### The L-Shaped Method

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### Linear 2-stage stochastic program

Consider the following problem

$$\begin{split} \min_{u_0,\mathbf{u}_1} & & \mathbb{E}\left[c^\top u_0 + \mathbf{q}^\top \mathbf{u}_1\right] \\ s.t. & & Au_0 = b, \quad u_0 \geq 0 \\ & & \mathbf{T}u_0 + \mathbf{W}\mathbf{u}_1 = \mathbf{h}, \quad \mathbf{u}_1 \geq 0, \qquad \mathbb{P}-a.s. \\ & & & u_0 \in \mathbb{R}^n, \quad \sigma(\mathbf{u}_1) \subset \sigma(\underbrace{\mathbf{q}, \mathbf{T}, \mathbf{W}, \mathbf{h}}_{\xi}) \end{split}$$

Which we rewrite

$$\min_{\substack{u_0 \ge 0}} \quad c^\top u_0 + \mathbb{E} \left[ Q(u_0, \xi) \right]$$
s.t.  $Au_0 = b$ 

with

$$egin{aligned} Q(u_0,\xi) &:= \min_{u_1 \geq 0} \qquad q_\xi^ op u_1 \ s.t. \qquad W_\xi u_1 &= h_\xi - T_\xi u_0 \end{aligned}$$

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# Linear 2-stage stochastic program: extensive formulation

The associated extensive formulation reads

$$\begin{array}{ll} \min & c^{\top} u_{0} + \sum_{s=1}^{S} \pi^{s} \ q^{s} \cdot u_{1}^{s} \\ s.t. & Au_{0} = b, \quad u_{0} \geq 0 \\ & T^{s} u_{0} + W^{s} u_{1}^{s} = h^{s}, \quad u_{1}^{s} \geq 0, \ \forall s \in \llbracket 1, S \rrbracket \end{array}$$

Which we rewrite

$$\min_{u_0} \qquad c^{\top} u_0 + \sum_{s=1}^{S} \pi^s Q^s(u_0) \\ s.t. \qquad A u_0 = b, \quad u_0 \ge 0$$

with

$$Q^{s}(u_{0}) := \min_{u_{1} \ge 0} \qquad q^{s} \cdot u_{1}$$
  
s.t. 
$$W^{s}u_{1} = h^{s} - T^{s}u_{0}$$

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## Relatively complete recourse

- We assume here relatively complete recourse (RCR) (without this assumption, we would need feasability cuts, as explained in a forthcoming slide)
- Here, relatively complete recourse means that, for  $u_0 \ge 0$ ,

$$Au_0 = b \implies Q_s(u_0) < +\infty, \ \forall s \in \llbracket 1, S \rrbracket$$

that is,

$$Au_0 = b \Rightarrow \left\{ u_1^s \ge 0 \mid T^s u_0 + W^s u_1^s = h^s \right\} \neq \emptyset , \ \forall s \in \llbracket 1, S \rrbracket$$

Interpret what RCR means

The value functions are polyhedral

Recall that

$$\begin{aligned} Q^s(u_0) &:= \min_{u_1^s \in \mathbb{R}^n} \qquad q^s \cdot u_1^s \\ s.t. \qquad W^s u_1^s &= h^s - T^s u_0, \quad u_1^s \geq 0 \end{aligned}$$

 can also be written (through strong duality by relatively complete recourse assumption)

$$\begin{array}{ll} (D_{u_0}) \quad Q^s(u_0) = \max_{\lambda^s \in \mathbb{R}^m} & \lambda^s \cdot \left(h^s - T^s u_0\right) \\ s.t. & (W^s)^\top \lambda^s \leq q^s \end{array}$$

▶ Let *P* be the polyhedron  $\{\lambda^s \mid (W^s)^\top \lambda^s \leq q^s\}$  of admissible dual value (independent of  $u_0$ ), and ext(P) the (finite) set of its extremal point. We have that  $Q^s(u_0) = \max_{\lambda^s \in ext(P)} \lambda^s \cdot (h^s - T^s u_0)$ , and thus  $Q^s$  is polyhedral.

