

Progressive Hedging

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Presentation Outline

A Toy Examples in Energy Management

The Newsvendor problem

Lagrangian recalls

The Progressive Hedging Algorithm

Outline of the presentation

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A Toy Examples in Energy Management

Economic dispatch as a cost-minimization problem under supply-demand balance.

We consider two energy *production* units

- ▶ a “cheap” limited one which can produce a quantity q_0 , with $0 \leq q_0 \leq q_0^\#$, at cost $c_0 q_0$
- ▶ an “expensive” unlimited one which can produce quantity q_1 , with $0 \leq q_1$, at cost $c_1 q_1$, with $c_1 > c_0$

A Toy Examples in Energy Management (II)

On the *consumption* side, the demand is $D \geq 0$.

We express the *supply-demand balance objective* as ensuring at least the demand, that is

$$q_0 + q_1 \geq D .$$

This objective is to be achieved at least cost, so that the *optimization* problems is :

$$\min_{q_0, q_1} \underbrace{c_0 q_0 + c_1 q_1}_{\text{total costs}} .$$

A Toy Examples in Energy Management (III)

Measurability constraints

- ▶ The probability law of the demand is known
- ▶ q_0 is decided not knowing the demand D
 - ▶ Open-Loop control
- ▶ q_1 is decided knowing the demand D (Recourse)
 - ▶ Feedback control $q_1 = \gamma(D)$

The Stochastic Optimization Problem

We have to consider a stochastic optimization problem

$$\min_{q_0, \mathbf{q}_1} \mathbb{E}[c_0 q_0 + c_1 \mathbf{q}_1]$$

under the constraints

$$0 \leq q_0 \leq q_0^\#$$

$$0 \leq \mathbf{q}_1$$

$$\mathbf{D} \leq q_0 + \mathbf{q}_1$$

\mathbf{q}_1 depends upon \mathbf{D} ,

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The One Day Newsvendor Problem as a Linear Program

Recall

$$\min_{u \in \mathbb{R}_+} J(u) = \mathbb{E}_{\mathbf{W}}[j(u, \mathbf{W})]$$

where

$$j(u, w) = c_M w + (c - c_M)u + (c_M + c_S)(u - w)_+$$

can be written as a linear program

The One Day Newsvendor Problem as a Linear Program

$$\min_{u \in \mathbb{U}, (r_s)_{s \in S} \in \mathbb{V}^S} \sum_{s \in S} \pi_s (c_M w_s + (c - c_M)u + (c_M + c_S)r_s)$$

subject to

$$r_s \geq u - w_s \quad \forall s \in S$$

$$r_s \geq 0 \quad \forall s \in S$$

$$u \geq 0$$

- ▶ From a non-linear optimization problem with $u \in \mathbb{R}_+$
- ▶ To a Linear Program with
 - ▶ $1 + |S|$ variables : $(u, (r_s)_{s \in S}) \in \mathbb{R}^{1+|S|}$
 - ▶ $2|S| + 1$ constraints

The measurability constraint (I)

- ▶ The control $u \in \mathbb{U}$ must be the same for all realizations of the demand w_s
- ▶ Introduce a control $u_s \in \mathbb{U}$ for each scenario (**duplication of variables**) and force all the control to be equal. That is, add a constraint $u_s = \bar{u}$ for all $s \in S$

$$\min_{\bar{u} \in \mathbb{U}, (u_s)_{s \in S} \in \mathbb{U}^S, (r_s)_{s \in S} \in \mathbb{V}^S} \sum_{s \in S} \pi_s (c_M w_s + (c - c_M) u_s + (c_M + c_S) r_s)$$

subject to

$$r_s \geq u_s - w_s \quad \forall s \in S$$

$$r_s \geq 0 \quad \forall s \in S$$

$$u_s \geq 0$$

$$u_s = \bar{u} \quad \forall s \in S$$

The measurability constraint (II)

