

# Optimization of an urban district microgrid

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*(presentation by F. Pacaud at the PGMO Days 2016)*

November 28, 2024

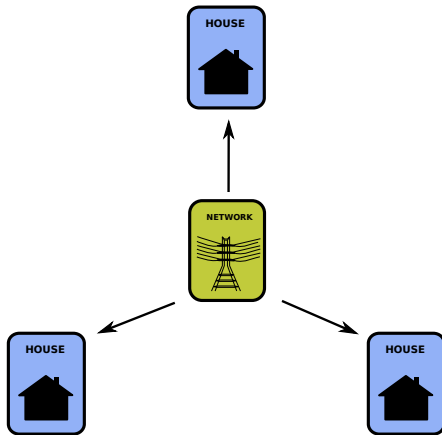


# A partnership between mathematicians and thermicians

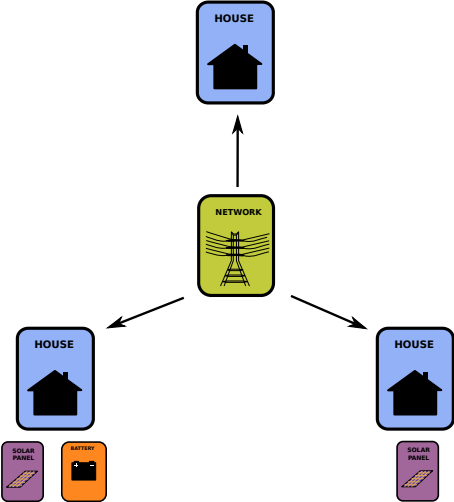


- ▶ Efficacity is a research institute for energy transition — an original mix of companies and academic researchers
- ▶ This presentation sums up a common work between CERMICS and Efficacity
- ▶ This cooperation develops optimization algorithms for real problems concerning the energy transition

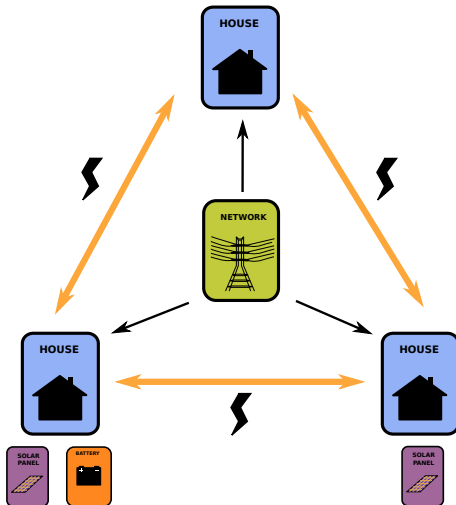
Usually houses import electricity from the grid



But more and more houses are equipped with solar panel



Is it worth to add a local grid to exchange electricity?



*Is it worth to connect different houses together inside a district?*

**Challenges:**

- ▶ Handle electrical exchanges between houses

**We turn to mathematical optimization to answer the question**

# Outline of the presentation

A brief recall of the single house problem

Optimization problem for a district

Numerical resolution

Conclusions and perspectives

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- Resolution methods and online simulation

- Assessment of strategies

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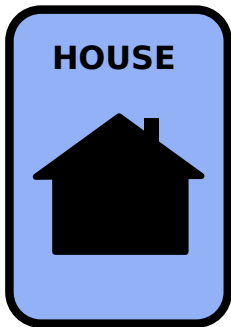
- Resolution and comparison

