

¹LIMSI-CNRS, Orsay, France
²Texas Institute for Computational and Applied Mathematics,
The University of Texas at Austin

Mathematical Aspects of Computational Fluid Dynamics
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¹J.-L. Guermund
Collaborator: S. Prudhomme²

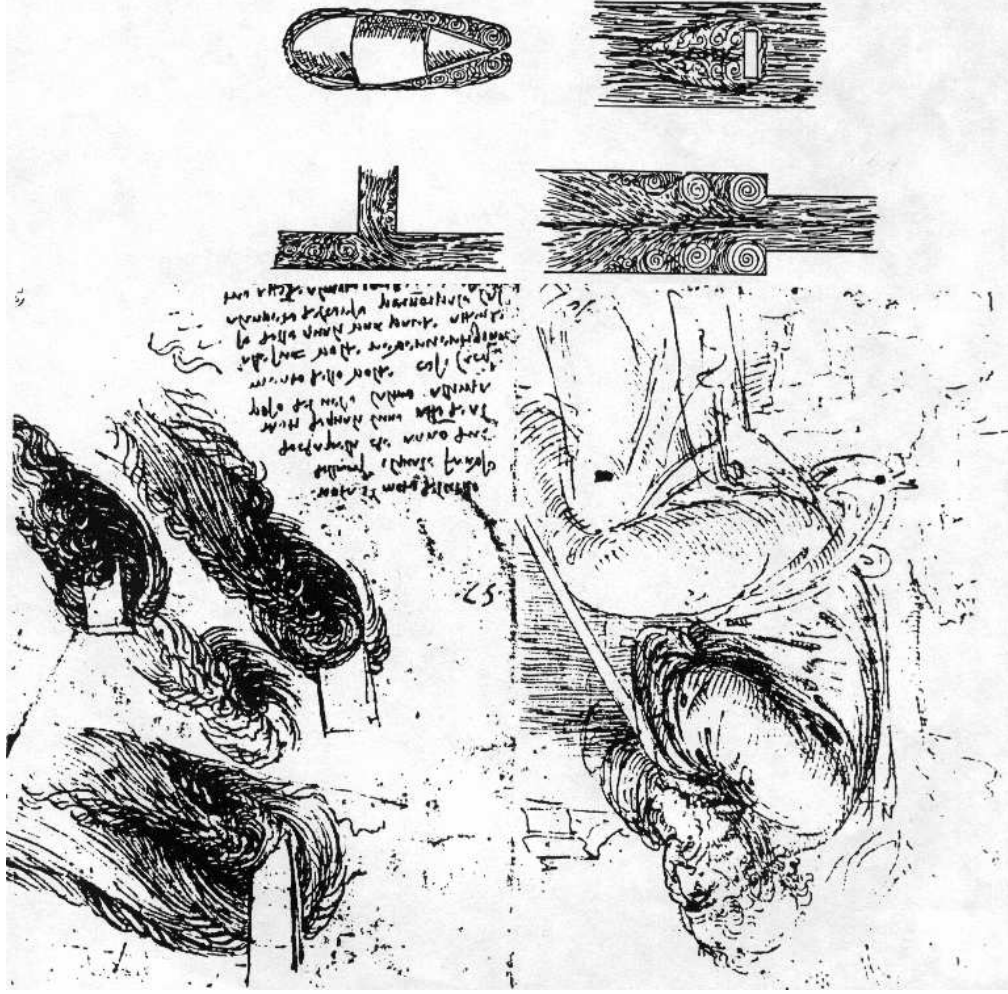
**A HYPERVISCOSITY SPECTRAL
LARGE EDDY SIMULATION MODEL
FOR TURBULENT FLOWS**

THE NAVIER-STOKES EQUATIONS

Overview

- Part I: Basic facts about the Navier–Stokes equations
- Part II: Proposition of a paradigm for LES
- Part III: The hyperviscosity model
- Part IV: The spectral hyperviscosity approximation

**BASIC FACTS
ABOUT THE
NAVIER-STOKES
EQUATIONS**



THE NAVIER-STOKES EQUATIONS

- u : velocity, p : pressure
- Ω is the fluid domain

$$\left. \begin{aligned} \partial_t u + u \cdot \nabla u + \Delta p - \nu \Delta^2 u &= f & \text{in } \Omega \\ \Delta \cdot u &= 0 & \text{in } \Omega, \\ n|_{\Gamma} &= 0 & \text{or } n \text{ is periodic,} \\ n|_{t=0} &= n_0, \end{aligned} \right\}$$

- n_0 is the initial data
- f a source term.
- ρ is chosen equal to unity.

EXISTENCE AND UNIQUENESS

- J. Leray (1934): introduces the notion of **turbulent solution**.
A turbulent solution is a weak solution in $L^2(0, T; H^1(\Omega)) \cup L^\infty(0, T; L^2(\Omega))$.