$u_s = \bar{u}$ for all $s \in S$ implies that $\bar{u} = \sum_{s' \in S} \pi_{s'} u_{s'}$

$$\min_{(u_s)_{s \in S} \in \mathbb{U}^S, (r_s)_{s \in S} \in \mathbb{V}^S} \sum_{s \in S} \pi_s (c_M w_s + (c - c_M) u_s + (c_M + c_S) r_s)$$

subject to

$$r_s \geq u_s - w_s \quad \forall s \in S$$

$$r_s \geq 0 \quad \forall s \in S$$

$$u_s \geq 0$$

$$u_s - \sum_{s' \in S} \pi_{s'} u_{s'} = 0 \quad \forall s \in S$$

Using multipliers

For all $s \in S$, dualize the constraint $u_s - \sum_{s' \in S} \pi_{s'} u_{s'} = 0$ We have that

$$\sum_{s \in S} \pi_s \langle \lambda_s, u_s - \sum_{s' \in S} \pi_{s'} u_{s'} \rangle = \sum_{s \in S} \pi_s \langle \lambda_s - \sum_{s' \in S} \pi_{s'} \lambda_{s'}, u_s \rangle$$

Thus we obtain

$$\min_{u_s \in \mathbb{U}^S, (r_s)_{s \in S} \in \mathbb{V}^S} \sum_{s \in S} \pi_s \left(c_M w_s + (c - c_M) u_s + (c_M + c_S) r_s \right. \\ \left. + \langle \lambda_s - \sum_{s' \in S} \pi_{s'} \lambda_{s'}, u_s \rangle \right)$$

$$r_s \geq u_s - w_s \quad \forall s \in S$$

$$r_s \geq 0 \quad \forall s \in S$$

$$u_s \geq 0$$

Using multipliers (II)

For given multipliers the problem is decomposed scenario by scenario. For scenario s we have to solve

$$\min_{u_s \in \mathbb{U}, r_s \in \mathbb{V}} \left(c_M w_s + (c - c_M) u_s + (c_M + c_S) r_s \right. \\ \left. + \left\langle \lambda_s - \sum_{s' \in S} \pi_{s'} \lambda_{s'}, u_s \right\rangle \right)$$

$$r_s \geq u_s - w_s$$

$$r_s \geq 0$$

$$u_s \geq 0$$

- ▶ $|S|$ Linear problems to solve in parallel
- ▶ Each L.P. have 2 variables and 3 constraints

How to chose multipliers in order to recover a solution of the original problem ?

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Lagrangian recalls

$$\min_{u \in \mathcal{U}, \Theta(u) \in -C} f(u)$$

- ▶ $\Theta : \mathcal{U} \rightarrow \mathbb{K}$, \mathbb{K} in duality with \mathbb{K}^*
 - ▶ **example** $\mathbb{K} = \mathbb{K}^* = \mathbb{R}^n$ with usual $\langle x, y \rangle$
- ▶ $C \in \mathbb{K}$ a closed convex cone such that $C \cap -C = \{0\}$ (salient).
- ▶ $C^* \in \mathbb{K}^*$, $C^* := \{u^* \in \mathbb{U}^* \mid \langle u^*, u \rangle \geq 0 \forall u \in C\}$
 - ▶ **example** $K : \mathbb{R}^p \rightarrow \mathbb{R}^n$, $Ku = 0 \sim Ku \in -C$ with $C = \{0\}$, $C^* = \mathbb{R}^n$
 - ▶ **example** $Ku \leq 0 \sim Ku \in -C$ with $C = \mathbb{R}_+^n$, $C^* = \mathbb{R}_+^n$

We introduce the **Lagrangian**

$$\begin{aligned} L(u, \lambda) : \mathcal{U} \times \mathbb{K}^* &\rightarrow \overline{\mathbb{R}} \\ (u, \lambda) &\rightarrow f(u) + \langle \lambda, \Theta(u) \rangle \end{aligned}$$

We consider the Lagrangian restricted to $u \in \mathcal{U}$ and $\lambda \in C^*$

Lagrangian recalls

The solutions of the problems

$$\min_{u \in \mathcal{U}, \Theta(u) \in -C} f(u)$$

and

$$\min_{u \in \mathcal{U}} f(u) + \delta_{-C}(\Theta(u))$$

and

$$\min_{u \in \mathcal{U}} \sup_{\lambda \in C^*} L(u, \lambda)$$

are the same.