- Optimal trajectories of storages

Conclusions and perspectives

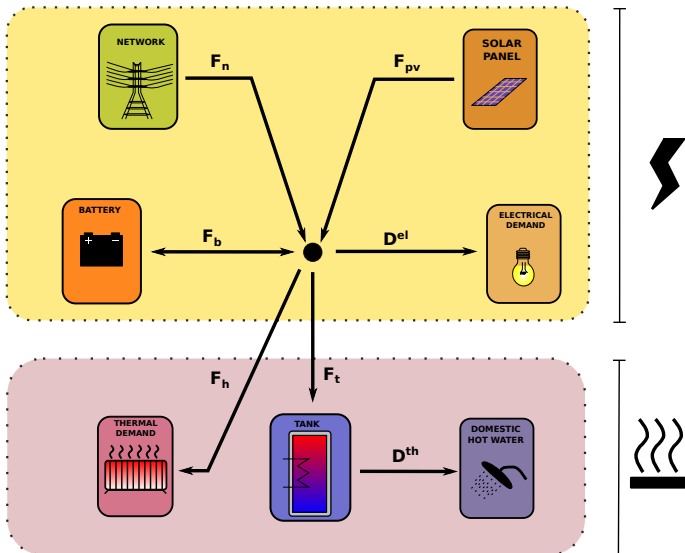


## Two goals for the control of a house

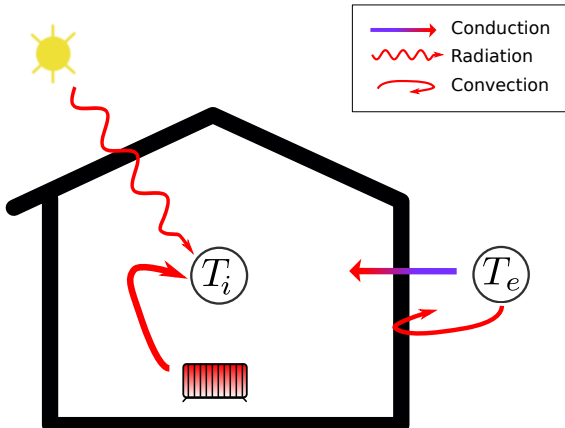


- ▶ Satisfy thermal comfort
- ▶ Optimize operational costs

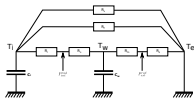
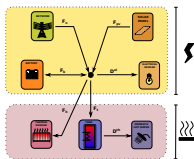
For each house, we consider the electrical system...



... and the thermal envelope



# We introduce states, controls and noises



- ▶ **Stock variables**  $X_t = (B_t, H_t, \theta_t^i, \theta_t^w)$ 
  - ▶  $B_t$ , battery level (kWh)
  - ▶  $H_t$ , hot water storage (kWh)
  - ▶  $\theta_t^i$ , inner temperature ( $^{\circ}\text{C}$ )
  - ▶  $\theta_t^w$ , wall's temperature ( $^{\circ}\text{C}$ )
- ▶ **Control variables**  $U_t = (F_{B,t}^+, F_{B,t}^-, F_{T,t}, F_{H,t})$ 
  - ▶  $F_{B,t}^+$ , energy stored in the battery
  - ▶  $F_{B,t}^-$ , energy taken from the battery
  - ▶  $F_{T,t}$ , energy used to heat the hot water tank
  - ▶  $F_{H,t}$ , thermal heating
- ▶ **Uncertainties**  $W_t = (D_t^E, D_t^{DHW}, P_t^{ext}, \theta_t^e)$ 
  - ▶  $D_t^E$ , electrical demand (kW)
  - ▶  $D_t^{DHW}$ , domestic hot water demand (kW)
  - ▶  $P_t^{ext}$ , external radiations (kW)
  - ▶  $\theta_t^e$ , external temperature ( $^{\circ}\text{C}$ )

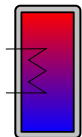
# Discrete time state equations

So we have the four state equations (all linear):



$$B_{t+1} = \alpha_B B_t + \Delta T \left( \rho_c F_{B,t}^+ - \frac{1}{\rho_d} F_{B,t}^- \right)$$

$$H_{t+1} = \alpha_H H_t + \Delta T [F_{T,t} - D_t^{DHW}]$$



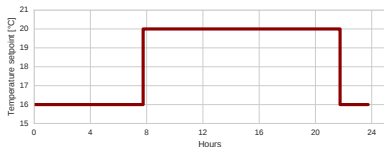
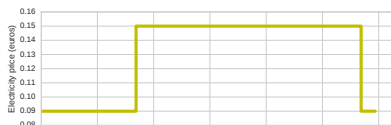
$$\theta_{t+1}^w = \theta_t^w + \frac{\Delta T}{c_m} \left[ \frac{\theta_t^i - \theta_t^w}{R_i + R_s} + \frac{\theta_t^e - \theta_t^w}{R_m + R_e} + \gamma F_{H,t} + \frac{R_i}{R_i + R_s} P_t^{int} + \frac{R_e}{R_e + R_m} P_t^{ext} \right]$$