- J. Leray uses **mollification** to prove existence:
 $\phi \in D(\mathbb{R}^3), \phi \geq 0, \int_{\mathbb{R}^3} \phi = 1, \phi^\varepsilon(x) = \int \phi\left(\frac{\cdot}{\varepsilon}\right) \cdot$

$$\partial_t u^\varepsilon + \operatorname{div}(u^\varepsilon * u^\varepsilon) + \Delta u^\varepsilon - \nu \Delta^2 u^\varepsilon = f$$

- E. Hopf (1951) *et al.* uses the **Galerkin technique** to prove existence.

The question of the existence of **classical solutions** for long times is open. This question is linked to the **question of uniqueness** of turbulent solutions.

⇒ Clay Institute 1M\$ prize.

SUITABLE WEAK SOLUTION

V. Shaffer (1976) introduces **suitable weak solutions**:

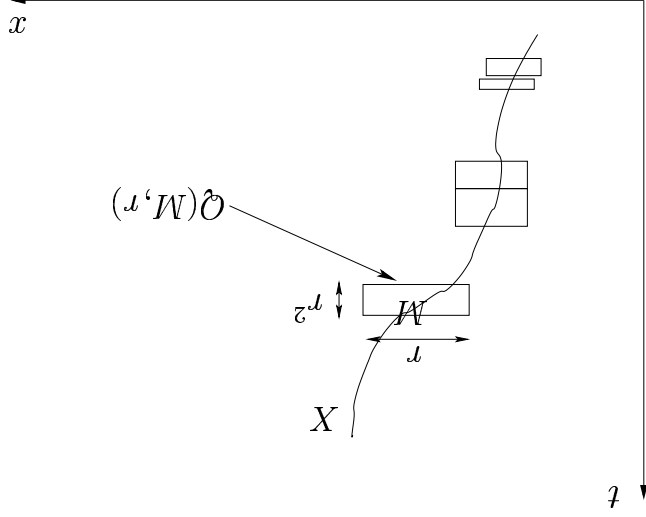
DEFINITION: A NS weak solution is said to be **suitable** (or **dissipative**) iff

$$\partial_t \left(\frac{1}{2} n^2 \right) + \Delta \cdot (n \frac{1}{2} n^2 + p) - \nu \Delta^2 \left(\frac{1}{2} n^2 \right) + \nu (\Delta n)^2 - f \cdot n \leq 0.$$

THEOREM: (Caffarelli-Kohn-Nirenberg (1982)) The “dimension” of the set of singular points of suitable weak solutions in $\Omega \times [0, +\infty]$ is less than 1.

Best partial regularity theorem to date.

$$P_k(X) = \lim_{\delta \rightarrow 0^+} \inf \{ r_k^i \mid \Sigma \subset \cup \mathcal{O}(M_i, r_i), r_i > \delta \}$$



Singular set: S

$$S = \{(x, t) \in \Omega \times [0, T], u \notin T^\infty(V), \forall V \text{ s.t. } (x, t) \in V\}$$

Caffarelli-Kohn-Nirenberg $\Leftrightarrow P_1(S) = 0$

THEOREM: (Duchon-Robert (2000)) *The limits (as $\varepsilon \rightarrow 0_+$) of Leray-regularized NS solutions are dissipative.*

The question is **open** for Galerkin weak NS solutions.

Proof: $u^\varepsilon \rightharpoonup u$ in $L^2(H^1)$ (up to subsequences) and $u^\varepsilon \rightharpoonup u$ in $L^p(T^b)$, $1 \leq p \leq \frac{3(b-2)}{4b}$, $2 \leq b < 6$.

Test with ϕu^ε , $\phi \in \mathcal{D}(\mathcal{Q})$ (OK, since u^ε is **smooth**).

$$\int_{\mathcal{Q}} -\frac{1}{2} u^\varepsilon \partial_t \phi + \nu \Delta_2 \phi - (\phi \partial_t u^\varepsilon + u^\varepsilon \partial_2 \phi) - (\phi \partial_2 u^\varepsilon + u^\varepsilon \partial_2 \phi) + d \partial_2 u^\varepsilon + \nu \Delta_2 (\phi u^\varepsilon) - \phi \Delta_2 u^\varepsilon - f u^\varepsilon \phi = 0$$

$$u^\varepsilon \rightharpoonup u \text{ in } L^p(T^b), \nu \Delta_2 u^\varepsilon \rightharpoonup \nu \Delta_2 u$$

$$\phi u^\varepsilon \rightharpoonup \phi u \text{ in } L^4(T^3) \iff \begin{cases} u^\varepsilon \rightharpoonup u \text{ in } L^{\frac{2}{3}}(T^{\frac{3}{4}}) \\ \phi u^\varepsilon \rightharpoonup \phi u \text{ in } L^{\frac{3}{4}}(T^1) \end{cases}$$

$$\liminf_{\epsilon \rightarrow 0} \int \phi_z(n\Delta) \geq \int \phi_z(\epsilon n\Delta) \geq \int \phi_z(n\Delta) + n\Delta(n - \epsilon n) \Delta \phi \geq \int \phi_z(n\Delta) \Rightarrow$$