where

$$\delta_A(u) = \begin{cases} 0 & \text{if } u \in A \\ +\infty & \text{if } u \notin A \end{cases}$$

Lagrangian recalls

$$\delta_{-C}(\Theta(u)) = \sup_{\lambda \in C^*} \langle \lambda, \Theta(u) \rangle$$

🔗 : ignore on first read

- ▶ If $\Theta(u) \in -C$ then $\langle \lambda, \Theta(u) \rangle \leq 0$ for all $\lambda \in C^*$ and equal to 0 when $\lambda = 0 \in C^*$ then $\sup_{\lambda \in C^*} \langle \lambda, \Theta(u) \rangle = 0$.
- ▶ C is a closed convex cone thus $C^{**} = C$. Thus if $\langle \lambda, \Theta(u) \rangle \leq 0$ for all $\lambda \in C^*$ we have that $\Theta(u) \in C^{**}$ and thus $\Theta(u) \in C$. Therefore, assume that $\Theta(u) \notin C$, then there exists $\lambda_0 \in C^*$ such that $\langle \lambda_0, \Theta(u) \rangle < 0$. Using the fact that C^* is a cone we have

$$\sup_{\lambda \in C^*} \langle \lambda, \Theta(u) \rangle \geq \sup_{\mu \in \mathbb{R}_+} \langle \mu \lambda_0, \Theta(u) \rangle = +\infty$$

Dual function

- ▶ We always have that

$$\sup_{\lambda \in C^*} \inf_{u \in \mathcal{U}} L(u, \lambda) \leq \inf_{u \in \mathcal{U}} \sup_{\lambda \in C^*} L(u, \lambda) = \min_{u \in \mathcal{U}, \Theta(u) \in -C} f(u)$$

- ▶ We can obtain a **lower bound** by maximizing the dual function

$$\sup_{\lambda \in C^*} \phi(\lambda) \quad \text{where} \quad \phi(\lambda) := \inf_{u \in \mathcal{U}} L(u, \lambda)$$

- ▶ For λ fixed $\phi(\lambda)$ is always a lower bound
- ▶ Possible Algorithm \leadsto **maximizing $\phi(\lambda)$ by projected gradient algorithm**

$$\lambda^{(k+1)} = P_{C^*}(\lambda^{(k)} + \rho \Theta(u^{(k+1)}))$$

Saddle Point

- ▶ Let $f : \mathbb{X} \times \mathbb{Y} \rightarrow \overline{\mathbb{R}}$ and $X \times Y \subset \mathbb{X} \times \mathbb{Y}$
 $(x^\#, y^\#) \in \mathbb{X} \times \mathbb{Y}$ is a saddle point of f on $\mathbb{X} \times \mathbb{Y}$ if

$$\forall (x, y) \in X \times Y, f(x^\#, y) \leq f(x^\#, y^\#) \leq f(x, y^\#)$$

- ▶ Result : $(x^\#, y^\#) \in \mathbb{X} \times \mathbb{Y}$ is a saddle point of f if and only if

$$\begin{aligned} f(x^\#, y^\#) &= \sup_{y \in \mathbb{Y}} f(x^\#, y) = \min_{x \in \mathbb{X}} \sup_{y \in \mathbb{Y}} f(x, y) \\ &= \max_{y \in \mathbb{Y}} \inf_{x \in \mathbb{X}} f(x, y) = \inf_{x \in \mathbb{X}} f(x, y^\#) \end{aligned}$$

- ▶ $\sup \inf$ and $\inf \sup$ commute
- ▶ we have $\sup \inf = \max \inf$ and $\inf \sup = \min \sup$

Lagrangian case

- ▶ If (u^*, λ^*) is a saddle point of $L(u, \lambda)$ on $\mathcal{U} \times C^*$ then u^* is solution of the primal problem $\min_{u \in \mathcal{U}, \Theta(u) \in -C} f(u)$.
- ▶ (u^*, λ^*) is a saddle point if and only if

$$\max_{\lambda \in C^*} \inf_{u \in \mathcal{U}} L(u, \lambda) = \min_{u \in \mathcal{U}} \sup_{\lambda \in C^*} L(u, \lambda)$$

