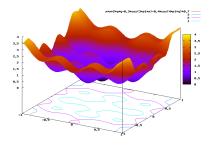
Introduction to Optimization

Pedro Gajardo¹ and Eladio Ocaña²

¹Universidad Técnica Federico Santa María - Valparaíso - Chile

²IMCA-FC. Universidad Nacional de Ingeniería - Lima - Peru



Mathematics of Bio-Economics (MABIES) - IHP

Introduction

Contents

Introduction

Optimality conditions

Introduction

Optimality conditions

In order to formulate an optimization problem, the following concepts must be very clear:

• decision variables

- restrictions
- objective function

Introduction

Optimality conditions

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Introduction

Optimality conditions

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Introduction

Optimality conditions

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Decision variables

- One or more variables on which we can decide (harvesting rate or effort, level of investment, distribution of tasks, parameters)
- Objective: to find the *best* value for the decision variable
- We denote by x the decision variable
- x can be a number, a vector, a sequence, a function,
- In a general framework, we denote by X the set where the decision variable is (x ∈ X)

Introduction

Optimality conditions

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Introduction

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Introduction

Optimality conditions

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Introduction

This tutorial is on Continuous Optimization

That means that decision variables are continuous variables

What that means?

Firstly, the set X where the decision variable belongs, is a (linear) vector space

Introduction

Optimality conditions

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Introduction

Optimality conditions

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Introduction

Optimality conditions

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Introduction

Restrictions

• Constraints that the decision variable has to satisfy

- If for a certain value of the decision variable the restrictions are satisfied, we say that it is a feasible solution
- In a general framework, we denote by $C \subseteq X$ the set of all feasible solutions
- If we have two decision variables, x₁ and x₂ and they have to satisfy the following constraints: x₁ ≥ 0, x₂ ≥ 0, 2 x₁ + 3 x₂ ≤ 5, we denote

 $C = \{ (x_1, x_2) \in \mathbb{R}^2 \mid x_1 \ge 0, x_2 \ge 0, \ 2x_1 + 3x_2 \le 5 \}$

Introduction

Optimality conditions

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Introduction

Optimality conditions

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Introduction

Optimality conditions

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Introduction

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Introduction

Optimality conditions

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Introduction

Objective function

It is the mathematical representation for measuring the *goodness* of values for the decision variable

This representation is done through a function

$$f: X \longrightarrow \mathbb{R}$$

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To find the *best* value for the decision variable from all feasible solutions

To find $\bar{x} \in C \subseteq X$ such that

 $f(\bar{x}) \le f(x) \text{ (or } f(\bar{x}) \ge f(x)) \text{ for all } x \in C$

$$\begin{cases} \min_{x \in X} f(x) & \left(\text{ or } \max_{x \in X} f(x) \right) \\ \text{subject to} \\ x \in C \end{cases}$$

Introduction

Optimality conditions

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Introduction

Example: maximizing a rectangular surface

With a given fence, to enclose the largest rectangular area

• Objective: maximize the rectangular surface

- Decision variables: lengths of the rectangular figure
- Constraints:
 - positive lengths
 - length of the fence

Introduction

Optimality conditions

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Introduction

Optimality conditions

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Introduction

Optimality conditions

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Introduction

Optimality conditions

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Introduction

Example: maximizing a rectangular surface

• Decision variables: *a* (height) and *b* (width)

• Objective: maximize s(a, b) = a b

• Constraints:

• positive lengths: a > 0, b > 0

• length of fence (L > 0): 2(a + b) = L

• $b = \frac{L}{2} - a$

• New objective function $f(a) = a \left(\frac{L}{2} - a\right)$

• Rewrite restrictions: a > 0, $a < \frac{L}{2}$

Introduction

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Introduction

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Introduction

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Introduction

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Introduction

Optimality conditions

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Introduction

Optimality conditions

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Example: maximizing a rectangular surface

$$\begin{cases} \max_{a \in \mathbb{R}} f(a) = a \left(\frac{L}{2} - a\right) \\ \text{subject to} \\ a > 0 \\ a < \frac{L}{2} \end{cases}$$

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Introduction

Example: Optimizing a portafolio

A firm wishes to maximize the utilities of its portafolio

• Objective: maximize profits

- Decision variables: amount to invest in each fund
- Constraints:
 - nonnegative investments
 - budget restrictions
 - o minimal or maximal bounds for investments

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Introduction

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▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

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Introduction

Optimality conditions

Example: Optimizing a portafolio

- Decision variables: $x_1, x_2, ..., x_n$, where x_j the quantity to invest in the fund j
- Objective: maximize

 $(1+r_1)x_1 + (1+r_2)x_2 + \ldots + (1+r_n)x_n$

where r_j is the rentability of the fund j

- Restrictions:
 - Non-negative investments: $z_j \ge 0$, $j = 1, 2, \ldots, n$
 - Budget restriction:

 $x_1 + x_2 + \ldots + x_n \leq B$

Minimal/maximal bounds for investments:

 $a_j \leq x_j \leq b_j$ for $j = 1, 2, \dots, n$

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Introduction

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A ロ ト 4 目 ト 4 目 ト 4 目 ・ 9 Q Q