Periodic domain and $\Delta \cdot f = 0$

$$\Delta_2 d^\epsilon = -\Delta \cdot \Delta \cdot \Delta \cdot (\psi^\epsilon * n^\epsilon \otimes n^\epsilon) \Rightarrow$$

$$\|d^\epsilon\|_{T^2} \leq c \|\psi^\epsilon * n^\epsilon \otimes n^\epsilon\|_{T^2} \leq c \|n^\epsilon\|_{T^4} \Rightarrow \|d^\epsilon\|_{T^{\frac{3}{4}}} \leq c \|n^\epsilon\|_{T^{\frac{3}{4}}}$$

$$\left\{ \begin{array}{l} \|n^\epsilon\|_{T^{\frac{3}{4}}} \leq c \|n^\epsilon\|_{T^2} \\ \|d^\epsilon\|_{T^{\frac{3}{4}}} \leq c \|n^\epsilon\|_{T^2} \end{array} \right. \Rightarrow \|n^\epsilon\|_{T^2} \leq c \|n^\epsilon\|_{T^4}$$

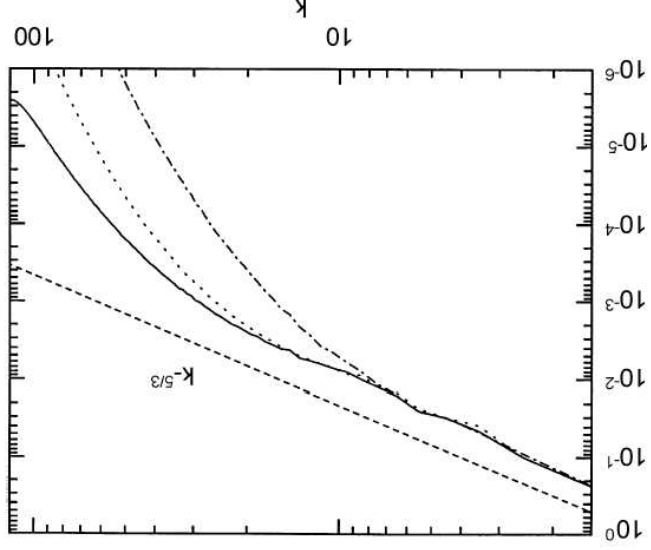
Proof (continued):



**LARGE EDDY
SIMULATIONS**

OBJECTIVES OF LES

- Concept introduced by Leonard (1974)
- The objective is to modify the NS model so that the new model is amenable to numerical simulations.



(From Foias, Holm and Titi, *Physica D*, 152-153 (2001))

- Almost no reasonable mathematical theory for LES.

THE FILTERING-EVERYTHING PARADIGM

Let $\underline{\underline{(\cdot)}} : w \mapsto \underline{w}$ be a regularizing operator acting on space- and time-dependent functions (we call it a **filter**).

Assume that the filter is **linear and commutes** with differential operators.

Apply the filter operator to the Navier–Stokes equations:

$$\left. \begin{aligned} \partial^t \underline{u} + \underline{u} \cdot \nabla \underline{u} + \underline{d} \Delta \underline{u} - \nu \Delta^2 \underline{u} &= \underline{f} - \Delta \cdot \mathbb{T}, \\ \Delta \cdot \underline{u} &= 0, \\ \underline{u}|_{t=0} &= \underline{u}_0, \end{aligned} \right\} \text{ or } \underline{u} \text{ is periodic,}$$

where we have introduced the so-called **subgrid-scale tensor**:

$$\underline{u} \otimes \underline{u} - \underline{\underline{u \otimes u}} = \mathbb{T}$$

THE FILTERING PARADOX

THE CLOSURE PROBLEM:

The goal of LES (Leonard (1974)) is to model \mathbb{T} in terms of \underline{u} only, without resorting to u .

THEOREM: (Germano (1986))

Exact closure is possible, e.g., take $\underline{v} := (I - \varepsilon_2 \Delta_2)^{-1} v$

PARADOX: (Guermont-Oden-Prudhomme (2001))

If the filter induces an isomorphism, the solution set of NS is isomorphic to the solution set of the filtered equations.

⇒ The two sets of weak solutions being isomorphic, one should expect to use **the same number of degrees of freedom** for approximating the NS solution as for approximating the filtered solution.