$$\theta_{t+1}^i = \theta_t^i + \frac{\Delta T}{c_i} \left[ \frac{\theta_t^w - \theta_t^i}{R_i + R_s} + \frac{\theta_t^e - \theta_t^i}{R_v} + \frac{\theta_t^e - \theta_t^i}{R_f} + (1 - \gamma) F_{H,t} + \frac{R_s}{R_i + R_s} P_t^{int} \right]$$

which will be denoted:

$$X_{t+1} = f_t(X_t, U_t, W_{t+1})$$

# Prices and temperature setpoints vary along time



- ▶  $T_f = 24\text{h}$ ,  $\Delta T = 15\text{mn}$
- ▶ Electricity peak and off-peak hours
- ▶  $\pi_t^E = 0.09$  or  $0.15$  euros/kWh
- ▶ Temperature set-point  
 $\bar{\theta}_t^i = 16^\circ\text{C}$  or  $20^\circ\text{C}$

# The costs we have to pay

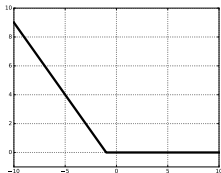
- ▶ Cost to import electricity from the network

$$- \underbrace{b_t^E \max\{0, -F_{NE,t+1}\}}_{\text{selling}} + \underbrace{\pi_t^E \max\{0, F_{NE,t+1}\}}_{\text{buying}}$$

where we define the recourse variable (electricity balance):

$$\underbrace{F_{NE,t+1}}_{\text{Network}} = \underbrace{D_{t+1}^E}_{\text{Demand}} + \underbrace{F_{B,t}^+ - F_{B,t}^-}_{\text{Battery}} + \underbrace{F_{H,t}}_{\text{Heating}} + \underbrace{F_{T,t}}_{\text{Tank}} - \underbrace{F_{pv,t}}_{\text{Solar panel}}$$

- ▶ Virtual Cost of thermal discomfort:  $\kappa_{th}(\underbrace{\theta_t^i - \bar{\theta}_t^i}_{\text{deviation from setpoint}})$



$\kappa_{th}$   
Piecewise linear cost  
Penalize temperature if  
below given setpoint

# Instantaneous and final costs for a single house

- ▶ The instantaneous convex costs are

$$L_t(X_t, U_t, W_{t+1}) = \underbrace{-b_t^E \max\{0, -F_{NE,t+1}\}}_{\text{buying}} + \underbrace{\pi_t^E \max\{0, F_{NE,t+1}\}}_{\text{selling}} \\ + \underbrace{\kappa_{th}(\theta_t^i - \bar{\theta}_t^i)}_{\text{discomfort}}$$

- ▶ We add a final linear cost

$$K(X_{T_f}) = -\pi^H H_{T_f} - \pi^B B_{T_f}$$

to avoid empty stocks at the final horizon  $T_f$



That gives the following stochastic optimization problem

$$\begin{aligned} \min_{X,U} \quad & J(X, U) = \mathbb{E} \left[ \underbrace{\sum_{t=0}^{T_f-1} L_t(X_t, U_t, W_{t+1})}_{\text{instantaneous cost}} + \underbrace{K(X_{T_f})}_{\text{final cost}} \right] \\ \text{s.t.} \quad & X_{t+1} = f_t(X_t, U_t, W_{t+1}) \quad \text{Dynamic} \\ & X^b \leq X_t \leq X^\# \\ & U^b \leq U_t \leq U^\# \\ & X_0 = X_{ini} \\ & \sigma(U_t) \subset \sigma(W_1, \dots, W_t) \quad \text{Non-anticipativity} \end{aligned}$$

This **stochastic multistage optimization problem**, corresponding to a single house, is solvable using standard **Stochastic Dynamic Programming (SDP)**

