

Anisotropic, adaptive finite elements

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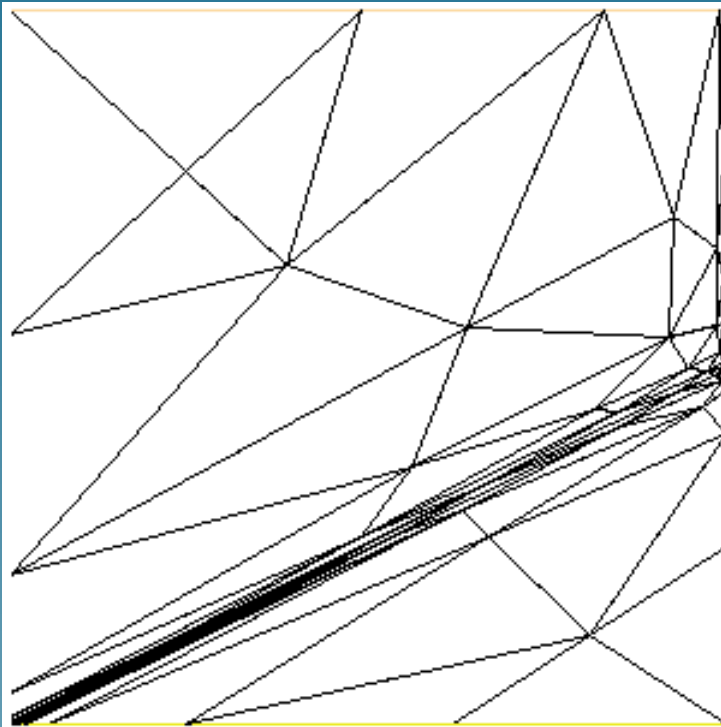
Collaboration with

Erik Burman, Lausanne

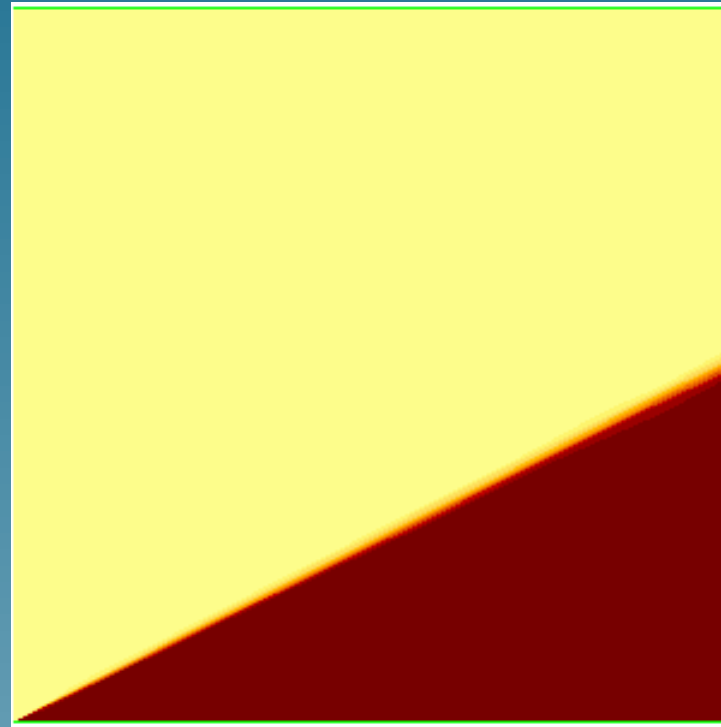
Luca Formaggia, Stefano Micheletti, Simona Perotto, Politecnico di Milano

Example of strongly anisotropic mesh

- Boundary layer 0.0001, 241 vertices, asp. ratio $\geq 10^4$.



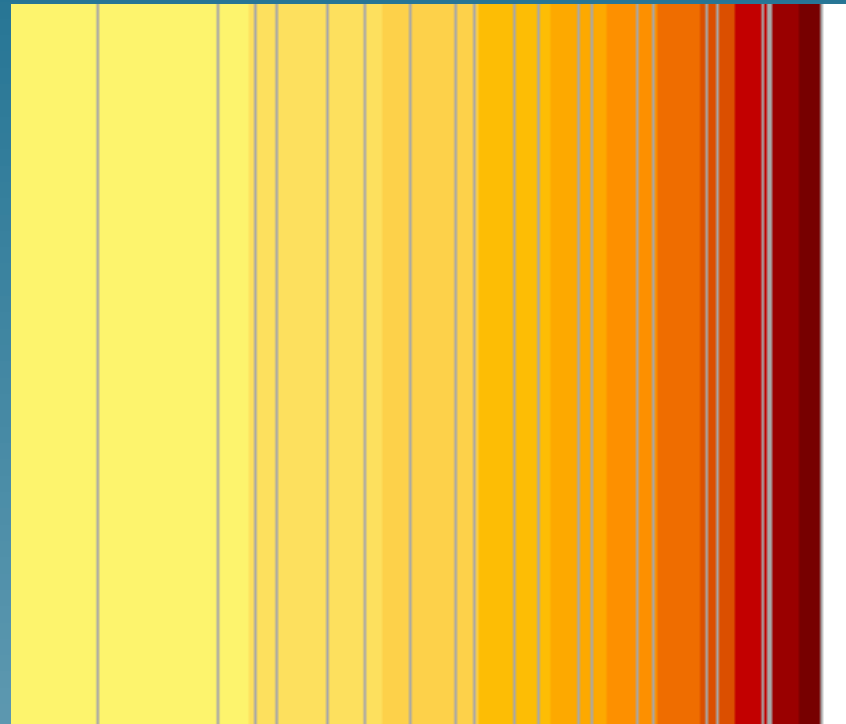
Mesh



Isovalues

- Same accuracy with isotropic, adaptive finite elements : $O(10\ 000)$ vertices !

Example of strongly anisotropic mesh



Zoom 10 000x

Anisotropic a posteriori error estimates and anisotropic, adaptive finite elements

- Laplace problem
- Advection-diffusion
- The heat equation
- Strongly nonlinear parabolic problems arising from solidification of binary alloys (dendrites, cristal growth)

Laplace problem

- Find $u : \Omega \rightarrow \mathbb{R}$ such that

$$\begin{aligned} -\Delta u &= f && \text{in } \Omega, \\ u &= 0 && \text{on } \partial\Omega. \end{aligned}$$

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- Let \mathcal{T}_h be a mesh of Ω into triangles with diameter less than h .
- Find $u_h \in V_h$ (continuous, piecewise linears) such that, for all $v_h \in V_h$

$$\int_{\Omega} \nabla u_h \cdot \nabla v_h = \int_{\Omega} f v_h.$$

Adaptive criteria : a posteriori error estimates

- u solution of the exact problem, u_h finite element solution, $e = u - u_h$.

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$$\int_{\Omega} |\nabla e|^2 \leq Ch^2$$

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$$\int_{\Omega} |\nabla e|^2 \leq Ch^2$$

- A posteriori error estimates : $\exists C(\text{aspect ratio}), \forall h$

$$\int_{\Omega} |\nabla e|^2 \leq C \sum_{K \in \mathcal{T}_h} \eta_K^2(u_h, K, \text{data})$$

A posteriori error estimates : terminology

- Error estimator : $\int_{\Omega} |\nabla e|^2 \leq C \sum_{K \in \mathcal{T}_h} \eta_K^2.$

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- Error estimator is equivalent to the true error : $\exists C_1, C_2, \forall h$

$$C_1 \sum_{K \in \mathcal{T}_h} \eta_K^2 \leq \int_{\Omega} |\nabla e|^2 \leq C_2 \sum_{K \in \mathcal{T}_h} \eta_K^2.$$

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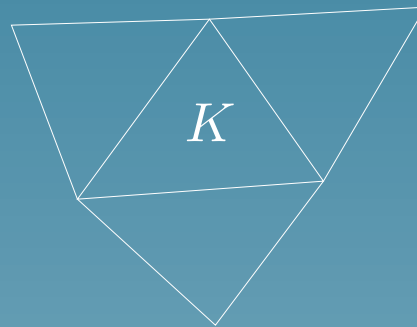
- Quality of the error estimator : effectivity index $ei = \frac{\text{estimated error}}{\text{true error}}.$

- Asymptotically equivalent error estimator : $ei \xrightarrow{h \rightarrow 0} 1.$

A posteriori error estimators : example 1

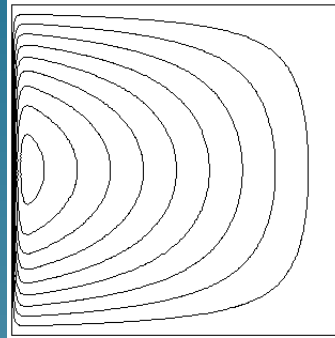
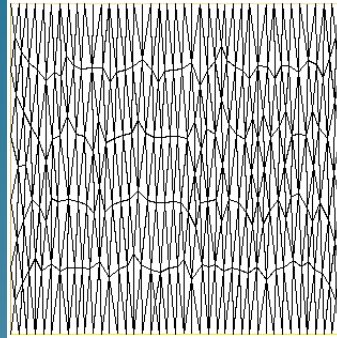
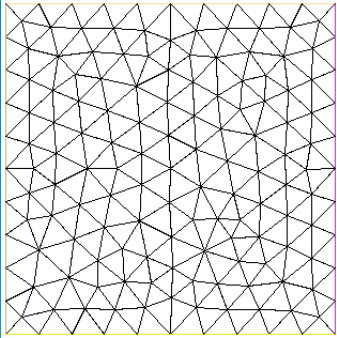
- Isotropic, residual-based, explicit a posteriori error estimator (Baranger El-Amri M2AN 1991, Babuska Duran Rodriguez SIAM Numer. Anal. 1992)

$$\int_{\Omega} |\nabla e|^2 \leq C \sum_{K \in \mathcal{T}_h} \left(h_K^2 \int_K (f + \Delta u_h)^2 + \frac{1}{2} h_K \int_{\partial K} \left[\frac{\partial u_h}{\partial n} \right]^2 \right).$$

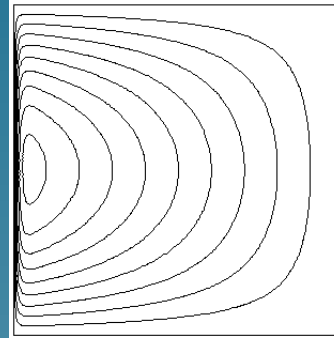
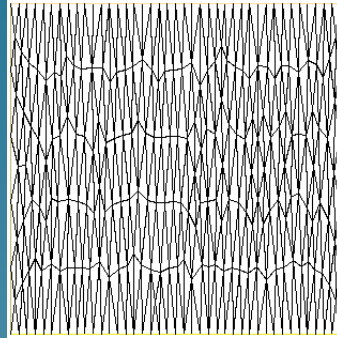
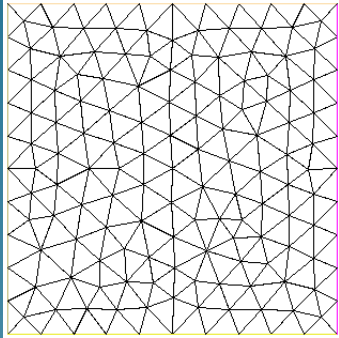


- Equivalent to the true error (the effectivity index depends on the mesh aspect ratio).