THE FILTERING PARADOX

CONCLUSION:

- Filtering and achieving exact closure **may not reduce** the number of degrees of freedom.
- Filtering the Navier–Stokes equations is an efficient approach only if **inexact** closure is performed.
- The filtering-everything paradigm is probably nonsensical.

PROPOSITION FOR A NEW PARADIGM FOR LES

DEFINITION: A sequence $(u^\epsilon, d^\epsilon)_{\epsilon > 0}$ is said to be a LES solution of NS if

- For all $\epsilon > 0$, (u^ϵ, d^ϵ) is uniquely defined for all times (i.e. regularization technique s.t there is **existence and uniqueness** for u^ϵ and d^ϵ for all times).
- $u^\epsilon \rightharpoonup u$, $d^\epsilon \rightharpoonup d$ (up to subsequences) and (u, d) is a **suitable weak** solution of NS.

EXAMPLE 0: Galerkin approximations are regularizing techniques (so-called DNS). Does a Galerkin solution converge to a suitable weak solution? (500k\$ question?).

EXAMPLES OF LES

EXAMPLE 1: Leray's regularization is a LES technique (1934)! However the "model" is **not frame invariant** (is it important?).

EXAMPLE 2: NS- α model (Holmes–Marsden–Rattus (1998), Holmes *et al.* (1999)). Theoretical mechanics \Rightarrow

$$\partial_t u^\epsilon + (\underline{u}^\epsilon) \cdot \nabla u^\epsilon - \nabla u^\epsilon \cdot (\underline{u}^\epsilon)_T + \Delta p^\epsilon - \nu \Delta^2 u^\epsilon = f$$

Alternative interpretation

$$\partial_t u^\epsilon + (\Delta \times u^\epsilon) \times \underline{u}^\epsilon + \Delta \pi^\epsilon - \nu \Delta^2 u^\epsilon = f.$$

• It is a Leray regularization where the nonlinear term is $(\Delta \times u) \times u + \Delta(\frac{z}{n^2})$.

• The equation is **frame-indifferent**.

• $u^\epsilon \rightarrow u$ (up to subsequences) and n is **suitable**

EXAMPLES OF LES

EXAMPLE 3: Ladyzenskaja (1967) proposed

$$\left\{ \begin{array}{l} \partial^t u^\epsilon + u^\epsilon \cdot \nabla u^\epsilon + \Delta p^\epsilon - \Delta \cdot \nu \Delta u^\epsilon + \mathcal{E}(\mathbf{D}) = f, \\ \Delta \cdot u^\epsilon = 0 \\ u^\epsilon|_{\Gamma} = 0, \text{ or } u \text{ is periodic,} \\ u^\epsilon|_{t=0} = u_0. \end{array} \right.$$

where operator \mathbb{T} is nonlinear, and $D = \frac{1}{2}(\Delta u^\epsilon + (\Delta u^\epsilon)_T)$.

For instance $\mathbb{T}(\xi) = \beta(|\xi|_2)\xi$ with $c\tau_\mu \leq \beta(\tau) \leq c'\tau_\mu$, with $\mu \geq \frac{1}{4}$ is possible. $\beta(\tau) = \tau^{1/2}$ yields Smagorinsky's model.

THEOREM: (Ladyzenskaja (1967)) *The modified NS equations*

*have a **unique** weak solution for all $t > 0$.*

Moreover $u^\epsilon \rightarrow u$ (up to subsequences) and u is **suitable**.

**EXAMPLE 4:
HYPERVISCOSITY**

HYPERVISCOSITY

EXAMPLE 4: Lions (1959) proposed to use hyperviscosity. Ω is the d -torus, where d is the space dimension.

$$\left\{ \begin{array}{l} \partial_t u^\epsilon + u^\epsilon \cdot \nabla u^\epsilon + \Delta^d u^\epsilon - \nu \Delta^2 u^\epsilon + \varepsilon (-\Delta^2)^\alpha u^\epsilon = f, \\ \Delta \cdot u^\epsilon = 0 \\ u^\epsilon \text{ is periodic,} \\ u^\epsilon|_{t=0} = u_0. \end{array} \right.$$

THEOREM: (Lions (1959)) *The modified NS equations have a **unique** weak solution for all $t > 0$ if $\alpha > \frac{d+2}{4}$.*

Moreover $u^\epsilon \rightarrow u$ (up to subsequences) and u is **suitable**.

QUESTION: How this technique can be implemented numerically?