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- District topology

- Resolution methods and online simulation

- Assessment of strategies

## Numerical resolution

- Resolution and comparison

- Optimal trajectories of storages

Conclusions and perspectives

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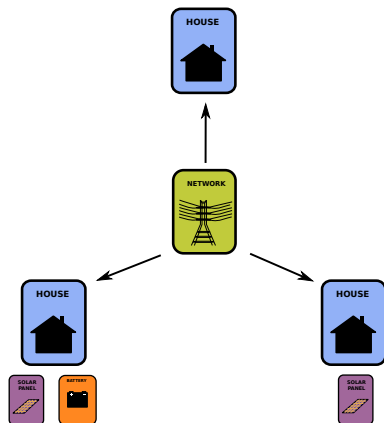
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# We have three different houses



Our (small) district:

- ▶ House 1: solar panel + battery
- ▶ House 2: solar panel
- ▶ House 3: nothing

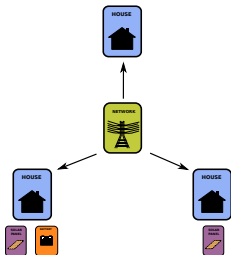
For the three houses:

- ▶ 10 stocks (= 4 + 3 + 3)
- ▶ 8 controls (= 4 + 2 + 2)
- ▶ 8 uncertainties  
(2 uncertainties in common)

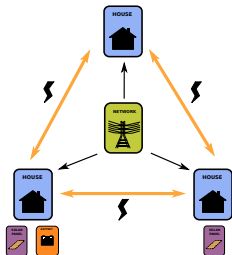
The total demand to the network is bounded:

$$\sum_{k=1}^3 F_{NE,t+1}^k \leq F_{NE}^\#$$

# We want to compare two configurations



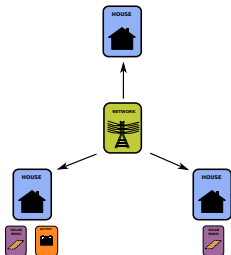
No exchange between houses



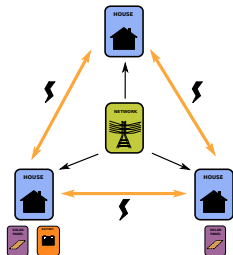
Exchange in a local grid

**How much costs decrease  
while allowing houses to exchange energy  
through a local grid?**

# We want to compare two configurations



No exchange between houses

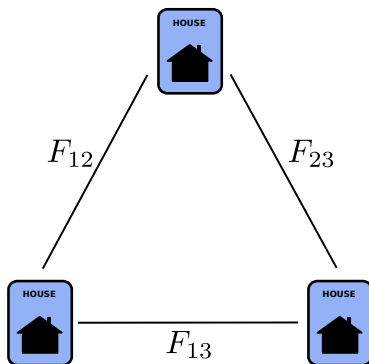


Exchange in a local grid

**How much costs decrease  
while allowing houses to exchange energy  
through a local grid?**

We show that adding a grid decreases costs by **23 %** during summer!

The grid adds three controls to the problem



# How to solve this stochastic optimal control problem?

We recall the different parameters of our multistage stochastic problem:

- ▶ 96 timesteps ( $= 4 \times 24$ )
- ▶ 10 stocks
- ▶ 11 controls
- ▶ 8 uncertainties



# How to solve this stochastic optimal control problem?

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The state dimension is high ( $=10$ ), the problem is not tractable by a straightforward use of *dynamic programming* because of the curse of dimensionality! :-)

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The state dimension is high ( $=10$ ), the problem is not tractable by a straightforward use of *dynamic programming* because of the curse of dimensionality! :-)

We will compare two methods that overcome this curse:

1. **Model Predictive Control** (MPC)
2. **Stochastic Dual Dynamic Programming** (SDDP)

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# A brief recall on Dynamic Programming