Numerical results (isotropic, residual-based, explicit err. est.)

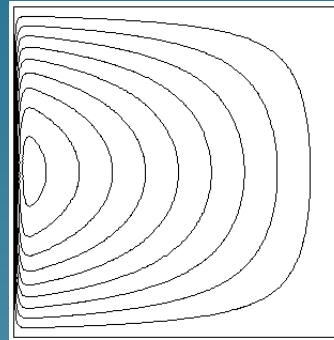
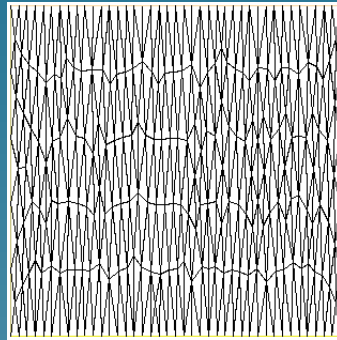
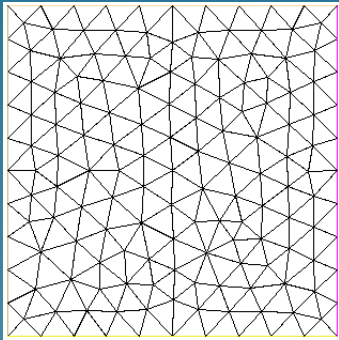


Numerical results (isotropic, residual-based, explicit err. est.)



$h_1 - h_2$	error	ei
0.01 - 0.01	1.36	4.71
0.005 - 0.005	0.69	4.64
0.0025 - 0.0025	0.35	4.74

Numerical results (isotropic, residual-based, explicit err. est.)



$h_1 - h_2$	error	ei	$h_1 - h_2$	error	ei
0.01 - 0.01	1.36	4.71	0.005 - 0.04	0.65	3.2
0.005 - 0.005	0.69	4.64	0.0025 - 0.02	0.33	13.4
0.0025 - 0.0025	0.35	4.74	0.00125 - 0.01	0.16	13.6

A posteriori error estimators : example 2

- Zienkiewicz-Zhu (ZZ) error estimator (post-processing) : From ∇u_h , compute values at nodes $\rightarrow Gu_h$.



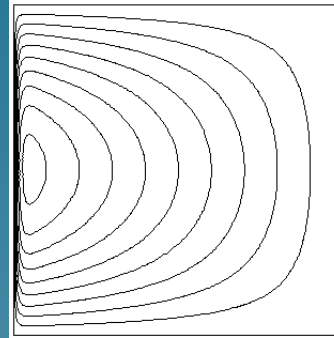
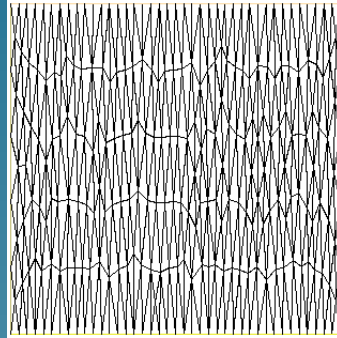
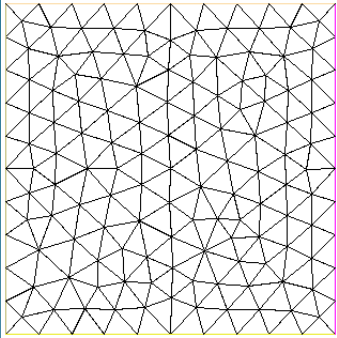
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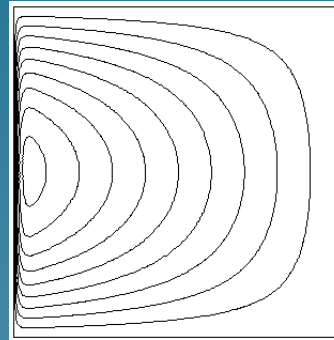
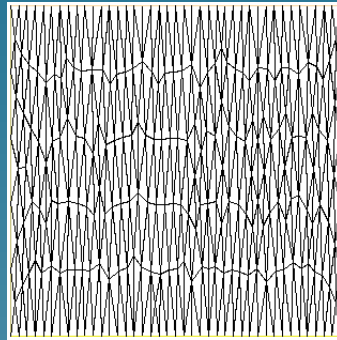
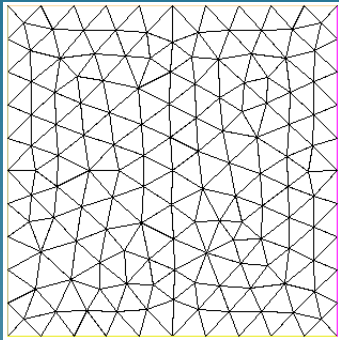


- Then $\eta^{ZZ} = \left(\int_{\Omega} |\nabla u_h - Gu_h|^2 \right)^{1/2}$ is asymptotically exact on parallel meshes (Rodriguez NMPDE 1994, Ainsworth Oden CMAME 1997) .

Numerical results (Zienkiewicz-Zhu)

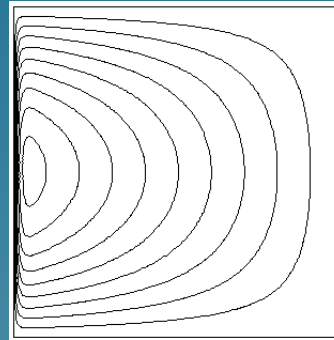
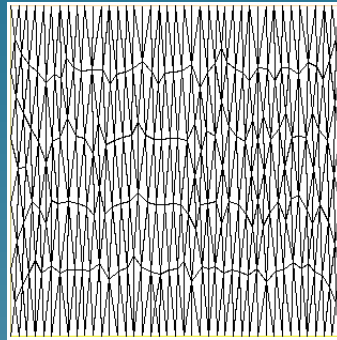
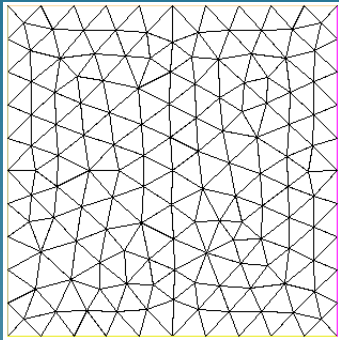


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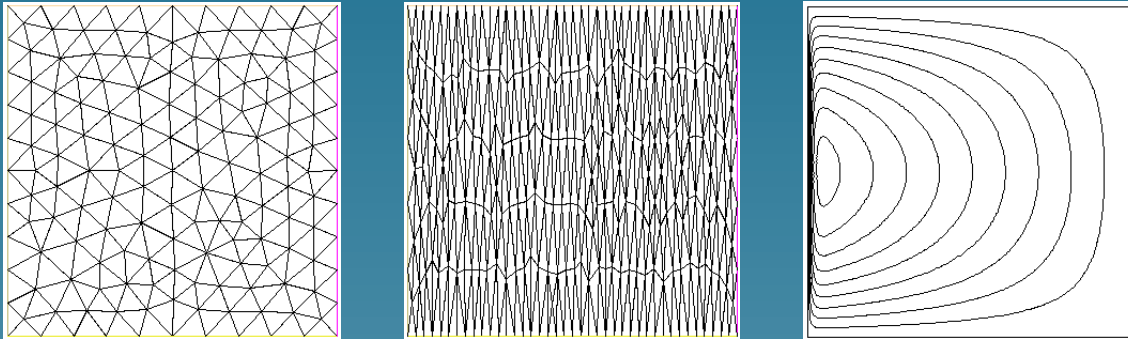
$h1 - h2$	error	ei
0.01 - 0.01	1.36	0.81
0.005 - 0.005	0.69	0.92
0.0025 - 0.0025	0.35	0.97

Numerical results (Zienkiewicz-Zhu)



$h1 - h2$	error	ei	$h1 - h2$	error	ei
0.01 - 0.01	1.36	0.81	0.005 - 0.04	0.65	0.94
0.005 - 0.005	0.69	0.92	0.0025 - 0.02	0.33	0.98
0.0025 - 0.0025	0.35	0.97	0.00125 - 0.01	0.16	0.99

Numerical results (Zienkiewicz-Zhu)



$h1 - h2$	error	ei	$h1 - h2$	error	ei
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0.0025 - 0.0025	0.35	0.97	0.00125 - 0.01	0.16	0.99

- Open question : why is ZZ asymptotically exact on some non-parallel meshes ?

Anisotropic, a posteriori error estimators

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- $G_K(e) = \begin{pmatrix} \int_K \left(\frac{\partial e}{\partial x_1} \right)^2 & \int_K \frac{\partial e}{\partial x_1} \frac{\partial e}{\partial x_2} \\ \int_K \frac{\partial e}{\partial x_1} \frac{\partial e}{\partial x_2} & \int_K \left(\frac{\partial e}{\partial x_2} \right)^2 \end{pmatrix}$

Anisotropic, a posteriori error estimators

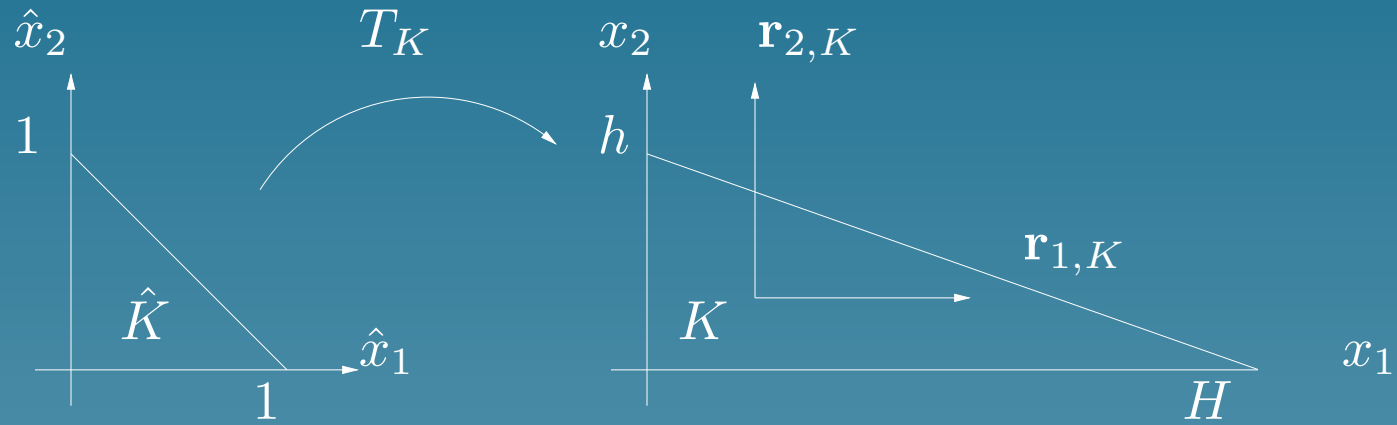
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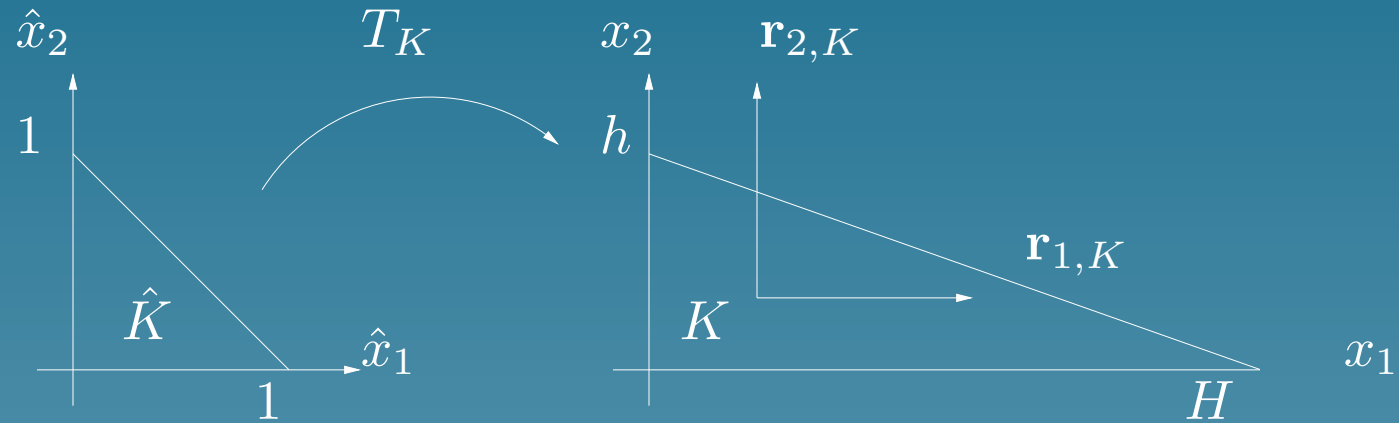
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- $\lambda_{1,K}$? $\lambda_{2,K}$? $\mathbf{r}_{1,K}$? $\mathbf{r}_{2,K}$? How to approach $G_K(e)$?