HYPERVISIOSITY: A PRIORI ESTIMATES

Testing the momentum equation by u^ϵ yields

$$\frac{1}{2} \frac{d}{dt} \|u^\epsilon\|_{L^2}^2 + \nu \|\Delta u^\epsilon\|_{L^2}^2 + \epsilon \|(-\Delta)^{\frac{\alpha}{2}} u^\epsilon\|_{L^2}^2 = (f, u^\epsilon).$$

Integration in time, gives the following estimate:

$$\|u^\epsilon\|_{L^2}^2 + \int_0^T \|u^\epsilon\|_{H^\alpha}^2 dt \lesssim \|u_0\|_{L^2}^2 + \|f\|_{L^2(T_2)}^2.$$

In a similar manner, testing by $u^{\epsilon,t}$ yields

$$\|u^{\epsilon,t}\|_{L^2(T_2)}^2 + \|u^\epsilon\|_{H^\alpha}^2 + \int_0^T dt \int \Omega |u^\epsilon|_2 |\Delta u^\epsilon|_2 dx + \|f\|_{L^2(T_2)}^2.$$

Using Hölder's inequality, we write

$$\int \Omega |u^\epsilon|_2 |\Delta u^\epsilon|_2 dx \lesssim \|u^\epsilon\|_{L^{2p}}^2 \|\Delta u^\epsilon\|_{L^{2p'}}^2, \quad \frac{1}{1} + \frac{d}{1} = 1.$$

HYPERVISIOSITY: A PRIORI ESTIMATES

Owing to Sobolev inequalities we also have

$$\begin{aligned} \|u^\epsilon\|_{T^{2p}} &\lesssim \|\Delta u^\epsilon\|_{T^{2p'}} \\ \|\Delta u^\epsilon\|_{T^{2p'}} &\lesssim \|u^\epsilon\|_{H^\alpha} \end{aligned}$$

if $\frac{1}{1} \geq \frac{2p'}{1} - \frac{1}{\alpha-1}$ if $\frac{1}{2} \geq \frac{1}{1} - \frac{p}{\alpha-1}$.

These two conditions yield

$$\alpha \geq \frac{4}{p+2} \quad \text{and} \quad p' \geq \frac{2p}{2p+2},$$

and

$$\|u^{\epsilon,t}\|_{T^2} + \|u^\epsilon\|_{T^\infty} \lesssim c(\nu, u_0, f, \epsilon).$$

and since $\int_0^T \|u^\epsilon\|_{H^\alpha}^2 dt$ is bounded, Gronwall's lemma yields

Existence of solutions in $T^\infty(0, T; H^\alpha)$, $\forall T > 0$, is proved by means of the Galerkin technique using the *a priori* estimates.

SPECTRAL HYPERVISCOSITY

FOURIER APPROXIMATION

DEFINITION:

$$H_s(\Omega) = \{u = \sum_{k \in \mathbb{Z}^3} u_k e^{ik \cdot x}, u_k = \underline{u}_{-k}, \sum_{k \in \mathbb{Z}^3} (1 + |k|)^s |u_k|_2 < +\infty\}.$$

$$(u, v) = \int_{\Omega} \underline{u} \underline{v} = \sum_{k \in \mathbb{Z}^3} u_k \underline{v}_k.$$

$$\mathbb{P}^N = \left\{ p(x) = \sum_{|k| \leq N} c_k e^{ik \cdot x}, c_k = \underline{c}_{-k} \right\},$$

Velocity space

←

$$X^N = \mathbb{P}^3_N,$$

Pressure space

←

$$M^N = \mathbb{P}^1_N.$$

FOURIER APPROXIMATION

$$H^s(\Omega) \ni \sum_{k \in \mathbb{Z}_3} v_k e^{ik \cdot x} = v \mapsto P^N v = \sum_{|k| \leq N} v_k e^{ik \cdot x} \in \mathbb{P}^N$$

LEMMA: P^N satisfies the following properties:

1) P^N is the restriction on $H^s(\Omega)$ of the L^2 projection onto \mathbb{P}^N .

2) $\forall s \geq 0, \|P^N\|_{\mathcal{L}(H^s(\Omega); H^s(\Omega))} \leq 1$.

3) P^N commutes with differentiation operators.

4) $\forall v \in H^s(\Omega), \forall \mu, 0 \leq \mu \leq s, \|v - P^N v\|_{H^\mu} \lesssim N^{\mu-s} \|v\|_{H^s}$.

5) $\forall v \in \mathbb{P}^N, \forall \mu, s, s \leq \mu, \|P^N v\|_{H^\mu} \lesssim N^{\mu-s} \|v\|_{H^s}$.