## Dynamic Programming

$\mu_t$  is the probability law of  $W_t$  and is being used to estimate expectation and compute **offline value functions** with the backward equation:

$$V_T(x) = K(x)$$

$$V_t(x_t) = \min_{U_t} \mathbb{E}_{\mu_t} \left[ \underbrace{L_t(x_t, U_t, W_{t+1})}_{\text{current cost}} + \underbrace{V_{t+1}(f(x_t, U_t, W_{t+1}))}_{\text{future costs}} \right]$$

# A brief recall on Dynamic Programming

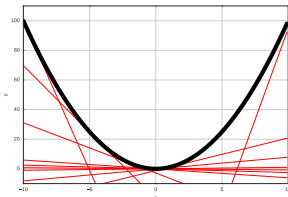
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## Stochastic Dual Dynamic Programming



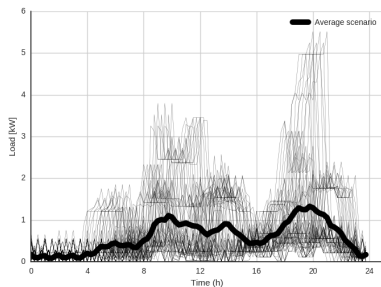
- ▶ Convex value functions  $V_t$  are approximated as a supremum of a finite set of affine functions
- ▶ Affine functions (=cuts) are computed during forward/backward passes, till convergence
- ▶ SDDP makes an extensive use of LP solver

$$\tilde{V}_t(x) = \max_{1 \leq k \leq K} \{ \lambda_t^k x + \beta_t^k \} \leq V_t(x)$$

# MPC vs SDDP: uncertainties modelling

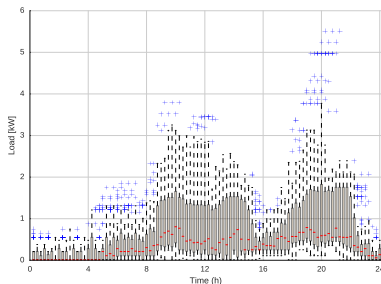
The two algorithms use optimization scenarios to model the uncertainties:

## MPC



MPC considers the average...

## SDDP



...and SDDP discrete laws

# MPC vs SDDP: online resolution

At the beginning of time period  $[\tau, \tau + 1]$ , do

## MPC

- ▶ Consider a **rolling horizon**  $[\tau, \tau + H[$
- ▶ Consider a **deterministic scenario** of demands (forecast)  
 $(\overline{W}_{\tau+1}, \dots, \overline{W}_{\tau+H})$
- ▶ Solve the **deterministic optimization** problem

$$\min_{X, U} \left[ \sum_{t=\tau}^{\tau+H} L_t(X_t, U_t, \overline{W}_{t+1}) + K(X_{\tau+H}) \right]$$

$$\text{s.t.} \quad \begin{aligned} X_t &= (X_{\tau}, \dots, X_{\tau+H}) \\ U_t &= (U_{\tau}, \dots, U_{\tau+H-1}) \\ X_{t+1} &= f(X_t, U_t, \overline{W}_{t+1}) \\ X^b &\leq X_t \leq X^{\#} \\ U^b &\leq U_t \leq U^{\#} \end{aligned}$$

- ▶ Get optimal solution  $(U_{\tau}^{\#}, \dots, U_{\tau+H}^{\#})$  over horizon  $H = 24h$
- ▶ Send only first control  $U_{\tau}^{\#}$  to assessor, and iterate at time  $\tau + 1$

## SDDP

- ▶ We consider the approximated value functions  $(\tilde{V}_t)_0^{T_f}$

$$\underbrace{\tilde{V}_t}_{\text{Piecewise affine functions}} \leq V_t$$

Piecewise affine functions

- ▶ Solve the **stochastic optimization problem**:

$$\min_{u_{\tau}} \mathbb{E}_{W_{\tau+1}} \left[ L_{\tau}(X_{\tau}, u_{\tau}, W_{\tau+1}) + \tilde{V}_{\tau+1}(f_{\tau}(X_{\tau}, u_{\tau}, W_{\tau+1})) \right]$$