Anisotropic interpolation estimates (Formaggia Perotto, Numer. Math. 2001)

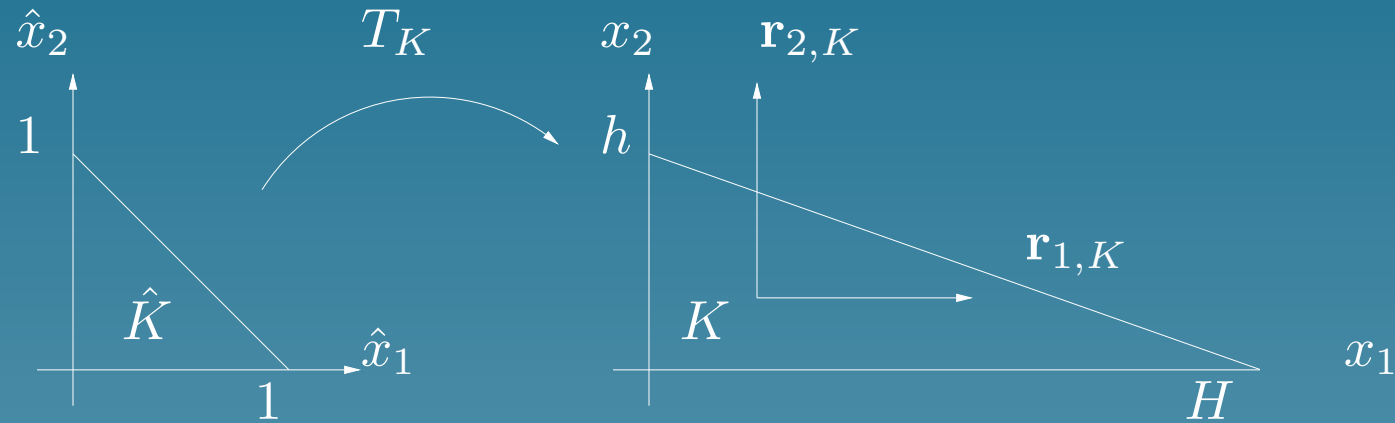


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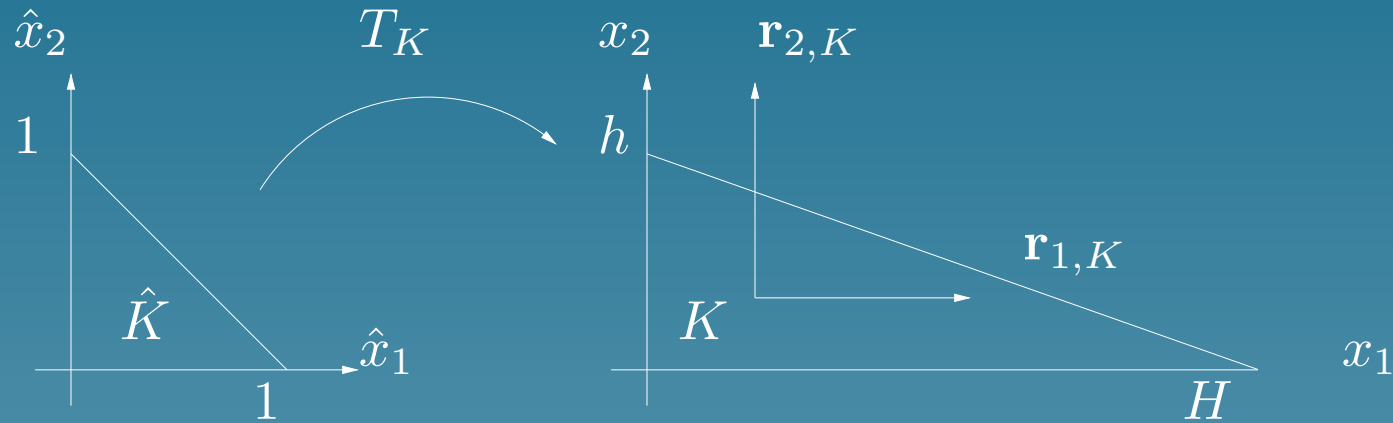
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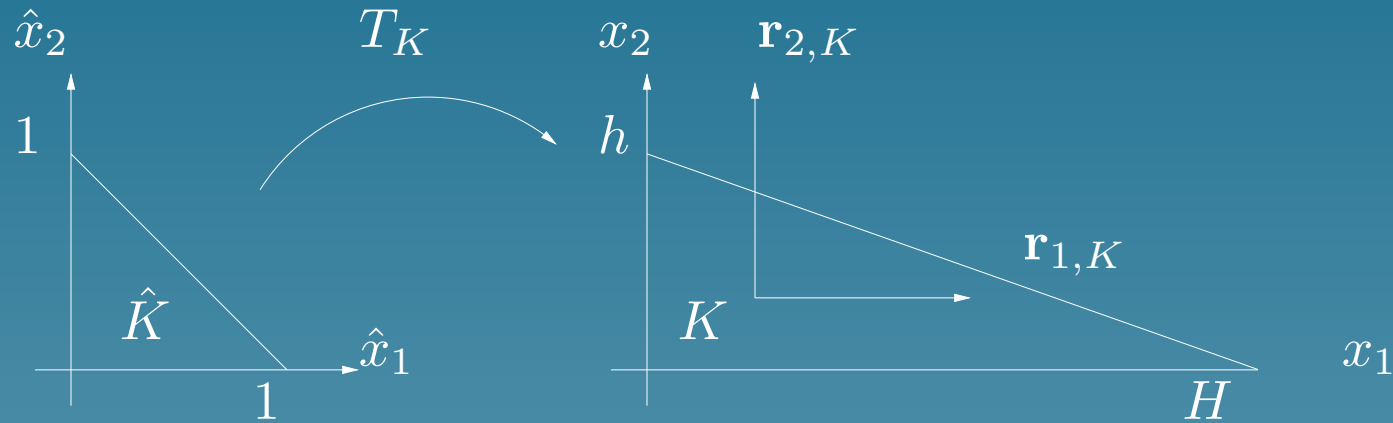
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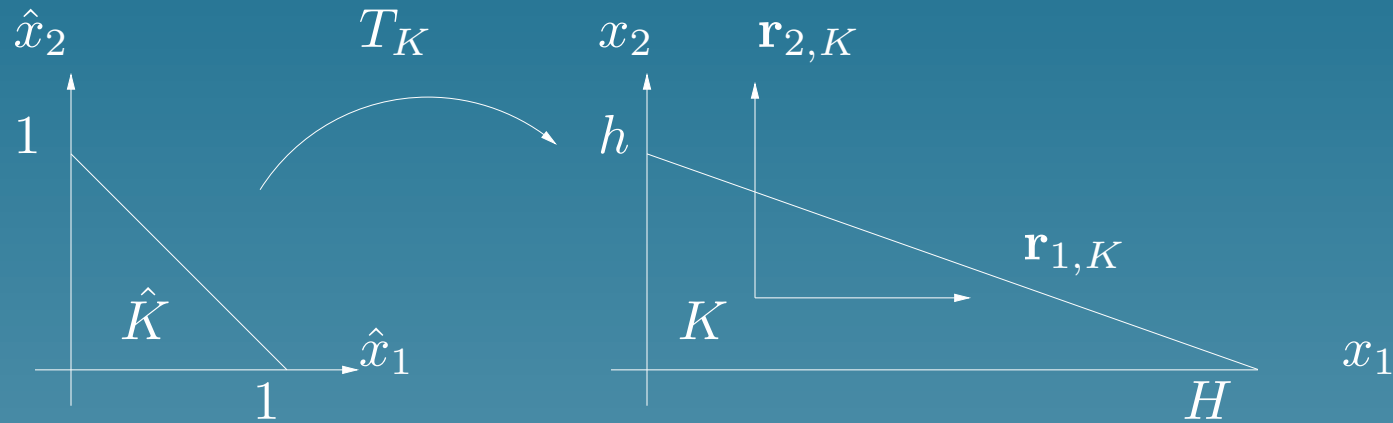
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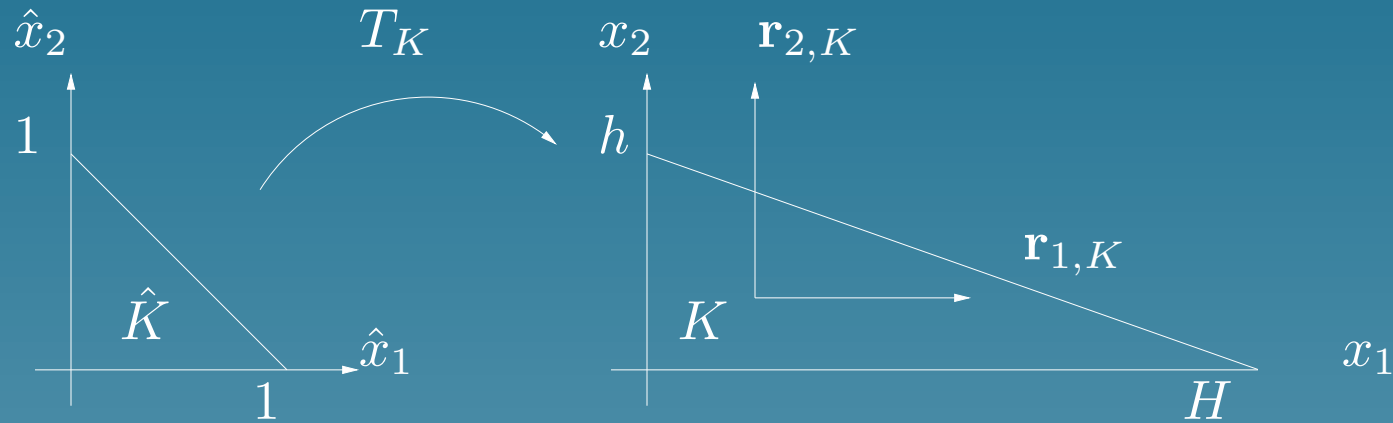
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Anisotropic, a posteriori error estimates