#### Decomposition of linear 2-stage stochastic program

We rewrite the extended formulation as

$$\begin{array}{ll} \min & c^{\top} u_0 + \sum_s \pi^s \theta^s \\ s.t. & A u_0 = b, \quad u_0 \ge 0 \\ & \theta^s \ge Q^s(u_0) & u_0 \in \mathbb{R}^n , \ \forall s \in \llbracket 1, S \rrbracket \end{array}$$

▶ As  $Q^{s}(u_{0})$  is a polyhedral function of  $u_{0}$ ,  $\theta^{s} \ge Q^{s}(u_{0})$  can be rewritten as  $\theta \ge \alpha_{k}^{s} \cdot u_{0} + \beta_{k}^{s}$ ,  $\forall k \in K^{s}$ 

 and the decomposition approach consists in constructing iteratively cut coefficients α<sup>s</sup><sub>k</sub> and β<sup>s</sup><sub>k</sub>

# Obtaining (optimality) cuts

Recall that

$$\begin{aligned} Q^{s}(\boldsymbol{u}_{0}) &:= \min_{\boldsymbol{u}_{1}^{s} \in \mathbb{R}^{n}} \qquad q^{s} \cdot \boldsymbol{u}_{1}^{s} \\ s.t. \qquad W^{s}\boldsymbol{u}_{1}^{s} &= h^{s} - T^{s}\boldsymbol{u}_{0}, \quad \boldsymbol{u}_{1}^{s} \geq 0 \end{aligned}$$

 can also be written (through strong duality by relatively complete recourse assumption)

$$\begin{array}{ll} (D_{u_0}) \quad Q^s(u_0) = \max_{\lambda^s \in \mathbb{R}^m} & \lambda^s \cdot \left(h^s - T^s u_0\right) \\ s.t. & (W^s)^\top \lambda^s \leq q^s \end{array}$$

# Obtaining (optimality) cuts

• Let  $\lambda_{u_0}^s$  be an optimal solution of the linear program

$$\begin{array}{ll} (D_{u_0}) \quad Q^s(u_0) = \max_{\lambda^s \in \mathbb{R}^m} & \lambda^s \cdot \left(h^s - T^s u_0\right) \\ s.t. & (W^s)^\top \lambda^s \leq q^s \end{array}$$

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• Considering another control  $u'_0$ , we have

$$\begin{array}{ll} (D_{u_0'}) \quad Q^s(u_0') = \max_{\lambda^s \in \mathbb{R}^m} & \lambda^s \cdot \left(h^s - T^s u_0'\right) \\ s.t. & (W^s)^\top \lambda^s \leq q^s \end{array}$$

► As  $\lambda_{u_0}^s$  is admissible for  $(D_{u_0})$ , it is also admissible for  $(D_{u'_0})$ , hence

$$Q^{s}(\boldsymbol{u}_{0}') \geq \lambda_{\boldsymbol{u}_{0}}^{s} \cdot \left(h^{s} - T^{s}\boldsymbol{u}_{0}'\right)$$

# Obtaining (optimality) cuts

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- To sum up we have seen that, for any admissible first stage solution, we can construct an exact cut for Q<sup>s</sup> by solving the dual of the second stage problem
- More precisely, letting u<sup>k</sup><sub>0</sub> ≥ 0 be such that Au<sup>k</sup><sub>0</sub> = b, and λ<sup>s</sup><sub>k</sub> be an optimal dual solution, we set

$$lpha_k^{s} := -(\mathcal{T}^{s})^ op \lambda_k^{s}$$
 and  $eta_k^{s} := (\lambda_k^{s})^ op h^{s}$ 

and we get

$$\begin{cases} Q^{s}(\boldsymbol{u}_{0}') \geq \alpha_{k}^{s} \cdot \boldsymbol{u}_{0}' + \beta_{k}^{s} , \quad \forall \boldsymbol{u}_{0}' \geq 0 , \ \boldsymbol{A}\boldsymbol{u}_{0}' = \boldsymbol{b} \\ \\ Q^{s}(\boldsymbol{u}_{0}^{k}) = \alpha_{k}^{s} \cdot \boldsymbol{u}_{0}^{k} + \beta_{k}^{s} \end{cases}$$

### L-shaped method (multi-cut version)

- 1. Start with a collection of  $K \times S$  cuts, such that  $Q^{s}(u_{0}) \geq \alpha_{k}^{s} \cdot u_{0} + \beta_{k}^{s}$
- 2. Solve the master problem, with optimal primal solution  $u_0^{K+1}$

$$\begin{split} \min_{\substack{u_0 \ge 0}} & c^\top u_0 + \sum_{s=1}^S \pi^s \theta^s \\ s.t. & Au_0 = b \\ & \theta^s \ge \alpha_k^s u_0 + \beta_k^s , \qquad \forall k \in \llbracket 1, K \rrbracket, \ \forall s \in \llbracket 1, S \rrbracket \end{split}$$

