# A general two-scale criteria for logarithmic Sobolev inequalities 

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#### Abstract

We present a general criteria to prove that a probability measure satisfies a logarithmic Sobolev inequality, knowing that some of its marginals and associated conditional laws satisfy a logarithmic Sobolev inequality. This is a generalization of a result by N. Grunewald et al. [5].


## 1 Motivation and notation

The motivation behind this work is molecular dynamics (in the canonical statistical ensemble), and more precisely, $(i)$ the analysis of numerical methods for the computation of free energy differences [7] and (ii) the derivation of effective dynamics on coarse-grained variables [6]. In both cases, it appears that estimates based on entropies for measures related to the BoltzmannGibbs measure is a useful tool. One important question is the following: what is the link between the logarithmic Sobolev inequality (LSI) constant of the Boltzmann-Gibbs measure for the original variables (microscopic level) and the LSI constant of the Boltzmann-Gibbs measure for some coarse-grained variables (macroscopic level). The aim of this work is to give an answer, which is a generalization to non-linear coarse-graining operators of results in $[8,5]$.

Let $\mathcal{D}$ be a domain of $\mathbb{R}^{n}$ representing the configuration space of the system under consideration, and $V: \mathcal{D} \rightarrow \mathbb{R}$ a potential, associating to each configuration an energy. Let us consider a function (representing the coarse-grained

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variables, also called the reaction coordinates)

$$
\xi: \mathcal{D} \rightarrow \mathcal{M}
$$

with $\mathcal{M} \subset \mathbb{R}^{p}$ (and $\left.1 \leq p<n\right)$. Let us introduce the Gram matrix $G: \mathcal{D} \rightarrow$ $\mathbb{R}^{p \times p}$ of the derivative $\nabla \xi: \mathcal{D} \rightarrow \mathbb{R}^{p \times n}: G=\nabla \xi \nabla \xi^{T}$, i.e., componentwise, $\forall \alpha, \beta \in\{1, \ldots, p\}$,

$$
\begin{equation*}
G_{\alpha, \beta}=\nabla \xi_{\alpha} \cdot \nabla \xi_{\beta} \tag{1}
\end{equation*}
$$

We suppose that $\xi$ is such that
[H1] $\xi$ is a smooth function such that $\operatorname{det} G \neq 0$ on $\mathcal{D}$.
The submanifolds

$$
\Sigma_{z}=\{x \in \mathcal{D}, \xi(x)=z\}
$$

are then smooth submanifolds of $\mathcal{D}$ of codimension $p$. We denote by $\sigma_{\Sigma_{z}}$ the surface measure on $\Sigma_{z}$, i.e. the Lebesgue measure on $\Sigma_{z}$ induced by the Lebesgue measure in the ambient Euclidean space $\mathcal{D}$. The submanifold $\Sigma_{z}$ naturally has a (complete and locally compact) Riemannian structure induced by the Euclidean structure of the ambient space $\mathcal{D}$.

Let us define the density $\psi_{0}$ (with respect to the Lebesgue measure on $\mathcal{D}$ ) of the Boltzmann-Gibbs probability measure $d \mu_{0}(x)=\psi_{0}(x) d x$ associated to the potential $V$ :

$$
\psi_{0}=Z^{-1} \exp (-V)
$$

where $Z=\int_{\mathcal{D}} \exp (-V)$. We denote by $\psi_{0}^{\xi}$ the density (with respect to the Lebesgue measure on $\mathcal{M}$ ) of the image $d \mu_{0}^{\xi}(z)=\psi_{0}^{\xi}(z) d z$ of the measure $\mu_{0}$ by $\xi$ :

$$
\psi_{0}^{\xi}(z)=Z^{-1} \int_{\Sigma_{z}} \exp (-V)(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}
$$

Let us introduce then the conditional measure $\mu_{0, z}$ of $\mu_{0}$ at a fixed value of $\xi$ :

$$
d \mu_{0, z}=\frac{Z^{-1} \exp (-V)(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}}{\psi_{0}^{\xi}(z)}
$$