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Introduction

Example: Optimizing a portafolio

- Decision variables: $x_1, x_2, ..., x_n$, where x_j the quantity to invest in the fund j
- Objective: maximize

$$(1+r_1)x_1 + (1+r_2)x_2 + \ldots + (1+r_n)x_n$$

where r_j is the rentability of the fund j

- Restrictions:
 - Non-negative investments: $x_j \ge 0$ j = 1, 2, ..., n
 - Budget restriction:

$$x_1+x_2+\ldots+x_n\leq B$$

• Minimal/maximal bounds for investments:

$$a_j \leq x_j \leq b_j$$
 for $j = 1, 2, \dots, n$

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Introduction

Example: Optimizing a portafolio

$$\begin{cases} \max_{x_1, x_2, \dots, x_n \in \mathbb{R}} (1+r_1)x_1 + (1+r_2)x_2 + \dots + (1+r_n)x_n \\ \text{subject to} \\ x_j \ge 0 \qquad j = 1, 2, \dots, n \\ x_1 + x_2 + \dots + x_n \le B \\ a_j \le x_j \le b_j \qquad j = 1, 2, \dots, n \end{cases}$$

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Introduction

Example: Least square problem

Given points on the plane, to find the *line of best fit* through these points

- Objective: To minimize the (squared) error between a line and the points
- Decision variables: the parameters of a line

Introduction

Optimality conditions

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Example: Least square problem

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• Decision variables: the parameters of a line

Introduction

Example: Least square problem

Given points

$$(x_1, y_1); (x_2, y_2); \ldots; (x_n, y_n)$$

to find the line of best fit through these points

• Decision variables (the parameters of a line): *m* and *n*, where the expression of a line in the plane is

$$y = mx + n$$

Objective: To minimize

$$\sum_{k=1}^{n} (mx_k + n - y_k)^2$$

Introduction

Optimality conditions

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Introduction

Optimality conditions

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Example: Least square problem

 $\max_{m, n \in \mathbb{R}} \sum_{k=1}^{n} (mx_k + n - y_k)^2$

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Introduction

Example: Harvesting of a renewable resource

To maximize the benefit from the harvesting of a natural resource

• Objective: maximize present utilities

- Decision variables: harvesting levels (or effort) at each period
- Constraints:
 - o nonnegative harvesting
 - biology
 - relation between harvesting and the amount of the resource
 - environmental constraints

Introduction

Optimality conditions

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Introduction

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Introduction

Optimality conditions

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Introduction

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Introduction

Optimality conditions

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Introduction

Optimality conditions

Example: Harvesting of a renewable resource

$$x(t+1) = F(x(t)) - h(t)$$
 $t = t_0, t_0 + 1, \dots, T - 1$

 $x(t_0) = x_0$ given (e.g. the current state of the resource)

where

- $x(t) \ge 0$ is the level of the resource at period *t*
- $h(t) \ge 0$ is the harvesting at period t
- $F : \mathbb{R} \longrightarrow \mathbb{R}$ is the biological growth function of the resource

Introduction

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Introduction

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Introduction

Optimality conditions

Example: Harvesting of a renewable resource

The total benefits can be represented by

$$B = \sum_{t=t_0}^{T-1} \rho^{(t-t_0)} U(x(t), h(t))$$

where

U(x, h) is the instantaneous profit if we have x and we harvest h

• $0 \le \rho \le 1$ is a descount factor

Introduction

Optimality conditions

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Introduction

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Introduction

Example: Harvesting of a renewable resource

$$\max_{\substack{h(t_0), h(t_0+1), \dots, h(T-1) \\ t = t_0}} \sum_{t=t_0}^{T-1} \rho^{(t-t_0)} U(x(t), h(t))$$

subject to
$$x(t+1) = F(x(t)) - h(t) \qquad t = t_0, t_0 + 1, \dots, T - 1$$

$$x(t_0) = x_0$$

$$x(t) \ge 0 \qquad t = t_0 + 1, t_0 + 2, \dots, T$$

$$0 \le h(t) \le F(x(t)) \qquad t = t_0, t_0 + 1, \dots, T - 1$$

Introduction

Optimality conditions

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Important remark: min is equivalent to max

We can restrict our study only to minimization problems

To find $\bar{x} \in C \subseteq X$ such that

 $f(\bar{x}) \le f(x)$ for all $x \in C$

$$\begin{array}{l}
\min_{x \in X} f(x) \\
\text{subject to} \\
x \in C
\end{array}$$

Introduction

Optimality conditions

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Introduction

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Introduction

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Introduction

Optimality conditions

Important remark: min is equivalent to max

$$(P_{max}) \begin{cases} \max_{x \in X} f(x) \\ \text{subject to} \\ x \in C \end{cases}$$

is equivalent to problem

$$(P_{min}) \begin{cases} \min_{x \in X} -f(x) \\ \text{subject to} \\ x \in C \end{cases}$$

In the following sense:

- \bar{x} is solution of (P_{max}) if and only if it is solution of (P_{min})
- The optimal value of (P_{max}) is the negative of the optimal value of (P_{min})

Introduction

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Introduction

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Introduction

Existence of solutions

$$(P) \begin{cases} \min_{x \in X} f(x) \\ \text{subject to} \\ x \in C \end{cases}$$

When (P) has solution?