- Recall that

$$\int_{\Omega} |\nabla e|^2 \leq C \sum_{K \in \mathcal{T}_h} \left(\|f + \Delta u_h\|_{L^2(K)} + \frac{1}{2\lambda_{2,K}^{1/2}} \left\| \left[\frac{\partial u_h}{\partial n} \right] \right\|_{L^2(\partial K)} \right) \\ \times \left(\lambda_{1,K}^2 \left(\mathbf{r}_{1,K}^T G_K(e) \mathbf{r}_{1,K} \right) + \lambda_{2,K}^2 \left(\mathbf{r}_{2,K}^T G_K(e) \mathbf{r}_{2,K} \right) \right)^{1/2}.$$

- How to approach $G_K(e) = \begin{pmatrix} \int_K \left(\frac{\partial e}{\partial x_1} \right)^2 & \int_K \frac{\partial e}{\partial x_1} \frac{\partial e}{\partial x_2} \\ \int_K \frac{\partial e}{\partial x_1} \frac{\partial e}{\partial x_2} & \int_K \left(\frac{\partial e}{\partial x_2} \right)^2 \end{pmatrix} ?$

Anisotropic, a posteriori error estimates

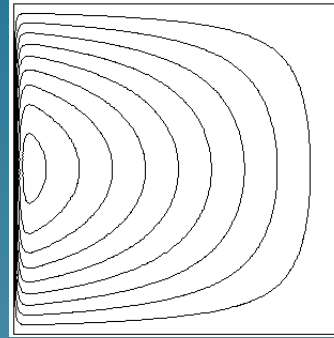
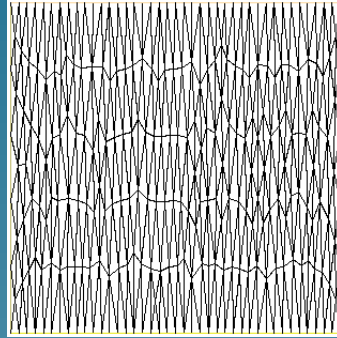
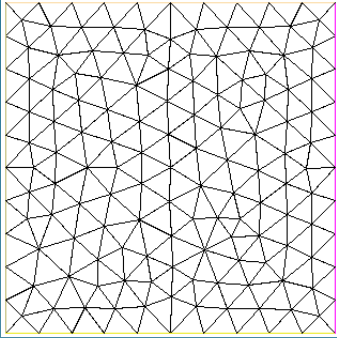
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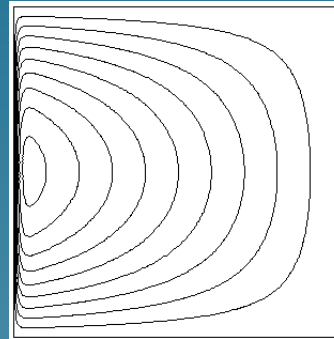
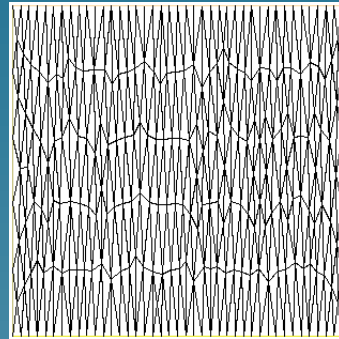
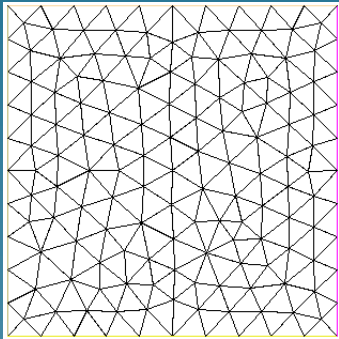
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- Zienkiewicz-Zhu (ZZ) error estimator $\int_K \left(\frac{\partial e}{\partial x_1} \right)^2 \rightarrow \int_K \left(\frac{\partial u_h}{\partial x_1} - (Gu_h)_1 \right)^2$.

An anisotropic error indicator based on ZZ error estimator

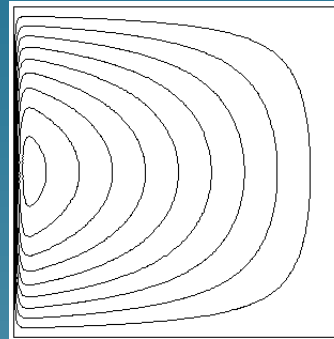
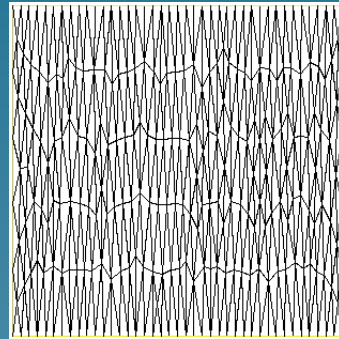
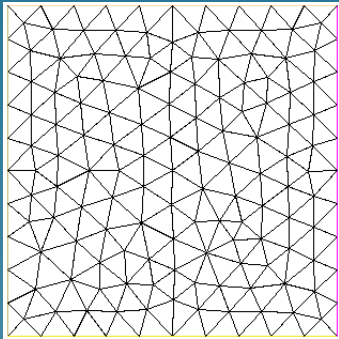


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An anisotropic error indicator based on ZZ error estimator

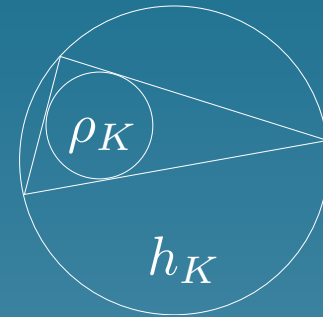


$h1 - h2$	error	ei	$h1 - h2$	error	ei
0.01 - 0.01	1.36	2.22	0.005 - 0.04	0.65	2.43
0.005 - 0.005	0.69	2.42	0.0025 - 0.02	0.33	2.62
0.0025 - 0.0025	0.35	2.54	0.00125 - 0.01	0.16	2.68

Anisotropic interpolation estimates (Formaggia Perotto, Numer. Math. 2001)

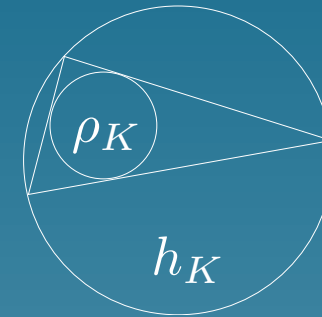
- Isotropic Clément

$$\|v - R_h v\|_{L^2(K)}^2 \leq C \left(\frac{h_K}{\rho_K} \right) h_K^2 \|\nabla v\|_{L^2(\Delta K)}^2$$

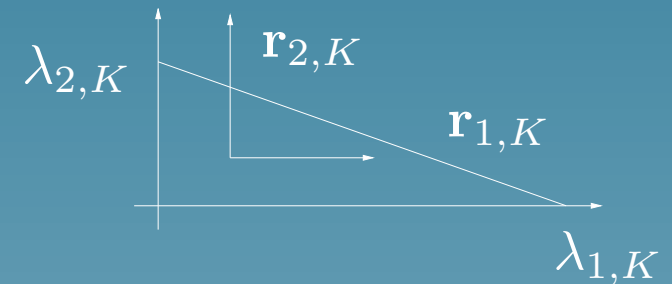


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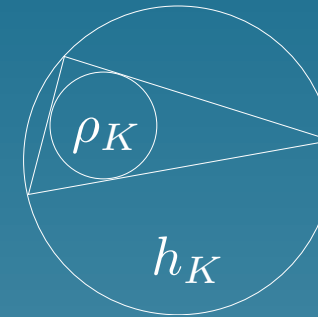


- Anisotropic Clément $\|v - R_h v\|_{L^2(K)} \leq C(\hat{K}) \left(\lambda_{1,K}^2 \left(\mathbf{r}_{1,K}^T G_K(v) \mathbf{r}_{1,K} \right) + \lambda_{2,K}^2 \left(\mathbf{r}_{2,K}^T G_K(v) \mathbf{r}_{2,K} \right) \right)$

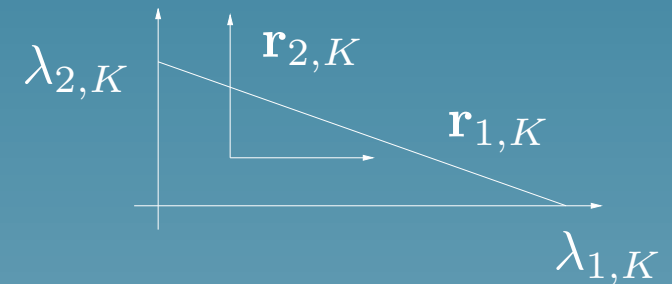


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- Optimality : $v(x_2)$, $\mathbf{r}_{1,K} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$, $\mathbf{r}_{2,K} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$, $\lambda_{1,K} = 1$, $\lambda_{2,K} = h$.

Anisotropic, adaptive finite elements

- Goal : find \mathcal{T}_h s.t. $0.75 TOL \leq \frac{\left(\sum_{K \in \mathcal{T}_h} \eta_K^2\right)^{1/2}}{\left(\int_{\Omega} |\nabla u_h|^2\right)^{1/2}} \leq 1.25 TOL$.

Anisotropic, adaptive finite elements

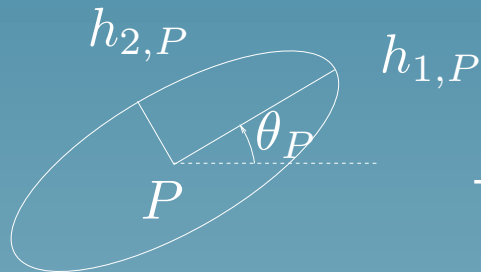
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- with $\eta_K^4 = \left(\|f + \Delta u_h\|_{L^2(K)} + \frac{1}{2\lambda_{2,K}^{1/2}} \left\| \left[\frac{\partial u_h}{\partial n} \right] \right\|_{L^2(\partial K)} \right)^2$
 $\times \left(\lambda_{1,K}^2 \left(\mathbf{r}_{1,K}^T G_K(e) \mathbf{r}_{1,K} \right) + \lambda_{2,K}^2 \left(\mathbf{r}_{2,K}^T G_K(e) \mathbf{r}_{2,K} \right) \right)$.