Let us introduce the effective potential $A_{0}$ associated to $\xi$ (also called free energy), defined by

$$
\begin{equation*}
A_{0}(z)=-\ln \psi_{0}^{\xi}(z) \tag{2}
\end{equation*}
$$

The following expression for the derivative of $A_{0}$ (also called the mean force) is obtained:

$$
\begin{equation*}
\nabla A_{0}(z)=\int_{\Sigma_{z}} F d \mu_{0, z} \tag{3}
\end{equation*}
$$

where $F$ is defined by: $\forall \alpha \in\{1, \ldots, p\}$,

$$
\begin{equation*}
F_{\alpha}=\sum_{\beta=1}^{p} G_{\alpha, \beta}^{-1} \nabla \xi_{\beta} \cdot \nabla V-\operatorname{div}\left(\sum_{\beta=1}^{p} G_{\alpha, \beta}^{-1} \nabla \xi_{\beta}\right) \tag{4}
\end{equation*}
$$

where $G_{\alpha, \beta}^{-1}$ denotes the $(\alpha, \beta)$-component of the inverse of the matrix $G$. All these results can be derived using the co-area formula (see Lemma 2.2 below), using similar computations as in Lemma 2.3 below.

Let us also introduce the following projection operators: For any $x \in \mathcal{D}$, we denote by

$$
\begin{equation*}
P(x)=\mathrm{Id}-\sum_{\alpha, \beta=1}^{p} G_{\alpha, \beta}^{-1} \nabla \xi_{\alpha} \otimes \nabla \xi_{\beta}(x) \tag{5}
\end{equation*}
$$

the orthogonal projection operator onto the tangent space $T_{x} \Sigma_{\xi(x)}$ to $\Sigma_{\xi(x)}$ at point $x$, and by

$$
\begin{equation*}
Q(x)=\operatorname{Id}-P(x)=\sum_{\alpha, \beta=1}^{p} G_{\alpha, \beta}^{-1} \nabla \xi_{\alpha} \otimes \nabla \xi_{\beta}(x) \tag{6}
\end{equation*}
$$

the orthogonal projection operator onto the normal space $N_{x} \Sigma_{\xi(x)}$ to $\Sigma_{\xi(x)}$ at point $x$. We denote by $\otimes$ the tensor product: for two vectors $u, v \in \mathbb{R}^{n}, u \otimes v$ is a $n \times n$ matrix with components $(u \otimes v)_{i, j}=u_{i} v_{j}$.

For any two probability measures $\mu$ and $\nu$ such that $\mu$ is absolutely continuous with respect to $\nu$ (this property being denoted $\mu \ll \nu$ in the following), we introduce the relative entropy

$$
H(\mu \mid \nu)=\int \ln \left(\frac{d \mu}{d \nu}\right) d \mu
$$

Let us also introduce the Fisher information: For any two probability measures $\mu$ and $\nu$ such that $\mu \ll \nu$,

$$
\begin{equation*}
I(\mu \mid \nu)=\int\left|\nabla \ln \left(\frac{d \mu}{d \nu}\right)\right|^{2} d \mu \tag{7}
\end{equation*}
$$

In (7) and in the following, $|\cdot|$ denotes the Euclidean norm (in $\mathbb{R}^{n}$ or in $\mathbb{R}^{p}$ ). In the case $\nu$ is a probability measure on the (Riemannian) submanifold $\Sigma_{z}$, $\nabla$ actually denotes the gradient on $\Sigma_{z}$ in (7), namely

$$
\begin{equation*}
\nabla_{\Sigma_{z}}=P \nabla \tag{8}
\end{equation*}
$$

We recall the definition of the Logarithmic Sobolev Inequality (LSI):
Definition 1.1 The probability measure $\nu$ satisfies a logarithmic Sobolev inequality with constant $\rho>0$ (in short: $\operatorname{LSI}(\rho)$ ) if for all probability measures $\mu$ such that $\mu \ll \nu$,

$$
H(\mu \mid \nu) \leq \frac{1}{2 \rho} I(\mu \mid \nu)
$$

The main result of this paper states under which condition a LSI holds for $\mu_{0}$,
assuming that a LSI holds for the conditional probability measure $\mu_{0, z}$ (this is [H2]) and for for the marginal $\mu_{0}^{\xi}$ (this is [H3]).