A NAIVE HYPERVISCOSITY MODEL

DEFINITION: $\hat{\mathcal{O}}(x) = \sum_{1 \leq |k| \leq N} \frac{1}{|k|^{2\alpha}} e^{ik \cdot x}$.

$$\hat{\mathcal{O}} * u_N(x) = \int_{\mathbb{T}^3} \hat{\mathcal{O}}(y) u_N(y) dy = \sum_{1 \leq |k| \leq N} |k|^{2\alpha} u_k e^{ik \cdot x}$$

If α is an integer $\hat{\mathcal{O}} * u_N(x) = (-\Delta)^{\alpha} u_N(x)$

Let $\epsilon > 0$

Find $u_N \in C^1([0, T]; X^N)$ and $p_N \in C^0([0, T]; M^N)$ such that

$$\left. \begin{aligned} & \partial_t u_N + (u_N \cdot \nabla) u_N - \Delta u_N + \nabla \cdot (u_N \Delta u_N) \\ & + \hat{\mathcal{O}} * u_N = f, \quad u_N|_{t=0} = u_0 \\ & \nabla \cdot u_N = 0, \quad \Delta p_N = -\nabla \cdot (u_N \Delta u_N) \end{aligned} \right\}$$

A NAIVE HYPERVISIOSITY MODEL

Consistency error in L^2 : $\epsilon \|Q * u_N\|_{L^2} \leq \epsilon \|u_N\|_{H^{2\alpha}} = \mathcal{O}(\epsilon^{\frac{1}{2}})$.
 But ϵ cannot be too small to play the regularizing effect we expect.

\Rightarrow Consistency error **cannot be** arbitrarily small.

But if $u \in H^s$, where s may be arbitrarily large if u is smooth,
 $\|u - P^N u\|_{L^2} \leq c N^{-s} \|u\|_{H^s} = \mathcal{O}(N^{-s})$.

\Rightarrow The interpolation error **can be** arbitrarily small.

\Rightarrow The hyperviscosity regularization **spoils** the consistency.

A SPECTRAL HYPERVISCOSITY MODEL

KEY: Actually it is not necessary to stabilize the low wave numbers since they should be controlled by means of the L^2 a priori estimate.

DEFINITION: Let $\alpha > \frac{3}{4}$ and $\beta > 0$ (two parameters).

$$\left. \begin{array}{l} \epsilon_N = N^{-\beta}, \text{ with } 0 < \beta < \begin{cases} \frac{4\alpha-5}{2} \\ \frac{4\alpha(\alpha-1)}{2\alpha+3} \end{cases} \\ \text{if } \alpha \leq \frac{3}{2}, \text{ otherwise.} \\ N_i = N_\theta, \text{ with } \frac{\beta}{2\alpha} = \theta \\ \sum_{N_i \leq |k| \leq \infty} e^{i k \cdot x} (2\pi)^{-3} = \hat{\mathcal{O}}(x) \end{array} \right\}$$

A SPECTRAL HYPERVISCOSITY MODEL

One can also define the hyperviscosity kernel as follows:

$$\hat{Q}(x) = \frac{1}{(2\pi)^3} \sum_{N_i \leq |k| \leq \infty} \hat{Q}|k| e^{ik \cdot x},$$

where the viscosity coefficients $\hat{Q}|k|$ are such that

$$|1 - \hat{Q}|k|| \lesssim \frac{|k|_{2\alpha}}{N_i^{2\alpha}}, \quad A|k|^\infty \gtrsim N_i.$$

This definition has the practical advantage of ensuring a smooth transition of the viscosity coefficients across the threshold N_i .

All the results stated hereafter hold also with this definition.

A SPECTRAL HYPERVISCOSITY MODEL

We'd like β **large** so that $\epsilon_N = N^{-\beta}$ is **small**.

But the condition $u_N \rightarrow u$ where u is **dissipative** enforces

$$\beta > \begin{cases} \frac{4\alpha-5}{2} \\ \frac{2}{4\alpha(\alpha-1)} \end{cases} \left\{ \begin{array}{l} \text{If } \alpha \leq \frac{2}{3}, \\ \text{Otherwise.} \end{array} \right. < 2\alpha$$

α	$\frac{2}{3}$	2	3	4	5
β	$< \frac{1}{2}$	$< \frac{7}{8}$	$< \frac{3}{8}$	$< \frac{11}{48}$	$< \frac{13}{80}$
θ	$< \frac{6}{1}$	$< \frac{7}{2}$	$< \frac{9}{4}$	$< \frac{11}{6}$	$< \frac{13}{8}$

Admissible values of the parameters α , β , and θ .

A SPECTRAL HYPERVISCOSITY MODEL

Note that $\epsilon_N = N^{-2\alpha}$

Find $u_N \in C^1([0, T]; X^N)$ and $p_N \in C^0([0, T]; M^N)$ such that

$$\left. \begin{aligned} & \partial_t u_N, a + (u_N \cdot \Delta u_N, a) - (u_N, \Delta p_N) + \nu (\Delta u_N, \Delta a) \\ & + \epsilon_N (\mathcal{G} * u_N, a) = (f, a), \quad a \in X^N, \forall t \in (0, T], \\ & \Delta \cdot u_N, b = 0, \quad b \in M^N, \forall t \in (0, T], \\ & u_N|_{t=0} = P_N u_0. \end{aligned} \right\}$$

Note that $\Delta \cdot u_N = 0$ since $\Delta \cdot u_n \in M_N$, i.e. the approximate velocity field is solenoidal.

