t \varphi(x) = \frac{1}{2}a(t, x)\varphi''(x) + b(t, x)\varphi'(x)$ . If  $[0, T] \ni t \mapsto \mu_t \in \mathcal{M}_+(\mathbb{R})$  is weakly continuous and solves the Fokker-Planck equation  $\partial_t \mu_t = L_t^* \mu_t$  in the sense of distributions then there exists a probability measure P on  $C([0, T], \mathbb{R})$  with marginals  $(P_t = \mu_t)_{t \in [0, T]}$  such that  $\forall \varphi \in C_b^2(\mathbb{R}), \ \varphi(X_t) - \int_0^t L_s \varphi(X_s) ds$  is a P-martingale.

 $\Rightarrow \text{for } i \in \{1, \dots, d\}, \text{ there exists a probab. } P^i \text{ on } C([0, T], \mathbb{R}) \\ \text{with } P_0^i = \mu \text{ and } P_t^i = \frac{P_i(t, x) dx}{\alpha_i} \text{ for } t \in (0, T] \text{ and } \forall \varphi \in C_b^2(\mathbb{R}),$ 

$$\varphi(X_t) - \int_0^t \frac{f^2(y_i)\sum_{j=1}^d p_j}{\sum_{j=1}^d f^2(y_j)p_j} (s, X_s)\varphi''(X_s)ds \text{ is a } P^i\text{-martingale.}$$

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#### Ideas of proof

## Step 3/3: Existence of a weak the SDE (FBM)

For

$$P(dX, dY) = \sum_{i=1}^{d} \alpha_i P^i(dX) \otimes \delta_{y_i}(dY),$$

• Under 
$$P$$
,  $(X_0, Y) \sim \mu \otimes \sum_{i=1}^d \alpha_i \delta_{y_i}$  and for  $t \in (0, T]$ ,  
 $(X_t, Y) \sim \sum_{i=1}^d p_i(t, x) dx \delta_{y_i}$  so that  $X_t \sim \sum_{i=1}^d p_i(t, x) dx$  and  
 $\sum_{i=1}^d e^{2(x_i) + e(t, X_i)}$ 

$$\mathbb{E}^{P}[f^{2}(Y)|X_{t}] = \frac{\sum_{j=1}^{d} f^{2}(y_{j})p_{j}(t, X_{t})}{\sum_{j=1}^{d} p_{j}(t, X_{t})}$$

$$\bullet \,\, \forall \varphi \in \mathit{C}^2_b(\mathbb{R})$$

$$\varphi(X_t) - \int_0^t \underbrace{\frac{f^2(Y)\sum_{j=1}^d p_j}{\sum_{j=1}^d f^2(y_j)p_j}(s, X_s)}_{=\frac{f^2(Y)}{\mathbb{E}^P[f^2(Y)|X_s]}} \varphi''(X_s) ds \text{ is a } P \text{-martingale.}$$

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## Outline

#### Processes matching given marginals

- Motivation
- Simulation of calibrated LSV models and theoretical results

#### 2 A new fake Brownian motion

- The studied problem
- Main result
- Ideas of proof

#### Existence of Calibrated RSLV models

- The calibrated RSLV model
- Main result

Processes matching given marginals	A new <i>fake</i> Brownian motion	Existence of Calibrated RSLV models
The calibrated RSLV model		
Presentation		

• We consider the following dynamics (RSLV):

$$dS_t = rS_t dt + \frac{f(Y_t)}{\sqrt{\mathbb{E}\left[f^2(Y_t)|S_t\right]}}\sigma_{Dup}(t,S_t)S_t dW_t,$$

where  $(Y_t)_{t\geq 0}$  takes values in  $\mathcal{Y}$ , and

$$\mathbb{P}\left(Y_{t+dt}=y_{j}|Y_{t}=y_{i},S_{t}=x\right)=q_{ij}(x)dt.$$

- Switching diffusion, special case of LSV model.
- Jump distributions and intensities are functions of the asset level.

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Existence of Calibrated RSLV models

The calibrated RSLV model

#### Assumptions

• (C), (Coerc. 1): f satisfies condition (C). • (HQ), (Bounded I)  $\exists \overline{q} > 0$ ,  $s.t. \forall x \in \mathbb{R}, |q_{ij}(x)| \leq \overline{q}$ . We define  $\tilde{\sigma}_{Dup}(t, x) := \sigma_{Dup}(t, e^{x})$ . • (H1), (Bounded vol.)  $\tilde{\sigma}_{Dup} \in L^{\infty}([0, T], W^{1,\infty}(\mathbb{R}))$ . • (H2), (Coerc. 2)  $\exists \underline{\sigma} > 0$  s.t.  $\underline{\sigma} \leq \tilde{\sigma}_{Dup}$  a.e. on  $[0, T] \times \mathbb{R}$ ,. • (H3), (Regul. 1)  $\exists \eta \in (0, 1], \exists H_0 > 0$ , s.t.  $\forall s, t \in [0, T], \forall x, y \in \mathbb{R}$ ,  $|\tilde{\sigma}_{Dup}(s, x) - \tilde{\sigma}_{Dup}(t, y)| \leq H_0 (|x - y|^{\eta} + |t - s|^{\eta})$ .

(HQ), (H1) and (H2) permit to generalize the energy estimations to the Fokker-Planck system associated with  $((\ln(S_t), Y_t))_{t \in [0, T]}$  With (H3), uniqueness and Aronson estimates for the Fokker-Planck equation associated with  $(\ln(S_t^{Dup}))_{t \in [0, T]}$  where

$$dS_t^{Dup} = \sigma_{Dup}(t, S_t^{Dup}) S_t^{Dup} dW_t + rS_t^{Dup} dt, \ S_0^{Dup} = S_0$$

 $\longrightarrow$  replaces the heat equation

A new *fake* Brownian motion

Existence of Calibrated RSLV models  ${\circ}{\circ}{\circ}{\circ}{\circ}$ 

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Main result

#### Main result

#### Theorem

Under Conditions (H1)-(H3), (HQ) and (C) there exists a weak solution to the SDE (RSLV). Moreover, it has the same marginals as the solution to the local volatility SDE

$$dS_t^{Dup} = \sigma_{Dup}(t, S_t^{Dup}) S_t^{Dup} dW_t + rS_t^{Dup} dt, \ S_0^{Dup} = S_0$$

We generalize the results of Figalli to the regime switching case.

Processes	matching	given	marginals

Main result

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#### Thank you for your attention!