Theorem 1.2 In addition to [H1], let us assume (recall that the local mean force $F$ is defined by (4)):
[H2] $\left\{\begin{array}{c}V \text { and } \xi \text { are such that } \exists \rho>0, \text { for all } z \in \mathcal{M}, \\ \text { the conditional measure } \mu_{0, z} \text { satisfies } \operatorname{LSI}(\rho) .\end{array}\right.$
[H3] $V$ and $\xi$ are such that $\exists r>0$, the measure $d \mu_{0}^{\xi}=\psi_{0}^{\xi}(z) d z$ satisfies $\operatorname{LSI}(r)$.
$[\mathbf{H} 4]\left\{\begin{array}{c}V \text { and } \xi \text { are sufficiently differentiable functions such that: } \exists m>0, G \geq m \text { Id and } \\ \text { (a) }\left\|\nabla_{\Sigma_{z}} F\right\|_{L^{\infty}} \leq M<\infty \text { or (b) }\|F\|_{L^{\infty}} \leq \frac{M}{\sqrt{\rho}}<\infty .\end{array}\right.$
Then $\mu_{0}$ satisfies $L S I(R)$ for some constant $R$ which satisfies:

$$
\begin{equation*}
R \geq \frac{1}{2}\left(r m+\frac{M^{2} m}{\rho}+\rho-\sqrt{\left(r m+\frac{M^{2} m}{\rho}+\rho\right)^{2}-4 r m \rho}\right) . \tag{9}
\end{equation*}
$$

In [H4], $G \geq m$ Id should be understood in the following sense: for any vector $u \in \mathbb{R}^{p}, u^{T} G u \geq m|u|^{2}$. In [H4-a] or [H4-b], the $L^{\infty}$ norm is with respect to $x \in \mathcal{D}:\|F\|_{L^{\infty}}=\sup _{x \in \mathcal{D}}|F|$ and $\left\|\nabla_{\Sigma_{z}} F\right\|_{L^{\infty}}=\sup _{x \in \mathcal{D}}\left|\nabla_{\Sigma_{z}} F\right|$, where $|\cdot|$ here denotes the operator norm on the matrix $\nabla_{\Sigma_{z}} F$ associated to the Euclidean norm on the vectors: $\left|\nabla_{\Sigma_{z}} F(x)\right|=\sup _{u \in T_{x} \Sigma_{z}} \frac{|\nabla F(x) u|}{|u|}$.

Assumption [H4-a] is an assumption on the coupling in the following sense. Assume that $V(x)=\frac{1}{2} x^{T} H x$ for some symmetric positive matrix $H \in \mathbb{R}^{n \times n}$ (so that $\mu_{0}$ is a Gaussian law), and that $\xi\left(x_{1}, \ldots, x_{n}\right)=\left(x_{1}, \ldots, x_{p}\right)$. In this case, $G=\mathrm{Id}$, and $\nabla_{\Sigma_{z}} F=0$ is equivalent to the fact that the covariance $\operatorname{Cov}\left(\left(X_{1}, \ldots, X_{p}\right),\left(X_{p+1}, \ldots, X_{n}\right)\right)=0$, where $\left(X_{1}, \ldots, X_{n}\right)$ is a random variable with law $\mu_{0}$. In this case of Gaussian laws and a linear function $\xi$, it can be checked that (9) is optimal (see [8]).

## 2 Proof

To prove the result, we need to introduce a few other notation. Let $\psi$ be a probability density functional on $\mathcal{D}$. We denote the total entropy by

$$
E=H\left(\psi \mid \psi_{0}\right)
$$

and the macroscopic entropy by

$$
E_{M}=H\left(\psi^{\xi} \mid \psi_{0}^{\xi}\right)
$$

where

$$
\psi^{\xi}(z)=\int_{\Sigma_{z}} \psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}} .
$$

We denote the conditioned probability measures of $\psi$ at a fixed value $z$ of the reaction coordinate by

$$
d \mu_{z}=\frac{\psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}}{\psi^{\xi}(z)}
$$

the "local entropy" by

$$
e_{m}(z)=H\left(\mu_{z} \mid \mu_{0, z}\right)=\int_{\Sigma_{z}} \ln \left(\frac{\psi}{\psi^{\xi}(z)} / \frac{\psi_{0}}{\psi_{0}^{\xi}(z)}\right) d \mu_{z}
$$

and finally the microscopic entropy by

$$
E_{m}=\int_{\mathcal{M}} e_{m}(z) \psi^{\xi}(z) d z
$$

It is straightforward to obtain the following result which can be seen as a property of extensivity of the entropy:

Lemma 2.1 It holds

$$
E=E_{M}+E_{m}
$$

We will need the co-area formula (see [1,4]):
Lemma 2.2 For any smooth function $\phi: \mathbb{R}^{n} \rightarrow \mathbb{R}$,

$$
\begin{equation*}
\int_{\mathbb{R}^{n}} \phi(x)(\operatorname{det} G(x))^{1 / 2} d x=\int_{\mathbb{R}^{p}} \int_{\Sigma_{z}} \phi d \sigma_{\Sigma_{z}} d z \tag{10}
\end{equation*}
$$

where $G$ is defined by (1).
Remark 1 The co-area formula shows that if the random variable $X$ has law $\psi(x) d x$ in $\mathbb{R}^{n}$, then $\xi(X)$ has law

$$
\int_{\Sigma_{z}} \psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}} d z
$$

and the law of $X$ conditioned to a fixed value $z$ of $\xi(X)$ is

$$
d \mu_{z}=\frac{\psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}}{\int_{\Sigma_{z}} \psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}}
$$

Indeed, for any bounded functions $f$ and $g$,

$$
\begin{aligned}
\mathbb{E}(f(\xi(X)) g(X)) & =\int_{\mathbb{R}^{n}} f(\xi(x)) g(x) \psi(x) d x \\
& =\int_{\mathbb{R}^{p}} \int_{\Sigma_{z}} f \circ \xi g \psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}} d z \\
& =\int_{\mathbb{R}^{p}} f(z) \frac{\int_{\Sigma_{z}} g \psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}}{\int_{\Sigma_{z}} \psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}} \int_{\Sigma_{z}} \psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}} d z
\end{aligned}
$$

The measure $(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}$ is sometimes denoted by $\delta_{\xi(x)-z}$ in the literature.
From the co-area formula, we get:
Lemma 2.3 The derivative of $\psi^{\xi}$ reads: $\forall \alpha \in\{1, \ldots, p\}$,

$$
\partial_{z_{\alpha}} \psi^{\xi}(z)=\int_{\Sigma_{z}} \sum_{\beta=1}^{p}\left(G_{\alpha, \beta}^{-1} \nabla \xi_{\beta} \cdot \nabla \psi+\operatorname{div}\left(G_{\alpha, \beta}^{-1} \nabla \xi_{\beta}\right) \psi\right)(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}} .
$$

Proof: For any smooth test function $g: \mathcal{M} \rightarrow \mathbb{R}^{p}$, we obtain (using the co-area formula (10) and an integration by parts) ${ }^{1}$ :

$$
\begin{aligned}
\int_{\mathcal{M}} \psi^{\xi} \operatorname{div} g & =\int_{\mathcal{D}} \psi(\operatorname{div} g) \circ \xi \\
& =\int_{\mathcal{D}} \psi G_{\alpha, \beta}^{-1} \nabla \xi_{\beta} \cdot \nabla\left(g_{\alpha} \circ \xi\right) \\
& =-\int_{\mathcal{D}} \operatorname{div}\left(\psi G_{\alpha, \beta}^{-1} \nabla \xi_{\beta}\right) g_{\alpha} \circ \xi \\
& =-\int_{\mathcal{M}} g_{\alpha}(z) \int_{\Sigma_{z}}\left(G_{\alpha, \beta}^{-1} \nabla \xi_{\beta} \cdot \nabla \psi+\operatorname{div}\left(G_{\alpha, \beta}^{-1} \nabla \xi_{\beta}\right) \psi\right)(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}} d z
\end{aligned}
$$

which yields the result.

A corollary of Lemma 2.3 applied with $\psi=\psi_{0}$ is Equation (3). Let us now introduce the mean force associated with $\psi$ (compare with (3)):

$$
D(z)=\int_{\Sigma_{z}} F d \mu_{z} .
$$

Notice that, in general, $D \neq-\nabla \ln \psi^{\xi}$, and curl $D \neq 0$. We need a measure of the difference between $D$ and $\nabla A_{0}$, in terms of the difference between $\psi$ and $\psi_{0}$ :

Lemma 2.4 The difference between $D$ and $\nabla A_{0}$ can be expressed in terms

[^0]of $\psi$ and $\psi_{0}$ as: for $\alpha \in\{1, \ldots, p\}$, for all $z \in \mathcal{M}$,
$$
\left(D_{\alpha}-\partial_{z_{\alpha}} A_{0}\right)(z)=\int_{\Sigma_{z}} \sum_{\beta=1}^{p} G_{\alpha, \beta}^{-1} \nabla \xi_{\beta} \cdot \nabla \ln \left(\frac{\psi}{\psi_{0}}\right) \frac{\psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}}{\psi^{\xi}}-\partial_{z_{\alpha}} \ln \left(\frac{\psi^{\xi}}{\psi_{0}^{\xi}}\right) .
$$