PROPOSITION: The hyperviscosity perturbation is **spectrally small** in the sense that

$$\epsilon_N \| \mathcal{Q} * v_N \|_{T^2} \leq c N^{-\theta_s} \| v_N \|_{H^s}, \quad \forall v_N \in H^s(\mathcal{U}), \quad \forall s \geq 2\alpha.$$

PROOF: Note that

$$\| \mathcal{Q} * u_N \|_{T^2} = \sum_{N_i \leq |k| \leq N} |k|_{4\alpha} |u_k|_2.$$

Using the fact that $2\alpha \leq s$ and that $N_i \leq |k| \leq N$, we have:

$$|k|_{4\alpha} = N_i^{4\alpha} \left(\frac{|k|}{N_i} \right)^{4\alpha} \leq N_i^{4\alpha} \left(\frac{|k|}{N_i} \right)^{2s} = N_i^{4\alpha-2s} |k|_{2s}$$

Moreover, from the definition of N_i , ϵ_N , and θ , we have

$$N_i^{4\alpha-2s} \epsilon_N = \epsilon_N^{-2} N^{-2\theta_s}$$

so that

$$\epsilon_N^2 \| \mathcal{Q} * u_N \|_{T^2} \leq \epsilon_N^2 \sum_{N_i \leq |k| \leq N} |k|_{2s} |u_k|_2 \leq N^{-2\theta_s} \| u_N \|_{H^s}^2$$

LEMMA: We have the *a priori* estimates

$$\|u_N\|_{T^\infty(T_2)} + \nu^{1/2} \|u_N\|_{T_2(H^1)} + \epsilon_N^{1/2} \|u_N\|_{T_2(H^\alpha)} \lesssim c.$$

PROOF: Observe that

$$\epsilon_N \|u_N\|_{T_2(H^\alpha)} = \epsilon_N \|u_N\|_{T_2(H^\alpha)} = \mathcal{O}(\epsilon_N) + \sum_{1 \leq |k| \leq \infty} \epsilon_N |k|_{2^\alpha} |u_k|_2$$

To estimate the last term in the above inequality. Use the fact that $\epsilon_N = N_i^{-2\alpha}$ and that $|k| \leq \sqrt{3}|k|^\infty$.

$$\epsilon_N \sum_{1 \leq |k| \leq \infty} |k|_{2^\alpha} |u_k|_2 \leq 3^\alpha N_i^{-2\alpha} \sum_{1 \leq |k| \leq \infty} |u_k|_2 \leq 3^\alpha \|u_N\|_{T_2}.$$

Since u_N is **solenoidal** and using the above bound, we obtain

$$\|u_N\|_{T_2} + \nu \|u_N\|_{T_2(H^1)} + \epsilon_N \|u_N\|_{T_2(H^\alpha)} \lesssim \|u_0\|_{T_2} + \frac{1}{2} \|f\|_{T_2(T_2)} + (3^\alpha + \frac{1}{2}) \|u_N\|_{T_2(T_2)}.$$

The result is a consequence of Gronwall's lemma.

LEMMA: We have

$$\|u_N\|_{T^d(H^{2/d})} + \|u_N\|_{T^d(T^b)} \leq c, \quad \text{with } 1 \leq d \leq \frac{3(b-2)}{4b}, \quad 2 \leq b \leq 6,$$

$$\|p_N\|_{T^{4/3}(T^2)} \leq c.$$

PROOF: First, we observe that $\Delta_2 : M_N \rightarrow M_N$ is bijective.

Then, we multiply the momentum equation by $\Delta_2^{-1} p_N$

(note that $\Delta_2^{-1} p_N \in X_N$ is an admissible test function).

By using several integrations by parts, we obtain

$$\|p_N\|_{T^2}^2 = (\Delta_2 p_N, \Delta_2^{-1} p_N)$$

$$= (-\partial_t u_N + \nu \Delta_2 u_N - u_N \cdot \nabla u_N + f, \Delta_2^{-1} p_N)$$

$$= -(u_N \cdot \nabla u_N, \Delta_2^{-1} p_N), \quad \text{since } u_N \text{ and } f \text{ are solenoidal}$$

$$= -(\Delta_2^{-1} p_N, (u_N \otimes u_N) \cdot \nabla)$$

$$= (u_N \otimes u_N, \Delta_2 \Delta_2^{-1} p_N)$$

$$\lesssim \|u_N\|_2^{T^4} \|p_N\|_{T^2},$$

$$\text{i.e. } \|p_N\|_{T^2} \lesssim \|u_N\|_2^{T^4}. \quad \text{Use the bound on } u_N, \text{ for } b = 4, \quad d = \frac{3}{8}.$$

COROLLARY: Let s be a real number such that $s \geq 2\alpha - 1 > \frac{2}{3}$, we have

$$\|\partial^t u_N\|_{T^{4/3}(H^{-s})} \lesssim c.$$

THEOREM: $u_N \rightarrow u$ and u is a **weak suitable** solution to NS.