- ▶ In the convex case (+ technical conditions) if u^* is solution of the primal problem there exists λ^* such that (u^*, λ^*) is a saddle point of the Lagrangian

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The newsvendor problem

$$\min_{(u_s, r_s)_{s \in S} \in (\mathbb{U} \times \mathbb{V})^S} \sum_{s \in S} \pi_s \overbrace{(c_M w_s + (c - c_M) u_s + (c_M + c_S) r_s)}^{f_s((u_s, r_s))}$$

subject to

$$(u_s, r_s) \in \bar{\mathcal{U}}_s \subset \mathbb{U} \times \mathbb{V}$$

$$u_s - \sum_{s' \in S} \pi_{s'} u_{s'} = 0 \quad \forall s \in S$$

where $\bar{\mathcal{U}}_s \subset \mathbb{U} \times \mathbb{V}$ is defined by

$$r_s \geq u_s - w_s \quad \forall s \in S$$

$$r_s \geq 0 \quad \forall s \in S$$

$$u_s \geq 0$$

Abstract Version of P.H.

- ▶ $\mathbb{U} = \prod_{s=1}^n \mathbb{U}_s$ equipped with a scalar product
 $\langle u, u' \rangle = \sum_{s=1}^n \pi_s \langle u_s, u'_s \rangle_s$ ($\pi_s > 0$ for all $i \in \{1, \dots, n\}$)
- ▶ $\Pi : \mathbb{U} \rightarrow \mathbb{V} \subset \mathbb{U}$ an orthogonal projection on \mathbb{V} a subspace of \mathbb{U}
 $\mathbb{V} := \{u \in \mathbb{U} \mid Ku = 0\}$ where $K = Id - \Pi$
- ▶ $f : \mathbb{U} \rightarrow \mathbb{R} \cup +\infty$ such that $f(u) := \sum_{s=1}^n \pi_s f_s(u_s)$
- ▶ $\mathcal{U} \subset \mathbb{U}$ such that $\mathcal{U} = \prod_{s=1}^n \mathcal{U}_s$ with $\mathcal{U}_s \subset \mathbb{U}_s$

Minimization problem

$$\min_{u \in \mathcal{U} \cap \mathbb{V}} f(u)$$

Without the coupling constraint $u \in \mathbb{V}$ we would have

$$\min_{u \in \mathcal{U}} f(u) = \sum_{s=1}^n \pi_s \min_{u_s \in \mathcal{U}_s} f_s(u_s)$$

The coupling constraint $u \in \mathbb{V}$ can be written $Ku = 0$

Abstract Version of P.H.

- ▶ Measurability constraint $Ku = 0$
- ▶ $K = Id - \Pi$
- ▶ $\Pi : \mathbb{U} \rightarrow \mathbb{U}$ is a projection

$$\Pi((u_1, \dots, u_n)) = \left(\left(\sum_{i=1}^n \pi_i u_i \right), \dots, \left(\sum_{i=1}^n \pi_i u_i \right) \right)$$

- ▶ The subspace \mathbb{V}

$$\mathbb{V} := \{(u_1, \dots, u_n) \in \mathbb{U} \mid u_1 = \dots = u_n\}$$

- ▶ The subspace \mathbb{V}^\perp

$$\mathbb{V}^\perp := \{(\lambda_1, \dots, \lambda_n) \in \mathbb{U} \mid \sum_{i=1}^n \pi_i \lambda_i = 0\}$$

Abstract Version of P.H (II)

- ▶ Lagrangian $L : \mathbb{U} \times \mathbb{U}^* \rightarrow \overline{\mathbb{R}}$, associated to $Ku = 0$

$$L(u, v) = f(u) + \langle Ku, v \rangle$$

- ▶ We can in fact consider

$$L : \mathbb{U} \times \mathbb{U}^* \rightarrow \overline{\mathbb{R}}$$

$$(u, v) \mapsto L(u, v) = f(u) + \langle u, v \rangle$$

for $u \in \mathcal{U}$ and $\lambda \in K(\mathbb{U})$ (equivalent to $\sum_{s=1}^n \pi_s \lambda_s = 0$)