Proof: Using Lemma 2.3 and the definition of $D$, it holds:

$$
\begin{aligned}
& \int_{\Sigma_{z}} G_{\alpha, \beta}^{-1} \nabla \xi_{\beta} \cdot \nabla \ln \left(\frac{\psi}{\psi_{0}}\right) \frac{\psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}}{\psi^{\xi}}-\partial_{z_{\alpha}} \ln \left(\frac{\psi^{\xi}}{\psi_{0}^{\xi}}\right) \\
&= \frac{1}{\psi^{\xi}} \int_{\Sigma_{z}} G_{\alpha, \beta}^{-1} \nabla \xi_{\beta} \cdot \nabla \psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}+\int_{\Sigma_{z}} G_{\alpha, \beta}^{-1} \nabla \xi_{\beta} \cdot \nabla V \frac{\psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}}{\psi^{\xi}} \\
&-\partial_{z_{\alpha}} \ln \psi^{\xi}+\partial_{z_{\alpha}} \ln \psi_{0}^{\xi} \\
&=-\int_{\Sigma_{z}} \operatorname{div}\left(G_{\alpha, \beta}^{-1} \nabla \xi_{\beta}\right) \frac{\psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}}{\psi^{\xi}}+\int_{\Sigma_{z}} G_{\alpha, \beta}^{-1} \nabla \xi_{\beta} \cdot \nabla V \frac{\psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}}{\psi^{\xi}} \\
&-\partial_{z_{\alpha}} A_{0} \\
&= D_{\alpha}-\partial_{z_{\alpha}} A_{0} .
\end{aligned}
$$

From Lemma 2.4, the following estimates are obtained:
Lemma 2.5 Let us assume [H2] and [H4]. Then for all $z \in \mathcal{M}$,

$$
\left|D(z)-\nabla A_{0}(z)\right| \leq M \sqrt{\frac{2}{\rho} e_{m}(z)}
$$

Proof: If we suppose [H4-b], then we have:

$$
\begin{aligned}
\left|D(z)-\nabla A_{0}(z)\right| & =\left|\int F d \mu_{z}-\int F d \mu_{0, z}\right| \\
& \leq\|F\|_{L^{\infty}}\left\|\mu_{z}-\mu_{0, z}\right\|_{V T} \\
& \leq \frac{M}{\sqrt{\rho}}\left\|\mu_{z}-\mu_{0, z}\right\|_{V T}
\end{aligned}
$$

where $\left\|\mu_{z}-\mu_{0, z}\right\|_{V T}$ denotes the total variation norm of the signed measure $\left(\mu_{z}-\mu_{0, z}\right)$. The result then follows from the Csiszar-Kullback inequality (see for example [2]):

$$
\left\|\mu_{z}-\mu_{0, z}\right\|_{V T} \leq \sqrt{2 H\left(\mu_{z} \mid \mu_{0, z}\right)}
$$

Let us now assume [H4-a]. For any coupling measure $\pi \in \Pi\left(\mu_{z}, \mu_{0, z}\right)$ defined on $\Sigma_{z} \times \Sigma_{z}$ (namely any probability measure on $\Sigma \times \Sigma$ such that its marginals
are $\mu_{z}$ and $\mu_{0, z}$ ), it holds:

$$
\begin{aligned}
\left|D(z)-\nabla A_{0}(z)\right| & =\left|\int_{\Sigma_{z} \times \Sigma_{z}}\left(F(x)-F\left(x^{\prime}\right)\right) \pi\left(d x, d x^{\prime}\right)\right| \\
& \leq\left\|\nabla_{\Sigma_{z}} F\right\|_{L^{\infty}} \int_{\Sigma_{z} \times \Sigma_{z}} d_{\Sigma_{z}}\left(x, x^{\prime}\right) \pi\left(d x, d x^{\prime}\right), \\
& \leq M \int_{\Sigma_{z} \times \Sigma_{z}} d_{\Sigma_{z}}\left(x, x^{\prime}\right) \pi\left(d x, d x^{\prime}\right)
\end{aligned}
$$

where $d_{\Sigma_{z}}$ denotes the geodesic distance on $\Sigma_{z}: \forall x, y \in \Sigma_{z}$,

$$
d_{\Sigma_{z}}(x, y)=\inf \left\{\sqrt{\int_{0}^{1}|\dot{w}(t)|^{2} d t} \mid w \in \mathcal{C}^{1}\left([0,1], \Sigma_{z}\right), w(0)=x, w(1)=y\right\}
$$