3. Solve S "slave" (dual) problems, with optimal dual solution  $\lambda_{K+1}^s$ 

$$\begin{aligned} Q^{s}(u_{0}^{K+1}) &= \max_{\lambda^{s} \in \mathbb{R}^{m}} \qquad \lambda^{s} \cdot \left(h^{s} - T^{s} u_{0}^{K+1}\right) \\ s.t. \qquad W^{s} \cdot \lambda^{s} \leq q^{s} \end{aligned}$$

4. Construct S new cuts with

$$\alpha_{K+1}^{s} := -(T^{s})^{\top} \lambda_{K+1}^{s}, \qquad \beta_{K+1}^{s} := h^{s} \cdot \lambda_{K+1}^{s}$$

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## L-shaped method (multi-cut version): bounds

At any iteration of the L-shaped method, we can easily determine upper and lower bounds of the original problem

Upper bound. As  $u_0^{\kappa}$  is an admissible first stage solution, and  $Q^{\kappa}(u_0^{\kappa})$  is the value of a slave problem, thus the value of the admissible solution  $u_0^{\kappa}$  is simply given by

$$UB = c^\top u_0^K + \sum_{s=1}^S \pi^s Q^s(u_0^K)$$

Lower bound. As  $Q_{K}^{s}(u_{0}) \geq \max_{k \leq K} \alpha_{k}^{s} \cdot u_{0} + \beta_{k}^{s}$ , the value of the master problem is always a lower bound over the value of the SP problem

$$LB = c^{\top} u_0^{\kappa} + \sum_{s=1}^{S} \pi^s \theta_{\kappa}^s$$

### L-shaped method (single-cut version)

- 1. Start with a collection of K cuts, such that  $Q(u_0) \ge \alpha_k \cdot u_0 + \beta_k$
- 2. Solve the master problem, with optimal primal solution  $u_0^{K+1}$

$$\begin{array}{ll} \min_{u_0 \geq 0} & c^\top u_0 + \theta \\ s.t. & Au_0 = b \\ & \theta \geq \alpha_k u_0 + \beta_k & \forall k \in \llbracket 1, K \rrbracket \end{array}$$

3. Solve S slave dual problems, each with optimal dual solution  $\lambda_{K+1}^s$ 

$$egin{aligned} \max & \lambda^s \cdot \left(h^s - T^s u_0^{K+1}
ight) \ s.t. & W^s \cdot \lambda^s \leq q^s \end{aligned}$$

4. Construct a new cut with

$$\alpha_{K+1} := -\sum_{i=1}^{S} \pi^{s} \left(T^{s}\right)^{\top} \lambda^{s} , \quad \beta_{K+1} := \sum_{i=1}^{S} \pi^{s} h^{s} \cdot \lambda^{s}$$

# Feasibility cuts (complementary material)

- ► The relatively complete recourse (RCR) property, here Q(u<sub>0</sub>) < +∞, is equivalent to the property that the effective domain dom(Q) of the convex function Q is the whole space</p>
- However, without the relatively complete recourse assumption, we still have that Q is polyhedral, thus so is the effective domain dom(Q)
- Without RCR, we need to add feasibility cuts in the following way
  - If  $Q^{s}(u_{0}^{k}) = +\infty$ , there exists an unbounded ray of the dual problem

$$egin{aligned} \max_{\lambda^s \in \mathbb{R}^m} & \lambda^s \cdot \left(h^s - T^s u_0^k
ight) \ s.t. & W^s \cdot \lambda^s \leq q^s \end{aligned}$$

more precisely, there exists a vector  $\overline{\lambda}^k$  such that, for all  $t \geq 0$ , we have  $W^s \cdot t \overline{\lambda}^k \leq q^s$ 

▶ Then, for *u*<sup>0</sup> to be admissible, we need that

$$\overline{\lambda}^k \cdot \left(h^s - T^s u_0\right) \leq 0$$

which is a feasibility cut

# Convergence

#### Theorem

In the linear case, the L-Shaped algorithm terminates in finitely many steps, and yields the optimal solution

The proof is done by noting that only finitely many cuts can be added, and that not being able to add a cut proves that the algorithm has converged