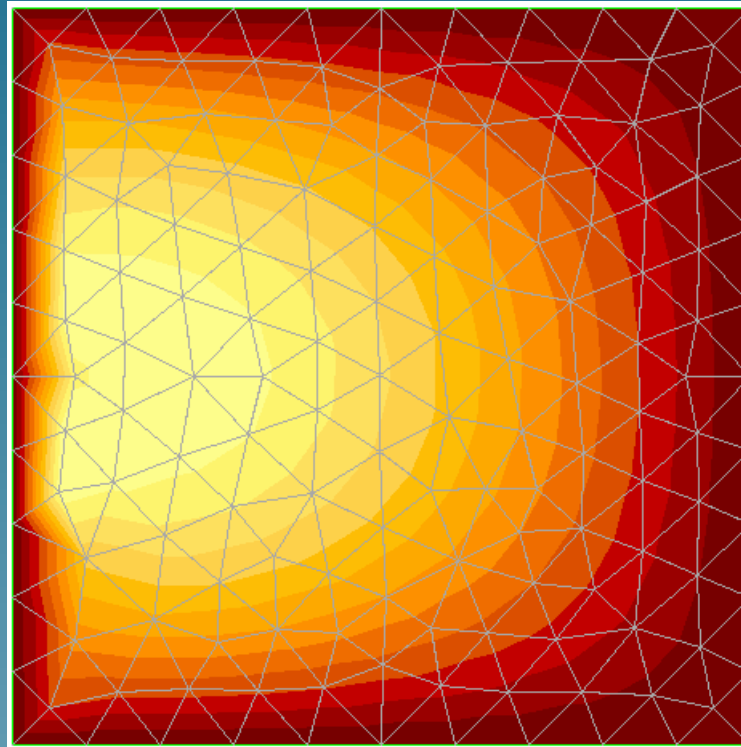
Anisotropic, adaptive finite elements

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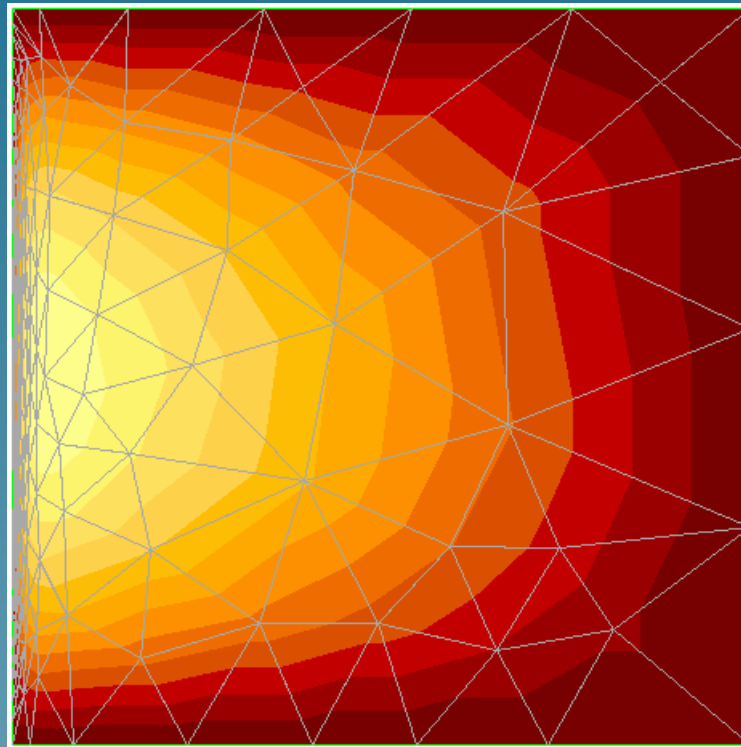
- The BL2D mesh generator (INRIA, Borouchaki, Laug)

Adaptive meshes for the Laplace problem



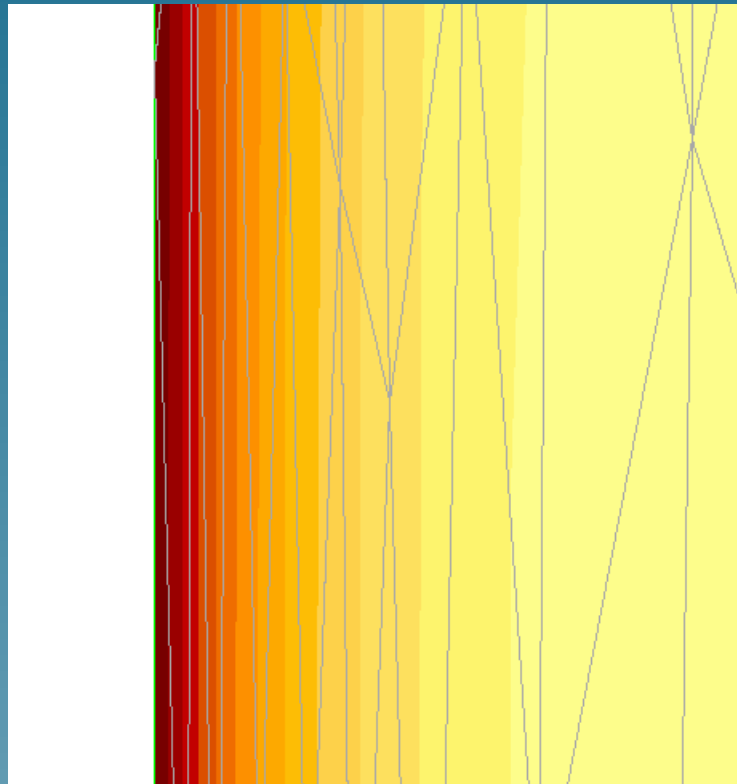
Initial 10×10 mesh

Adaptive meshes for the Laplace problem



$TOL = 0.25$: adapted mesh after 30 mesh generations, 145 vertices

Adaptive meshes for the Laplace problem



$TOL = 0.25$: adapted mesh after 30 mesh generations, 145 vertices (zoom)

Advection-diffusion

- Find $u : \Omega \rightarrow \mathbb{R}$ such that

$$\begin{aligned} -\epsilon \Delta u + \mathbf{a} \cdot \nabla u &= f && \text{in } \Omega, \\ u &= 0 && \text{on } \partial\Omega. \end{aligned}$$

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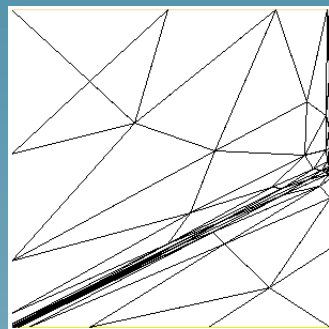
- Continuous, piecewise linear, stabilized finite elements
- Question : what is the stabilization coefficient on strongly anisotropic meshes ?

Advection-diffusion

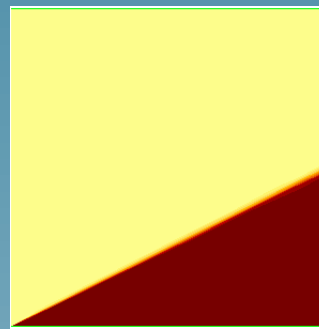
- Find $u : \Omega \rightarrow \mathbb{R}$ such that

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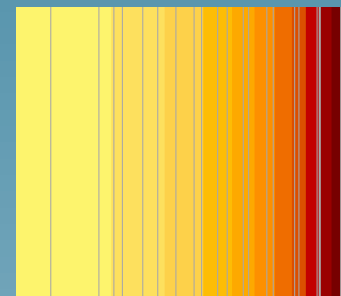
- Continuous, piecewise linear, stabilized finite elements
- Question : what is the stabilization coefficient on strongly anisotropic meshes ?
- $\Omega = (0, 1)^2$, $\epsilon = 0.0001$, $\mathbf{a} = (2, 1)^T$, $f = 0$, 241 vertices, asp. ratio $\geq 10^4$.



Mesh



Isovalues



Zoom

The heat equation

- Find $u : \Omega \times (0, T) \rightarrow \mathbb{R}$ such that

$$\frac{\partial u}{\partial t} - \Delta u = f \quad \text{in } \Omega \times (0, T),$$

plus initial and boundary conditions.

The heat equation

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plus initial and boundary conditions.

- For $n = 1, \dots, N$, find $u_h^n \in V_h$ such that, for all $v \in V_h$

$$\frac{1}{\tau} \int_{\Omega} (u_h^n - u_h^{n-1}) v dx + \int_{\Omega} \nabla u_h^n \cdot \nabla v dx = \int_{\Omega} f^n v dx.$$

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- $u_{h\tau}(x, t) = \frac{t - t^{n-1}}{\tau} u_h^n(x) + \frac{t^n - t}{\tau} u_h^{n-1}(x)$ for all $t^{n-1} \leq t \leq t^n$.

The heat equation

- Error : $e = u - u_{h\tau}, \int_0^T \int_{\Omega} |\nabla e|^2.$

The heat equation

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$$\sum_{n=1}^N \sum_{K \in \mathcal{T}_h} \int_{t^{n-1}}^{t^n} \left(\left\| f - \frac{\partial u_{h\tau}}{\partial t} + \Delta u_{h\tau} \right\|_{L^2(K)} + \frac{1}{2\lambda_{2,K}^{1/2}} \left\| \left[\frac{\partial u_{h\tau}}{\partial n} \right] \right\|_{L^2(\partial K)} \right) \left(\lambda_{1,K}^2 \left(\mathbf{r}_{1,K}^T G_K(e) \mathbf{r}_{1,K} \right) + \lambda_{2,K}^2 \left(\mathbf{r}_{2,K}^T G_K(e) \mathbf{r}_{2,K} \right) \right)^{1/2}.$$

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- | h | τ | error | ei |
|---------|-----------|-------|------|
| 0.05 | 0.1 | 3.48 | 5.25 |
| 0.025 | 0.025 | 1.68 | 2.09 |
| 0.0125 | 0.00625 | 0.82 | 2.57 |
| 0.00625 | 0.0015625 | 0.42 | 2.66 |

The heat equation

- Adaptive finite elements : $0.75 \text{ TOL} \leq \frac{\left(\sum_{n=1}^N \sum_{K \in \mathcal{T}_h} \eta_{n,K}^2 \right)^{1/2}}{\left(\int_0^T \int_{\Omega} |\nabla u_{h\tau}|^2 \right)^{1/2}} \leq 1.25 \text{ TOL}.$

The heat equation

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- Sufficient condition :

$$0.75^2 \text{ TOL}^2 \int_{t^{n-1}}^{t^n} \int_K |\nabla u_{h\tau}|^2 \leq \eta_{n,K}^2 \leq 1.25^2 \text{ TOL}^2 \int_{t^{n-1}}^{t^n} \int_K |\nabla u_{h\tau}|^2$$

The heat equation

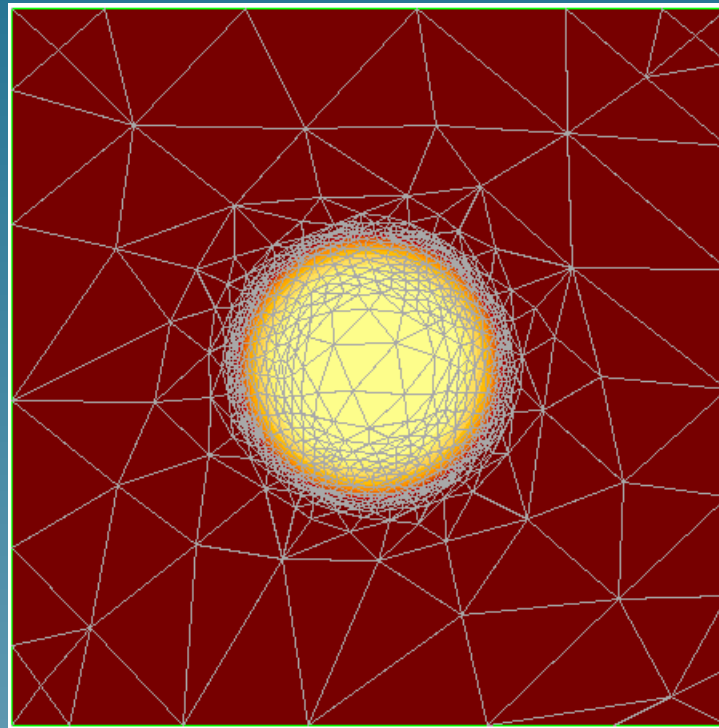
- Adaptive finite elements : $0.75 \, TOL \leq \frac{\left(\sum_{n=1}^N \sum_{K \in \mathcal{T}_h} \eta_{n,K}^2 \right)^{1/2}}{\left(\int_0^T \int_{\Omega} |\nabla u_{h\tau}|^2 \right)^{1/2}} \leq 1.25 \, TOL.$