Taking now the infimum over all $\pi \in \Pi\left(\mu_{z}, \mu_{0, z}\right)$, we obtain

$$
\left|D(z)-\nabla A_{0}(z)\right| \leq M W\left(\mu_{z}, \mu_{0, z}\right)
$$

where $W\left(\mu_{z}, \mu_{0, z}\right)$ denotes the Wasserstein distance with linear cost (see for example [2]). It is known that if $\mu_{0, z}$ satisfies a LSI (which is [H2]), then we have the following Talagrand inequality (see [3,9]):

$$
W\left(\mu_{z}, \mu_{0, z}\right) \leq \sqrt{\frac{2}{\rho} H\left(\mu_{z} \mid \mu_{0, z}\right)} .
$$

This implies the result.

Lemma 2.6 Let us assume [H2]. Then it holds

$$
E_{m} \leq \frac{1}{2 \rho} \int_{\mathcal{D}}\left|\nabla_{\Sigma_{z}} \ln \left(\frac{\psi}{\psi_{0}}\right)\right|^{2} \psi
$$

Proof: Notice that the Fisher information of $\mu_{z}$ with respect to $\mu_{0, z}$ writes

$$
I\left(\mu_{z} \mid \mu_{0, z}\right)=\int_{\Sigma_{z}}\left|\nabla_{\Sigma_{z}} \ln \left(\frac{\psi}{\psi_{0}}\right)\right|^{2} \frac{\psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}}{\psi^{\xi}(z)}
$$

Therefore, using [H2], it follows:

$$
\begin{aligned}
E_{m} & =\int_{\mathcal{M}} e_{m} \psi^{\xi} d z \\
& \leq \int_{\mathcal{M}} \frac{1}{2 \rho} \int_{\Sigma_{z}}\left|\nabla_{\Sigma_{z}} \ln \left(\frac{\psi}{\psi_{0}}\right)\right|^{2} \frac{\psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}}{\psi^{\xi}(z)} \psi^{\xi} d z
\end{aligned}
$$

which yields the result, using the co-area formula (10).

We are now in position to prove Theorem 1.2. We have (using [H2], [H3], Lemma 2.1, Lemma 2.4, and the inequality $(a+b)^{2} \leq(1+\varepsilon) a^{2}+\left(1+\varepsilon^{-1}\right) b^{2}$, for a positive $\varepsilon$ to be fixed later on):

$$
\begin{aligned}
E=E_{m}+E_{M} \leq & \frac{1}{2 \rho} \int_{\mathcal{D}}\left|\nabla_{\Sigma_{z}} \ln \left(\frac{\psi}{\psi_{0}}\right)\right|^{2} \psi+\frac{1}{2 r} \int_{\mathcal{M}}\left|\nabla \ln \left(\frac{\psi^{\xi}}{\psi_{0}^{\xi}}\right)\right|^{2} \psi^{\xi} \\
\leq & \frac{1}{2 \rho} \int_{\mathcal{D}}\left|\nabla_{\Sigma_{z}} \ln \left(\frac{\psi}{\psi_{0}}\right)\right|^{2} \psi+\frac{1+\varepsilon}{2 r} \int_{\mathcal{M}}\left|D-\nabla A_{0}\right|^{2} \psi^{\xi} \\
& +\frac{1+\varepsilon^{-1}}{2 r} \int_{\mathcal{M}} \sum_{\alpha=1}^{p}\left|\int_{\Sigma_{z}} G_{\alpha, \beta}^{-1} \nabla \xi_{\beta} \cdot \nabla \ln \left(\frac{\psi}{\psi_{0}}\right) \frac{\psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}}{\psi^{\xi}}\right|^{2} \psi^{\xi} .
\end{aligned}
$$