⇒ this problem resumes to solve a LP at each timestep

- ▶ Get optimal solution  $u_{\tau}^{\#}$
- ▶ Send  $u_{\tau}^{\#}$  to assessor

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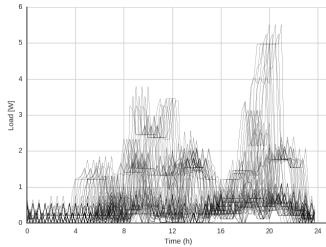
Resolution and comparison

Optimal trajectories of storages

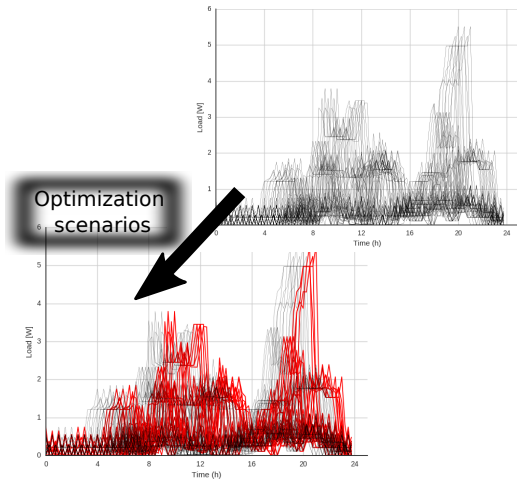
Conclusions and perspectives



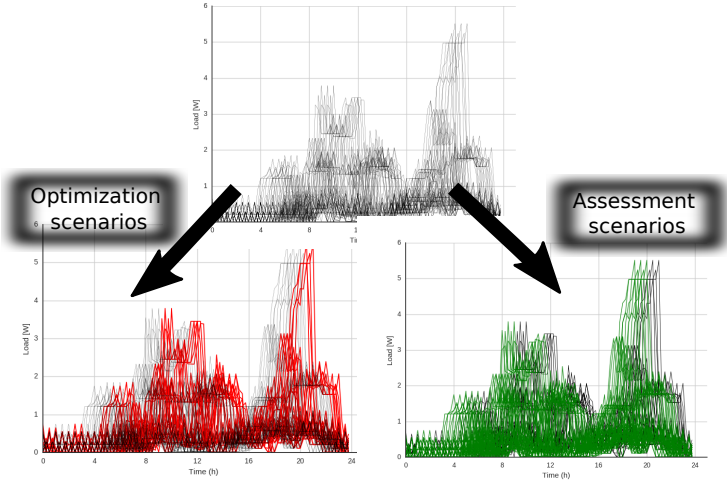
# Out-of-sample comparison



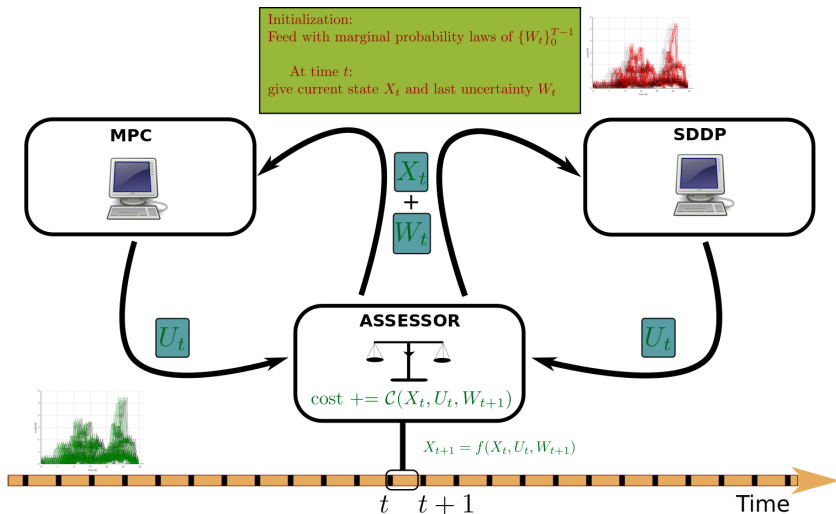
# Out-of-sample comparison



# Out-of-sample comparison



# We compare SDDP and MPC with assessment scenarios



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# Our stack is deeply rooted in Julia language