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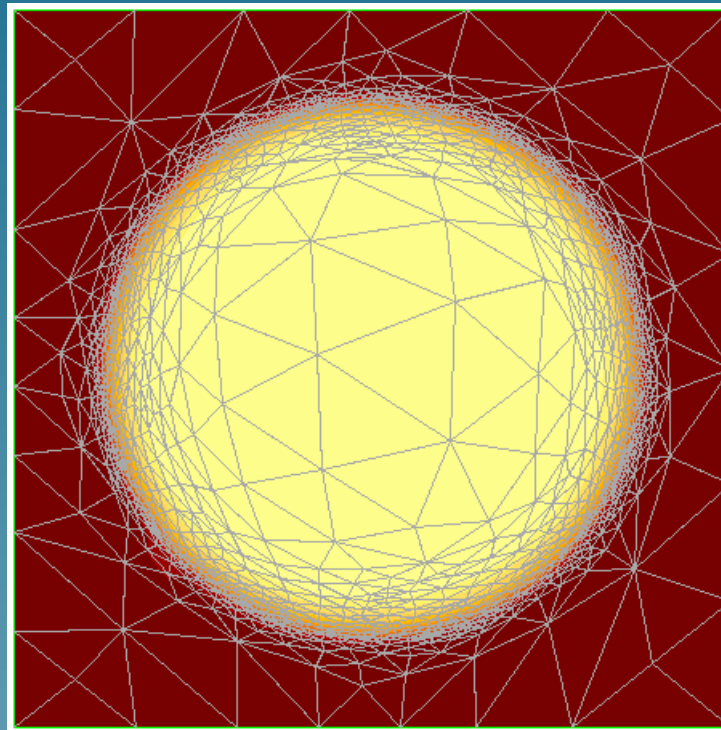
- | TOL | τ | error | ei |
|--------|-----------|-------|------|
| 0.25 | 0.025 | 0.55 | 2.56 |
| 0.125 | 0.00625 | 0.26 | 2.86 |
| 0.0625 | 0.0015625 | 0.13 | 2.88 |

Adaptive meshes for the heat problem



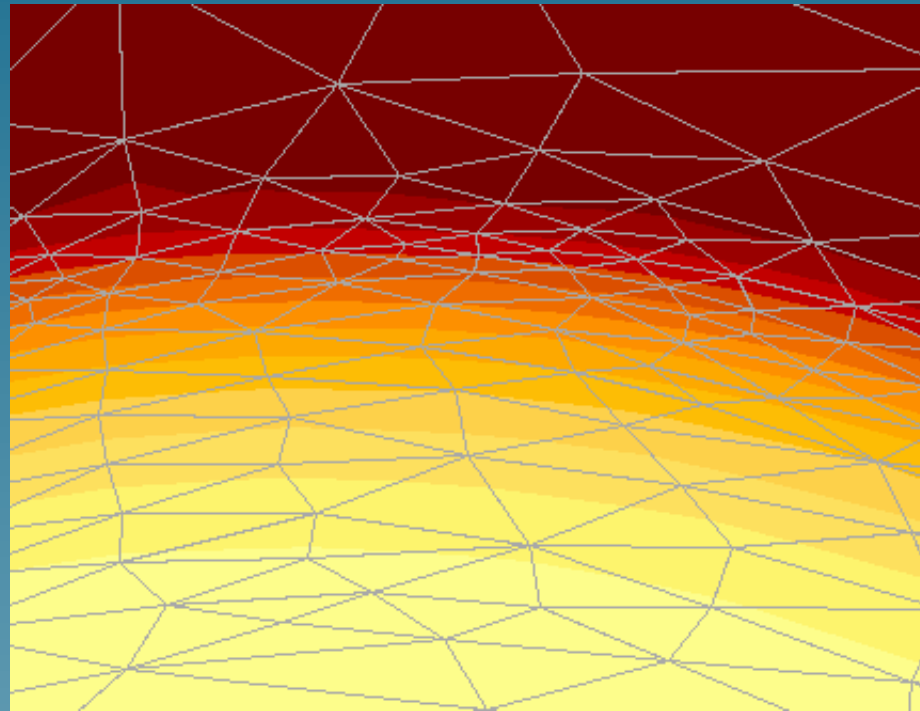
$TOL = 0.25$, 40 times steps : first time step

Adaptive meshes for the heat problem



$TOL = 0.25$, 40 times steps : last time step

Adaptive meshes for the heat problem



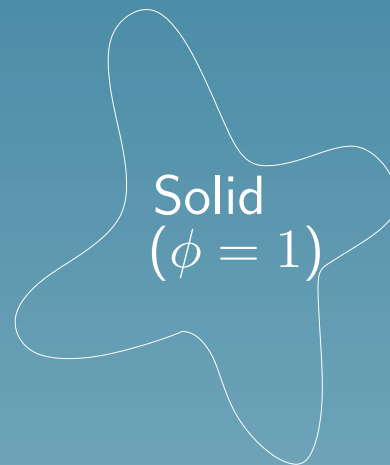
$TOL = 0.25$, 40 times steps : last time step (zoom)

Strongly nonlinear parabolic problems : Solidification of a binary alloy

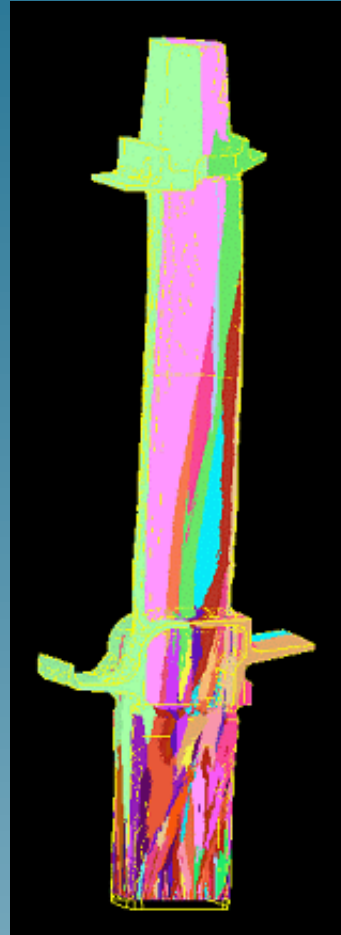
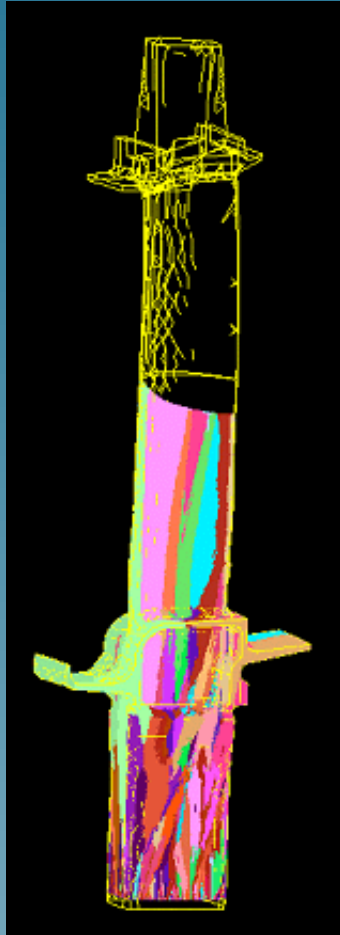
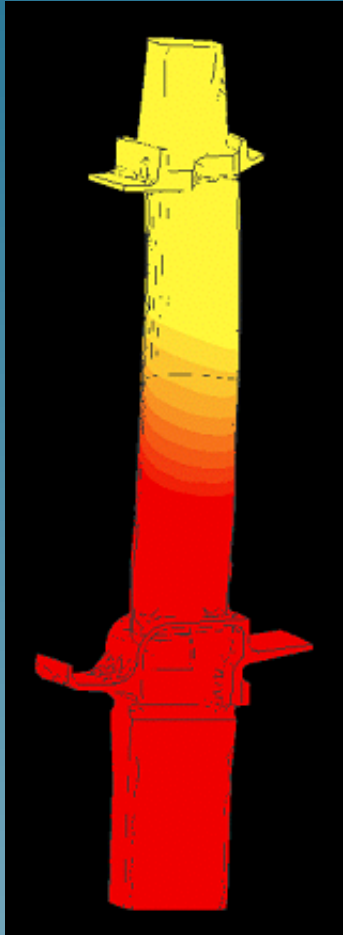
- with Lab. Métallurgie Physique, M. Rappaz A. Jacot.
- Phase field model. Find $c, \phi : \Omega \times (0, T) \rightarrow \mathbb{R}$ such that

$$\frac{1}{M} \frac{\partial \phi}{\partial t} - \operatorname{div} (A(\nabla \phi) \nabla \phi) - S(c, \phi) = 0 \quad \text{in } \Omega \times (0, T),$$

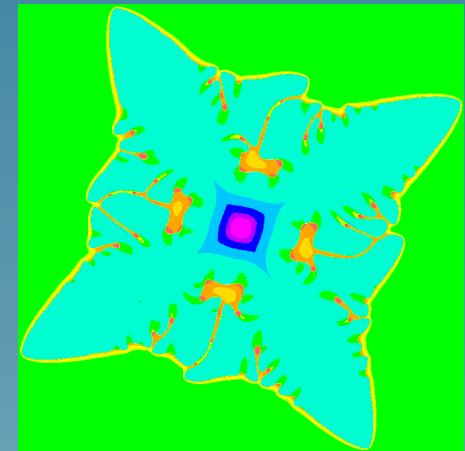
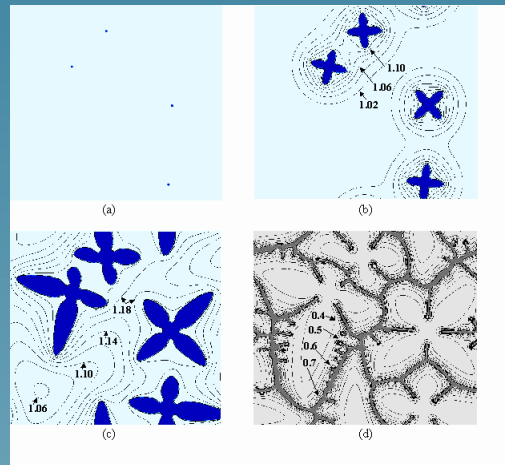
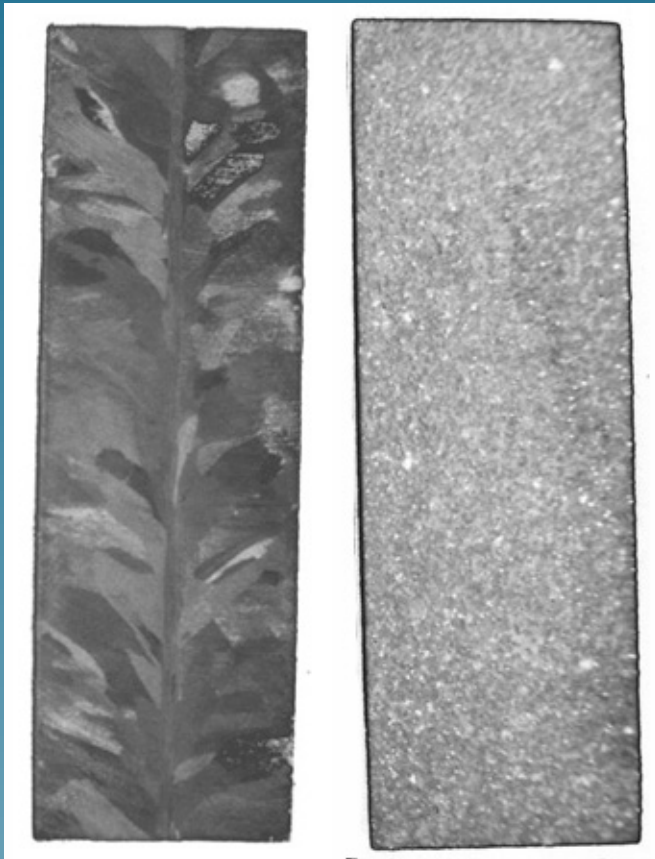
$$\frac{\partial c}{\partial t} - \operatorname{div} (D_1(\phi) \nabla c + D_2(c, \phi) \nabla \phi) = 0 \quad \text{in } \Omega \times (0, T).$$