- If $[a,b] = C \subseteq X = \mathbb{R}$
- When *X* = \mathbb{R}^n , there exists at least one solution if *C* is closed and bounded

Introduction

Optimality conditions

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Introduction

Optimality conditions

Contents

Introduction

Optimality conditions

Introduction

Optimality conditions

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$$(P) \begin{cases} \min_{x \in X} f(x) \\ \text{subject to} \\ x \in C \end{cases}$$

Optimality conditions are mathematical expressions: equations or system of equations, system of inequalities, ordinary differential equations, partial differential equations

Solutions of the mathematical problems obtained from optimality conditions are related with the solutions of the optimization problem Introduction

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Introduction

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The idea is to obtain optimality conditions and then to solve the associated mathematical problems (analytically or numerically)

Introduction

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Necessary conditions

$$(P) \begin{cases} \min_{x \in X} f(x) \\ \text{subject to} \\ x \in C \end{cases}$$

- Suppose that optimality conditions of this problem are represented by a system of equations (S)
- We say that (S) is a necessary condition if a solution of (P) is a solution of (S)
- The idea is to find solutions of (S) in order to have a list of candidates for the solutions of (P)
- If (S) is solved only for one point, then it is solution of (P) or (P) does not have solution
- Warning: A solution of (S) may be not a solution of (P)

Introduction

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Introduction

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Introduction

Necessary condition: unrestricted case

$$(P) \left\{ \min_{x \in \mathbb{R}} f(x) \right\}$$

where $f : \mathbb{R} \longrightarrow \mathbb{R}$

• A necessary condition is f'(x) = 0 where

$$f'(x) = \lim_{t \to 0} \frac{f(x+t) - f(x)}{t}$$

- That means: If \bar{x} is a solution of (P) then $f(\bar{x}) = 0$
- If we know the expression of f' we can solve the equation f'(x) = 0 in order to have candidates of solutions
- Warning!!!

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- Warning!!!

Necessary conditions: restrictions

$$(P) \begin{cases} \min_{x \in \mathbb{R}} f(x) \\ a \le x \le b \end{cases}$$

where $f : \mathbb{R} \longrightarrow \mathbb{R}$

- At a point x observe that f increase in the sense of (the sign of) f'(x)
- There are three posibilities:
 - an interior point $a < \bar{x} < b$ is a solution. Then $f'(\bar{x}) = 0$
 - $\bar{x} = a$ is a solution. Then $f'(\bar{x}) = f'(a) \ge 0$

 $\bar{x} = b$ is a solution. Then $f'(\bar{x}) = f'(b) \le 0$

• Observe that if f'(a) > 0 and f'(b) < 0, then there exists $a < \bar{x} < b$ such that $f'(\bar{x}) = 0$

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Introduction

Necessary conditions: restrictions

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Global vs local minimum

$$(P) \begin{cases} \min_{x \in X} f(x) \\ \text{subject to} \\ x \in C \end{cases}$$

- We say that $\bar{x} \in C$ is a global minimum, if it is a solution of (P)
- We say that x̄ ∈ C is a local minimum, if for every x ∈ C close enough, one has f(x̄) ≤ f(x)
- A global optimum is a local optimum

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Introduction

Optimality conditions

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- In the general case, this is very difficult
- It is much realistic to have that solutions of (S) are local solutions of (P)

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• A (local) sufficient condition to (P) is f'(x) = 0 and f''(x) > 0

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If we find $\bar{x} \in \mathbb{R}$ such that

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Then \bar{x} is a local minimum of the problem

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$$(P) \begin{cases} \min_{x \in X} f(x) \\ \text{subject to} \\ x \in C \end{cases}$$

- To formulate an optimization problem, the following concepts must be clear:
 - Decision variable(s): $x \in X$
 - Objective function: $f: X \longrightarrow \mathbb{R}$
 - Restrictions: $C \subset X$
- A maximization problem is equivalent to a minimization problem (deal with -f(x) instead of f(x))

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Introduction

$$(P) \begin{cases} \min_{x \in X} f(x) \\ \text{subject to} \\ x \in C \end{cases}$$

- To formulate an optimization problem, the following concepts must be clear:
 - Decision variable(s): $x \in X$
 - Objective function: $f: X \longrightarrow \mathbb{R}$
 - Restrictions: $C \subset X$
- A maximization problem is equivalent to a minimization problem (deal with -f(x) instead of f(x))

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• Optimality conditions are mathematical systems

• The idea is to solve these systems in order to:

- have candidates of solutions (if the system is a necessary condition)
- obtain a local solution (if the system is a sufficient condition)

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$$(P) \begin{cases} \min_{x \in X} f(x) \\ \text{subject to} \\ x \in C \end{cases}$$

• Several decision variables x_1, x_2, \ldots, x_n . That is

$$x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^n = X$$

- Necessary and sufficient conditions
- Why the convexity (or concavity) is relevant?

Introduction

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