- ▶ Modeling Language: JuMP
- ▶ Open-source SDDP Solver:  
`StochDynamicProgramming.jl`
- ▶ LP Solver: CPLEX 12.5

<https://github.com/JuliaOpt/StochDynamicProgramming.jl>

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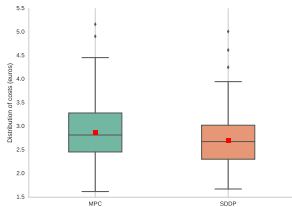
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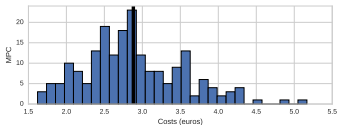
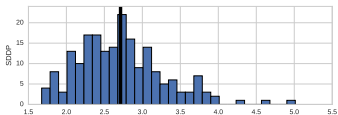
Conclusions and perspectives

# Comparison of MPC and SDDP

We compare MPC and SDDP during one day in summer over 200 assessment scenarios:



euros/day	
MPC	2.882
SDDP	2.713



SDDP is in average *6.9 %* better than MPC!



## Operational costs obtained in simulation

We compare different configurations, during summer and winter:

### Summer

Local Grid	Elec. bill euros/day	Self cons. %
<b>No</b>	3.53	48.1 %
<b>Yes</b>	2.71	55.2 %

### Winter

Local Grid	Elec. bill euros/day	Self cons. %
<b>No</b>	54.2	1.7 %
<b>Yes</b>	id.	id.

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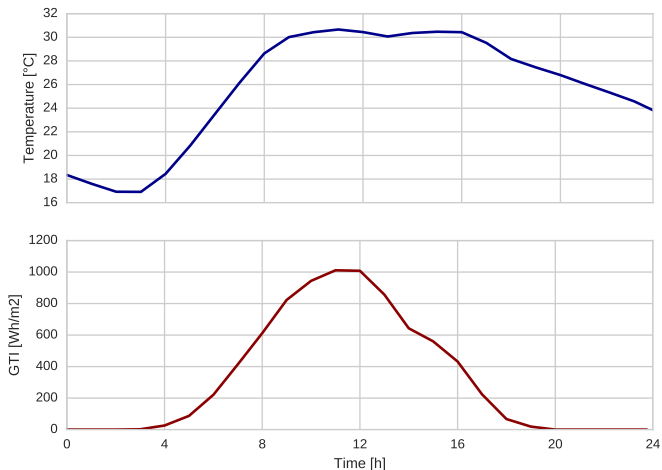
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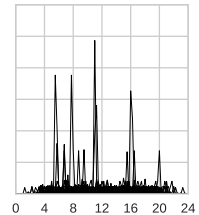
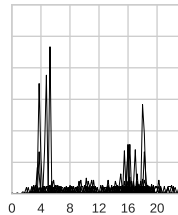
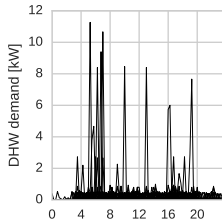
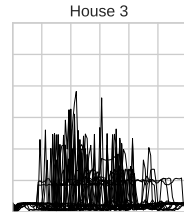
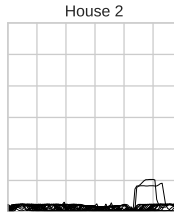
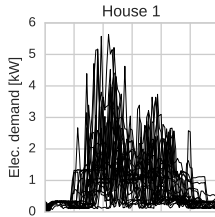
Conclusions and perspectives

# We work with real data

We consider one day during summer 2015 (data from Meteo France):