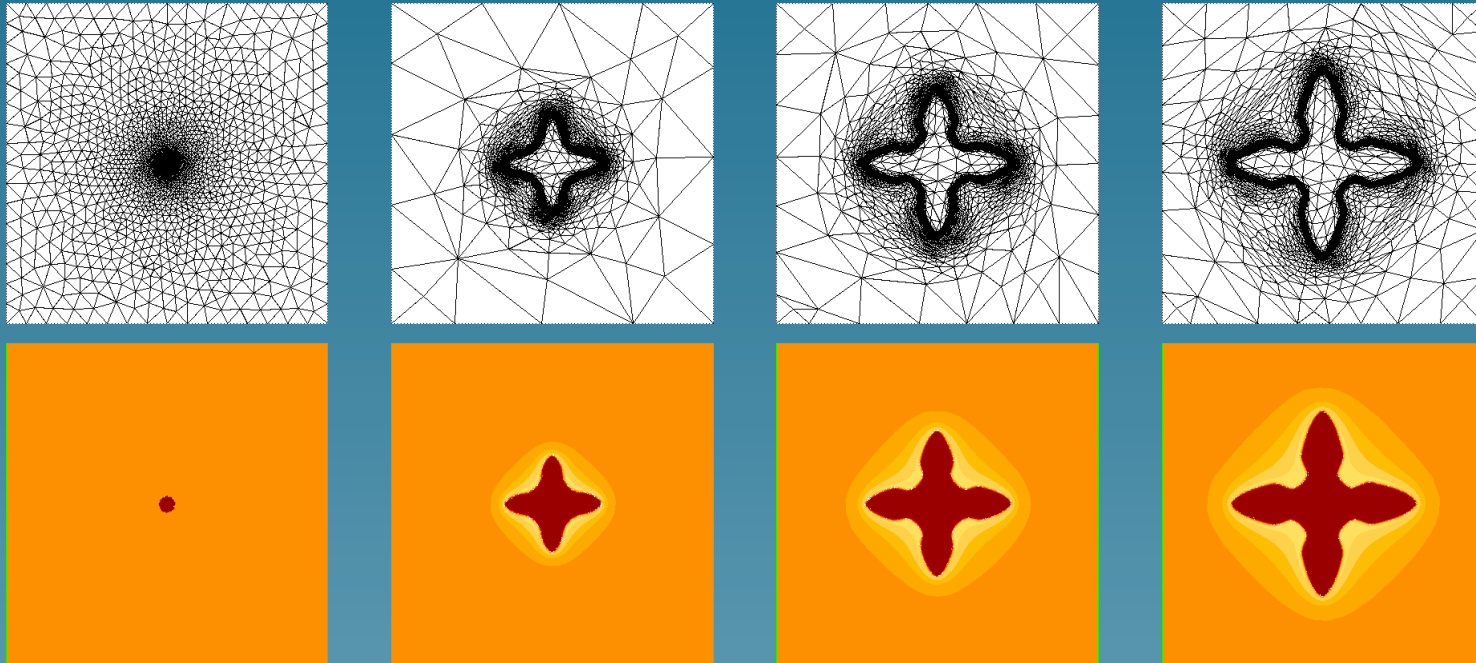
Solidification : from macro to meso scale



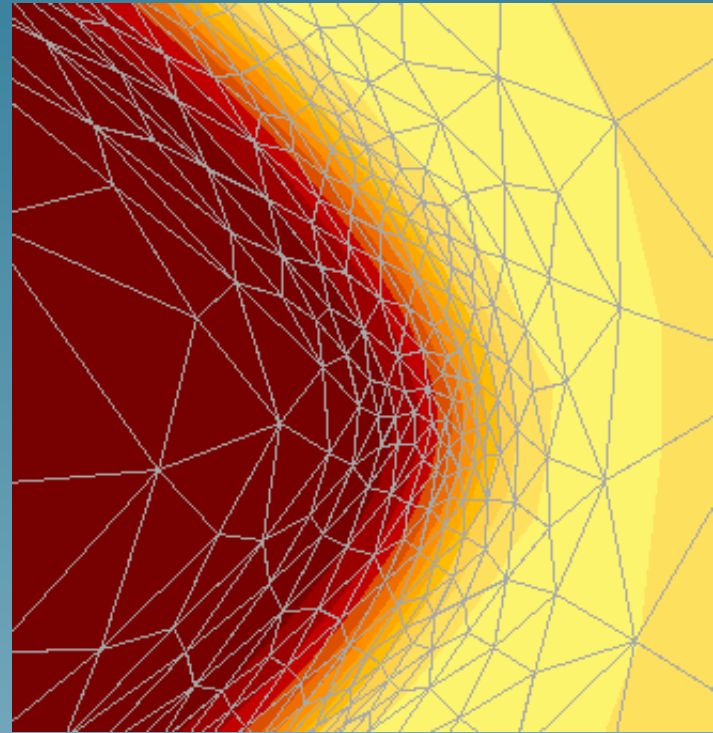
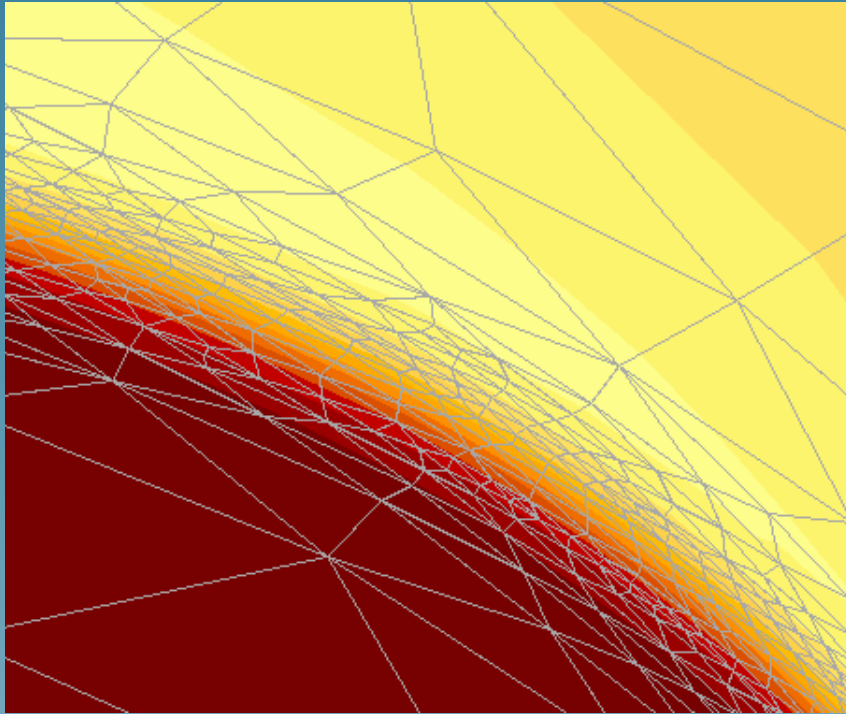
Solidification : from meso to micro scale



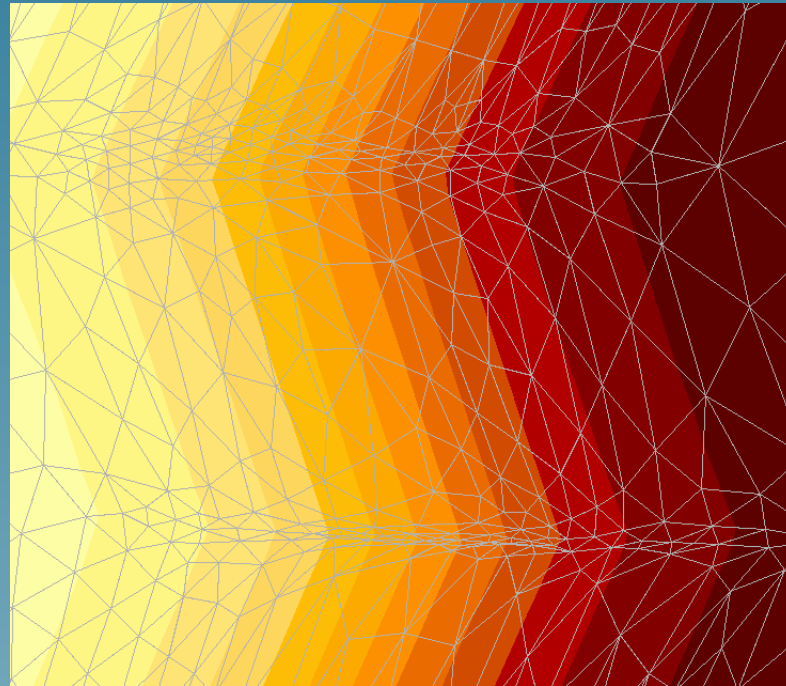
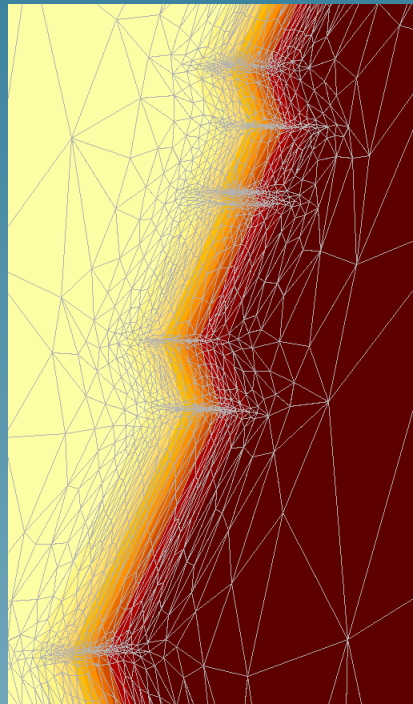
Phase field with low anisotropy