Using the Cauchy-Schwarz inequality:

$$
\begin{aligned}
& \left|\int_{\Sigma_{z}} G_{\alpha, \beta}^{-1} \nabla \xi_{\beta} \cdot \nabla \ln \left(\frac{\psi}{\psi_{0}}\right) \frac{\psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}}{\psi^{\xi}}\right|^{2} \\
& \quad \leq \int_{\Sigma_{z}}\left|G_{\alpha, \beta}^{-1} \nabla \xi_{\beta} \cdot \nabla \ln \left(\frac{\psi}{\psi_{0}}\right)\right|^{2} \frac{\psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}}}{\psi^{\xi}}
\end{aligned}
$$

and Lemma 2.5, we thus obtain

$$
\begin{aligned}
E \leq & \frac{1}{2 \rho} \int_{\mathcal{D}}\left|\nabla_{\Sigma_{z}} \ln \left(\frac{\psi}{\psi_{0}}\right)\right|^{2} \psi+\frac{(1+\varepsilon) M^{2}}{r \rho} \int_{\mathcal{M}} e_{m} \psi^{\xi} \\
& +\frac{1+\varepsilon^{-1}}{2 r} \int_{\mathcal{M}} \int_{\Sigma_{z}} \sum_{\alpha=1}^{p}\left|G_{\alpha, \beta}^{-1} \nabla \xi_{\beta} \cdot \nabla \ln \left(\frac{\psi}{\psi_{0}}\right)\right|^{2} \psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}} .
\end{aligned}
$$

For any vector $u \in \mathbb{R}^{n}$, notice that $|Q u|^{2}=G_{\alpha, \beta}^{-1} \nabla \xi_{\alpha} \cdot u \nabla \xi_{\beta} \cdot u$, and that $|u|^{2}=|P u|^{2}+|Q u|^{2}$ (where $P$ and $Q$ are the projection operators defined by (5) and (6)). Using [H4], we thus have:

$$
\begin{aligned}
\sum_{\alpha=1}^{p}\left|G_{\alpha, \beta}^{-1} \nabla \xi_{\beta} \cdot u\right|^{2} & =G_{\alpha, \beta}^{-1} \nabla \xi_{\beta} \cdot u G_{\alpha, \gamma}^{-1} \nabla \xi_{\gamma} \cdot u \\
& \leq \frac{1}{m} G_{\beta, \gamma}^{-1} \nabla \xi_{\beta} \cdot u \nabla \xi_{\gamma} \cdot u \\
& =\frac{1}{m}|Q u|^{2}
\end{aligned}
$$

Applying this inequality with $u=\nabla \ln \left(\frac{\psi}{\psi_{0}}\right)$ and using Lemma 2.6, we get:

$$
\begin{aligned}
E \leq & \frac{1}{2 \rho} \int_{\mathcal{D}}\left|P \nabla \ln \left(\frac{\psi}{\psi_{0}}\right)\right|^{2} \psi+\frac{(1+\varepsilon) M^{2}}{r \rho} E_{m} \\
& +\frac{1+\varepsilon^{-1}}{2 r m} \int_{\mathcal{M}} \int_{\Sigma_{z}}\left|Q \nabla \ln \left(\frac{\psi}{\psi_{0}}\right)\right|^{2} \psi(\operatorname{det} G)^{-1 / 2} d \sigma_{\Sigma_{z}} \\
\leq & \left(\frac{1}{2 \rho}+\frac{(1+\varepsilon) M^{2}}{2 r \rho^{2}}\right) \int_{\mathcal{D}}\left|P \nabla \ln \left(\frac{\psi}{\psi_{0}}\right)\right|^{2} \psi \\
& +\frac{1+\varepsilon^{-1}}{2 r m} \int_{\mathcal{D}}\left|Q \nabla \ln \left(\frac{\psi}{\psi_{0}}\right)\right|^{2} \psi .
\end{aligned}
$$

This shows that $\psi$ satisfies a LSI with constant $R$ satisfying

$$
\begin{aligned}
R & \geq \frac{1}{2}\left(\max \left(\frac{1}{2 \rho}+\frac{(1+\varepsilon) M^{2}}{2 r \rho^{2}}, \frac{1+\varepsilon^{-1}}{2 r m}\right)\right)^{-1} \\
& =\min \left(\frac{\rho^{2}}{\rho+(1+\varepsilon) M^{2} / r}, \frac{r m}{1+\varepsilon^{-1}}\right)
\end{aligned}
$$

Optimizing in $\varepsilon$, namely solving $\frac{\rho^{2}}{\rho+(1+\varepsilon) M^{2} / r}=\frac{r m}{1+\varepsilon^{-1}}$ concludes the proof.

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[^0]:    ${ }^{1}$ In all the following proofs, we use the summation convention on repeated Greek indices going from 1 to $p$.