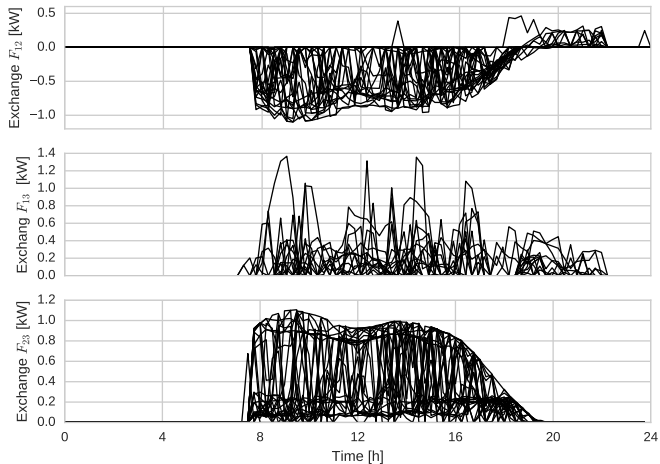
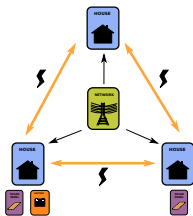


# We have 200 scenarios of demands during this day



These scenarios are generated with StRoBE, a generator open-sourced by KU-Leuven

As we gain solar energy, surplus is traded in local grid

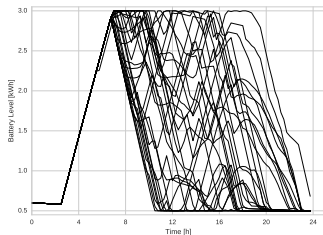


# The battery is used as a global storage inside the local grid

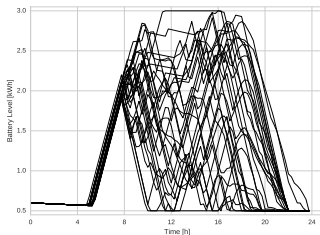
We observe that, in presence of the local grid,

- ▶ the battery is more widely used
- ▶ the saturation level is reached more often (need a bigger battery?)

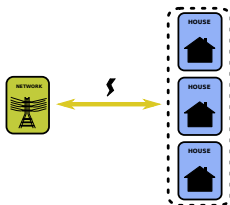
**No local grid**



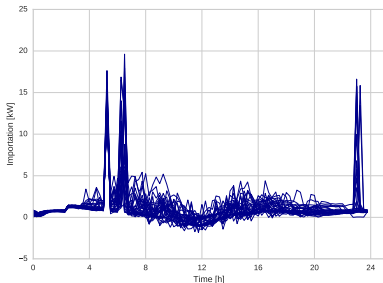
**Local grid**



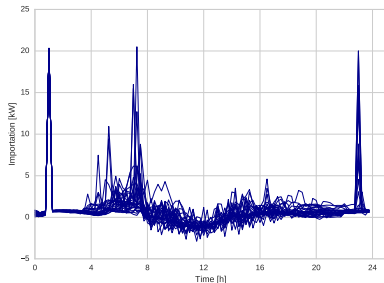
# We minimize our average importation from the network



**No local grid = 25.8 kWh**



**Local grid = 19.4 kWh**



# Outline of the presentation

A brief recall of the single house problem

Optimization problem for a district

- District topology

- Resolution methods and online simulation

- Assessment of strategies

Numerical resolution

- Resolution and comparison

- Optimal trajectories of storages

Conclusions and perspectives

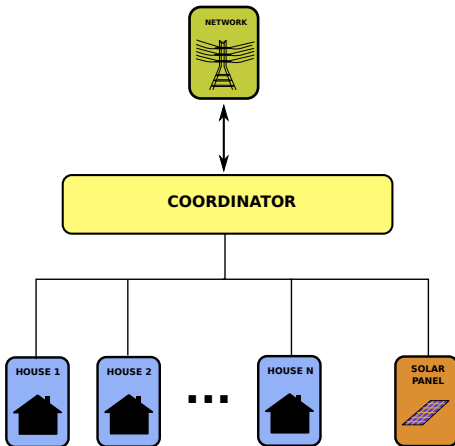


# Conclusions

- ▶ We extend the results obtained with a single house to a small district
- ▶ This study can help to perform an economic analysis
- ▶ It pays to use stochastic optimization: SDDP is better than MPC
- ▶ We want to scale for optimizing large microgrids

# Perspectives

Mix **dynamic programming techniques** like SDP or SDDP with **spatial decomposition** like **Dual Approximate Dynamic Programming (DADP)** to control large urban neighbourhood



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