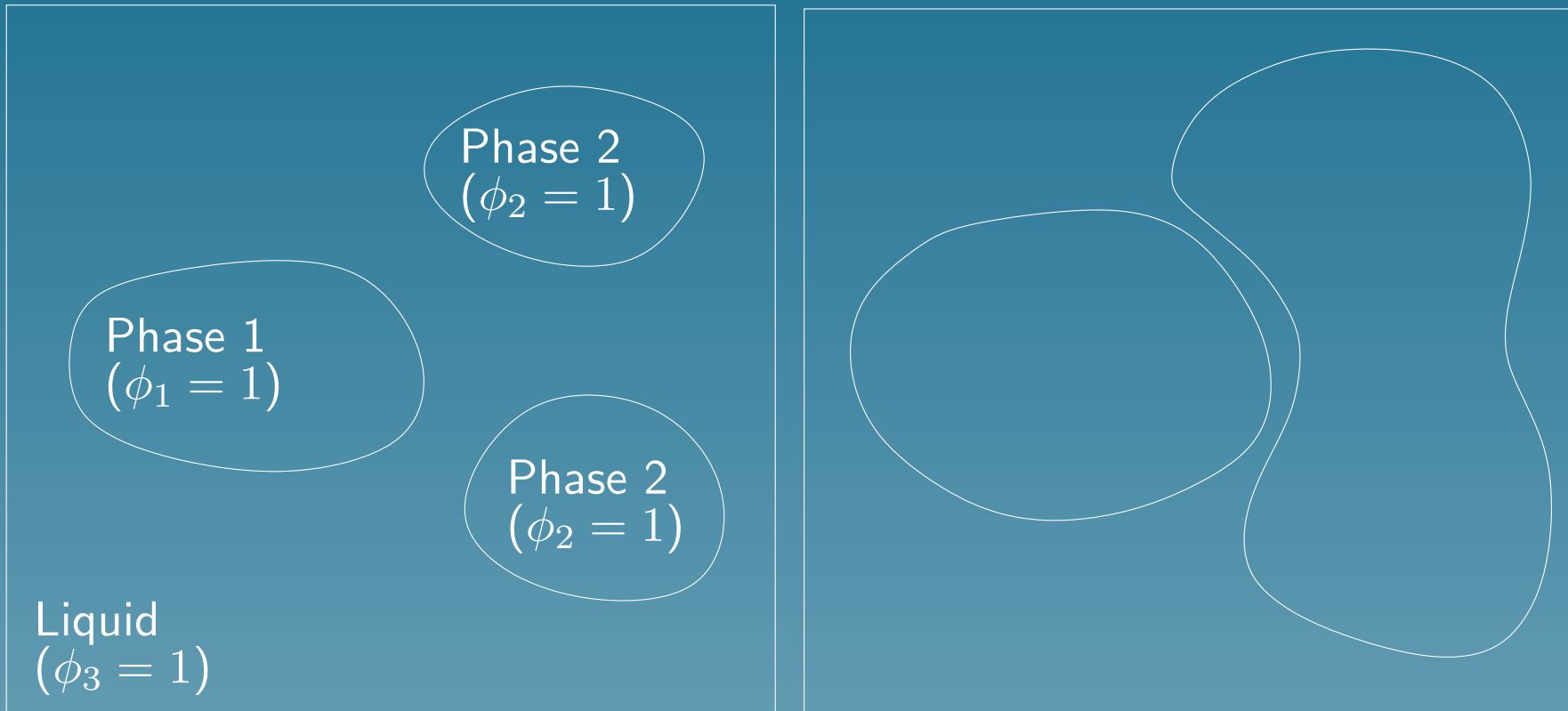
Phase field with low anisotropy



Phase field with strong anisotropy

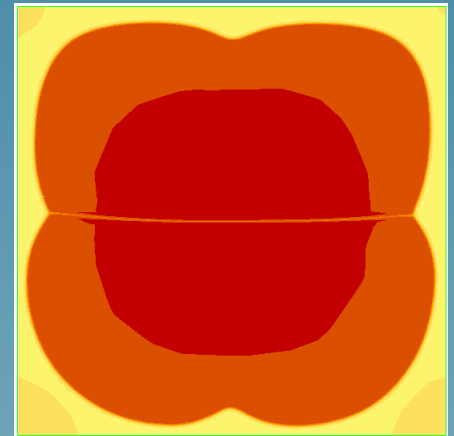
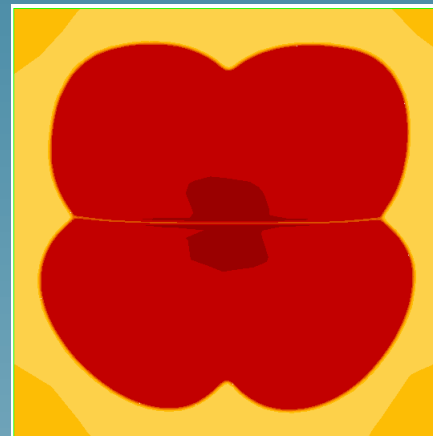
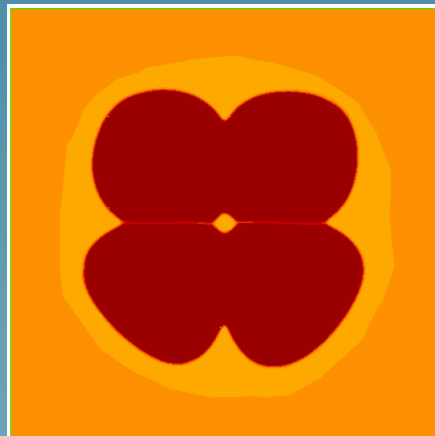
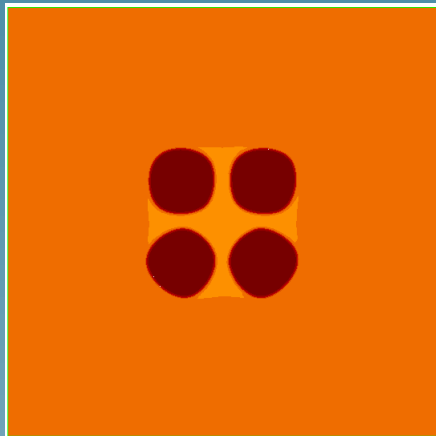
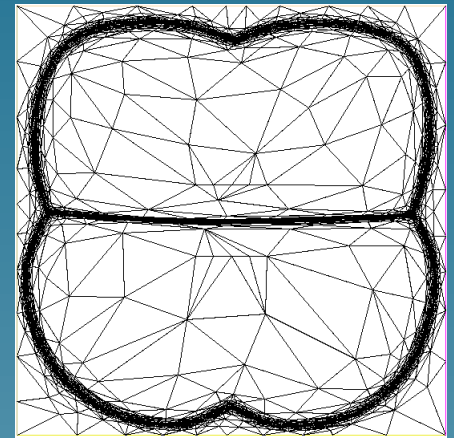
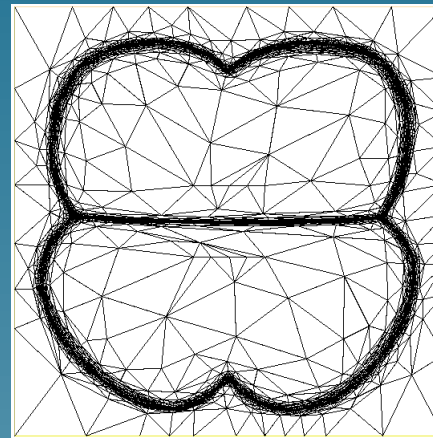
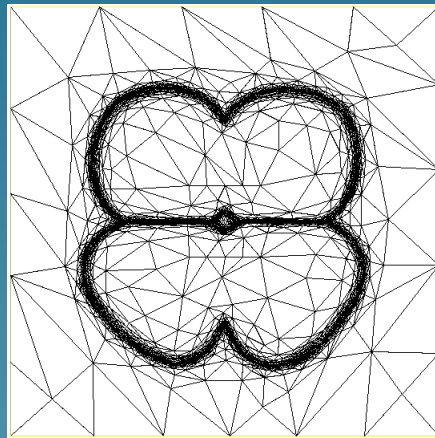
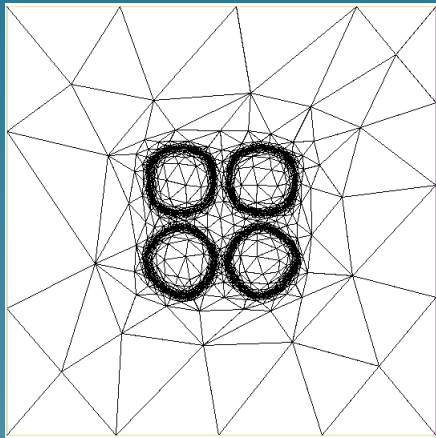


The multiphase field model

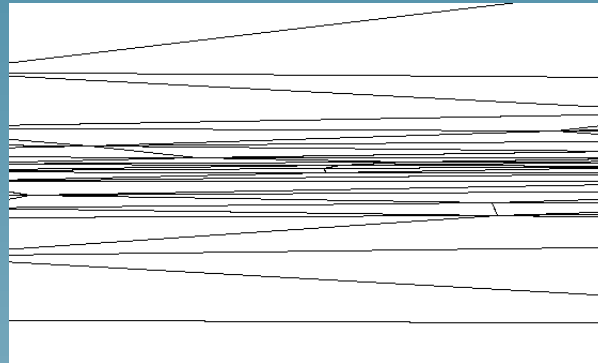
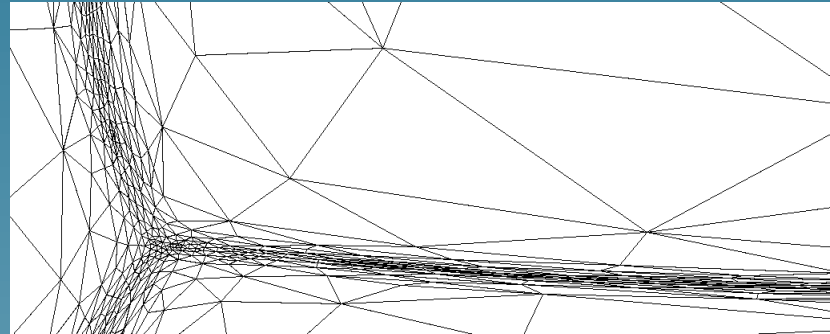
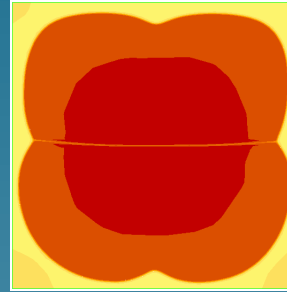
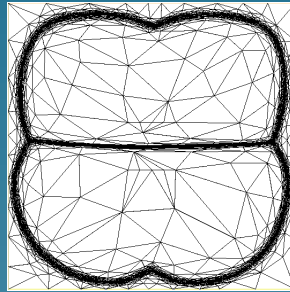


- Unknowns : ϕ_1 , ϕ_2 , ϕ_3 , λ (Lagrange multiplier $\phi_1 + \phi_2 + \phi_3 = 1$) and c .

The multiphase field model



The multiphase field model



Conclusions and perspectives

- Use of anisotropic, adaptive grids : same accuracy with fewer vertices.
- Robustness ? Lower bound ? ZZ ?
- Systems of p.d.e ? (Stokes)
- Optimal control
- Anisotropic meshes in 3D ?