 : ignore on first read

- ▶ $v \in \mathbb{U}$, $v = (Id - \Pi)v + \Pi v$ with $(Id - \Pi)v \in \mathbb{V}$ and $\Pi v \in \mathbb{V}^\perp$
- ▶ $L(x, v) = f(u) + \langle Ku, Kv + \Pi v \rangle = f(u) + \langle Ku, Kv \rangle = L(x, Kv)$
- ▶ We can restrict the dual space to $K(\mathbb{U})$ considering $L : \mathbb{U} \times K(\mathbb{U}) \rightarrow \overline{\mathbb{R}}$. That is dual variables u' satisfying $\Pi u' = 0$.
- ▶ Assuming that $v \in K(\mathbb{U})$ we have
- ▶ $L(x, v) = f(u) + \langle Ku, v \rangle = f(u) + \langle Ku, Ku' \rangle = f(u) + \langle u, K \circ Ku' \rangle = f(u) + \langle u, Ku' \rangle = f(u) + \langle u, v \rangle$
- ▶ We thus consider $L(u, v) = f(u) + \langle u, v \rangle$

Augmented Lagrangian

“Augmented Lagrangian methods were developed in part to bring robustness to the dual ascent method, and in particular, to yield convergence without assumptions like strict convexity or finiteness of f ”

$$\min_{\Theta(u)=0} f(u) \rightsquigarrow L_r(u, v) = f(u) + \langle v, \Theta(u) \rangle + \frac{r}{2} \|\Theta(u)\|_2^2$$

The augmented Lagrangian can be viewed as the (unaugmented) Lagrangian associated with the problem

$$\min_{\Theta(u)=0} f(u) + \frac{r}{2} \|\Theta(u)\|_2^2$$

Augmented Lagrangian

- ▶ Augmented Lagrangian associated to $Ku = 0$

$$L_r(u, v) = L(u, v) + r/2 \|Ku\|^2$$

- ▶ That is

$$L_r(u, v) = f(u) + \langle u, v \rangle + r/2 \|u - \Pi u\|^2$$

- ▶ with $\Pi u = \sum_{i=1}^n \pi_i u_i$

At first look We lose decomposition !

The Progressive Hedging Algorithm

1. given $u^k \in \mathcal{U}$, λ^k such that $\Pi\lambda^k = 0$
2. compute $\bar{u}^{k+1} = \Pi u^k$
3. compute u^{k+1} solution of

$$u^{k+1} \in \underset{u \in \mathcal{U}}{\text{Argmin}} f(u) + \langle u, \lambda^k \rangle + r/2 \|u - \bar{u}^{k+1}\|^2$$

- ▶ From Linear Programming to Quadratic Programming
 - ▶ But we can Linearize a quadratic term
4. update multiplier with $\lambda^{k+1} = \lambda^k + rKu^{k+1}$.
(Note that $\Pi\lambda^{k+1} = \Pi\lambda^k + r\Pi Ku^{k+1} = 0$)

Abstract Version of P.H (III)

Compute u^{k+1} solution of

$$u^{k+1} \in \underset{u \in \mathcal{U}}{\text{Argmin}} f(u) + \langle u, \lambda^k \rangle + r/2 \|u - \bar{u}^{k+1}\|^2$$

leads to scenario decomposition as

$$u_s^{k+1} \in \underset{u_s \in \mathcal{U}_s}{\text{Argmin}} f(u_s) + \langle u_s, \lambda_s^k \rangle + r/2 \|u_s - \bar{u}^{k+1}\|^2$$

Note that $u^{k+1} \in \mathcal{U}$ and $\bar{u}^{k+1} \in \mathbb{V}$ thus $\|u^{k+1} - \bar{u}^{k+1}\|^2$ is used to measure how far is u^{k+1} from $\mathcal{U} \cap \mathbb{V}$.

Convergence of Progressive Hedging

Rockafellar, R.T., Wets R. J-B.

Scenario and policy aggregation in optimization under uncertainty,
Mathematics of Operations Research, 16, pp. 119-147, 1991

- ▶ Extend to N -stage problems easily
- ▶ With integer variables it is an heuristic
- ▶ Many extensions to improve the integer variable cases