PROOF: Test the momentum equation by $P_N(u_N \phi)$:

$$(\partial^t u_N, P_N(u_N \phi)) + \boxed{(u_N \cdot \nabla u_N, P_N(u_N \phi))} - (p_N, \nabla \cdot P_N(u_N \phi)) + \nu(\Delta u_N, \Delta P_N(u_N \phi)) + \epsilon_N(Q^* u_N, P_N(u_N \phi)) = (f, P_N(u_N \phi))$$

Define $R = (u_N \cdot \nabla u_N, P_N(u_N \phi) - u_N \phi)$ and because u_N is solenoidal, we have

$$(u_N \cdot \nabla u_N, P_N(u_N \phi)) = (u_N \cdot \nabla u_N, u_N \phi) + R = -\left(\frac{1}{2} |u_N|^2, \Delta \phi\right) + R.$$

For the remainder R we have

$$\begin{aligned}
 |R| &= |(u_N \cdot \Delta u_N, P_N(u_N \phi) - u_N \phi)|, \\
 &\lesssim \|u_N\|_2^{T_4} \|\Delta(P_N(u_N \phi) - u_N \phi)\|_{T_2}, \\
 &\lesssim N^{1-\alpha} \|u_N\|_2^{T_4} \|u_N \phi\|_{H^\alpha}, \\
 &\lesssim N^{1-\alpha} \|u_N\|_2^{T_4} \|u_N\|_2^{T_4} \|u_N\|_{H^\alpha} \|\phi\|_{H^s}.
 \end{aligned}$$

Approximation property,
Leibniz-like rule, $s > \alpha + \frac{2}{3}$.

To bound $\|u_N\|_{T^4}$ we proceed as follows.

$$\begin{aligned}
 \|u_N\|_2^{T_4} &\lesssim \|u_N\|_2^{H^r}, \\
 \text{Sobolev emb., } \frac{1}{4} &= \frac{1}{r} - \frac{2}{3}, \quad r = \frac{4}{3}, \\
 \|u_N\|_2^{T_4} &\lesssim \|u_N\|_{2^{(1-\gamma)T_2}}^{H^\alpha} \|u_N\|_{2^\gamma}^{H^\alpha}, \\
 \text{Interp. inq., } \gamma\alpha &= r, \quad \gamma = \frac{4\alpha}{3}, \\
 &\lesssim \|u_N\|_{\frac{2\alpha}{3}}^{H^\alpha}.
 \end{aligned}$$

At this point, there are two possibilities: either $\frac{2\alpha}{3} \leq 1$ or $\frac{2\alpha}{3} > 1$.

If $\alpha > \frac{2}{3}$, then

$$\|u_N\|_{T^4}^2 \lesssim \|u_N\|_{H^\alpha} \|u_N\|_{\frac{2\alpha}{3}-1}^{\frac{2\alpha}{3}-1},$$

$$\lesssim N^{\frac{2}{3}-\alpha} \|u_N\|_{H^\alpha} \|u_N\|_{\frac{2\alpha}{3}-1}^{\frac{2\alpha}{3}-1},$$

inverse inequality.

Then, owing to $\epsilon_N = N^{-\beta}$

$$|R| \lesssim N^{\frac{2}{5}-2\alpha} \|u_N\|_{H^\alpha} \|\phi\|_{H^s} = N^{\frac{2}{5}-2\alpha+\beta} \epsilon_N \|u_N\|_{H^\alpha} \|\phi\|_{H^s}.$$

That is to say, owing to the hypothesis $\beta \leq \frac{4\alpha-5}{2}$ we have

$$\int_0^T |R| \rightarrow 0 \text{ as } N \rightarrow +\infty.$$

CONCLUSIONS

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- The new LES paradigm is constructive: i.e. enforcing the regularized solution to converge to a suitable weak solution implies strong constraints on the numerical methods.
- Extension to non periodic domains and finite elements is likely to be highly technical.

⇒ There is no easy *a priori* estimate on the pressure.
⇒ There is no easy *a priori* estimate on $\partial_t u_h$ (Fourier analysis gives $u_h \in H^{\frac{8}{3}-\epsilon} L^2$), this is not enough!
⇒ The nonlinear term does not pose difficulties!
⇒ The trouble maker is the product $p^h u_h$!