Optimization under risk constraints: an economic interpretation as maxmin over a family of utility functions

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December 8, 2011

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DE LARA,ANDRIEU,SECK () Séminaire Louis Bachelier, 9 décembre 2011 December 8, 2011 1 / 40

Liberalization of energy market:

- **•** new set of problems for electrical companies
- instrument for hedging
	- gap between production and demand
	- financial risk

Our objective:

integrate risk constraints in the historical problem which consists in managing the electrical generation at lowest expected cost.

Equivalence between an expected profit maximization problem under risk constraint and a maxmin expected utility problem "à la Maccheroni". ⇓ In the case of CVaR constraint, interpretation of the corresponding piecewise linear utility functions class with the loss aversion notion "à la Kahneman et Tversky".

Babacar Seck, Laetitia Andrieu, Michel De Lara Parametric multi-attribute utility functions for optimal profit under risk constraints. In Theory and Decision, 2011.

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We consider the maximisation of expected profit $\mathbb{E}\big[\mathtt{Profit}(a, \xi)\big]$ subject to risk constraint

$$
\left\{\begin{array}{c}\max\limits_{a\in\mathbb{A}}\mathbb{E}\big[\text{Profit}(a,\xi)\big] \\ \text{s.t. } \text{Risk}\big(-\text{Profit}(a,\xi)\big)\leq \gamma, \end{array}\right.
$$

where

- $A \subset \mathbb{R}^n$ is a set of actions;
- $\bullet \xi$ is a random variable defined on a probability space $(\Omega, \mathcal{F}, \mathbb{P});$
- **•** Profit is a mapping, such that for any action $a \in A$, the random variable Profit(a, ξ) represents the profit of the decision maker (DM);
- Risk is the risk measure on the loss $-Profit(a, \xi)$, together with the level constraint $\gamma \in \mathbb{R}$.

Examples of risk constraints formulations

The risk constraint can be expressed by

a mathematical expectation:

 $\mathbb{E}[L(a,\xi)] \leq \gamma$

a Value-at-Risk:

 $VaR_{p}(L(a, \xi)) \leq \gamma$

a Conditional Value-at-Risk:

 $CVaR_p(L(a, \xi)) \leq \gamma$

Pros and cons

$$
\left\{\begin{array}{c}\max\limits_{a\in\mathbb{A}}\mathbb{E}\big[\text{Profit}(a,\xi)\big] \\ \text{subject to risk constraint.}\end{array}\right.
$$

• Plus: explicit formulation of risk.

Minus:

- hard to solve or to formulate for some problems
- o no theoretical foundation

Expected utility theory

We consider the maximisation of the expected utility of the profit Profit (a, ξ)

```
max
a∈A
         \mathbb{E}[\texttt{Util}(\texttt{Profit}(a, \xi))],
```
where Util is a utility fonction.

The fonction Util captures more or less risk aversion of the DM.

Extensions: nonexpected utility theories.

Pros and cons

$$
\max_{a\in A} \mathbb{E}\big[\mathtt{Util}\big(\mathtt{Profit}(a,\xi)\big)\big] \,.
$$

Plus: no additional constraint in the optimization problem

• Minus: how to choose a utility function Util?

The infinimum of expectations class of risk measures

We shall consider the risk measures which can be expressed as

 $\mathtt{Risk}_\rho(\mathcal{L}):=\min_{\eta\in\mathbb{R}}$ $\mathbb{E}[\rho(L,\eta)]$

Two equivalents formulations

Under technical hypotheses, the maximisation problem subject to risk constraint

> max a∈A $\mathbb{E}\big[\text{Profit}(a, \xi)\big]$ s.t. $\text{Risk}_\rho\big(-\text{Profit}(a, \xi)\big)\leq \gamma$

is equivalent to the maxmin expected utility problem ("à la Maccheroni")

max min $\mathbb{E} \left[\text{Util} \left(\text{Profit}(a, \xi), \eta \right) \right]$
(a, η)∈A×R Util∈U

where the set of utility functions U is defined by:

 $\mathcal{U}:=\left\{\mathtt{Util}^{(\lambda)}:\mathbb{R}^2\to\mathbb{R}\,,\,\,\lambda\geq 0\ |\ \mathtt{Util}^{(\lambda)}(\mathsf{x},\eta)=\mathsf{x}+\lambda\big(-\rho(-\mathsf{x},\eta)+\gamma\big)\right\}.$

Table: Usual risk measures and their corresponding family of two-attributes utility functions.

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The Conditional Value-at-Risk case

When the risk measure $Risk_a$ is the CVaR, we have

$$
\text{Util}^{(\lambda)}(x,\eta) = x - \frac{\lambda}{1-\rho}(-x-\eta)_{+} - \lambda \eta + \lambda \gamma.
$$

- \bullet We consider only the argument x (profit) and we interpret η as a parameter.
- 2 Up to an additive constant, we obtain the utility function

$$
x+\eta-\frac{\lambda}{1-p}(-x-\eta)_+=\begin{cases} x+\eta & \text{if } x+\eta\geq 0, \\ (1+\frac{\lambda}{1-p})(x+\eta) & \text{if } x+\eta<0. \end{cases}
$$

Loss aversion interpretation

We interpret the ratio of derivatives

$$
\theta:=1+\frac{\lambda}{1-\rho}
$$

as a loss aversion parameter, introduced by Kahneman et Tversky.

Loss aversion interpretation

The utility function

$$
\texttt{Util}(x) = x + \eta + (1 - \theta)(-x - \eta)_+
$$

- is parameterized by
	- anchorage $-\eta$,
	- \bullet loss aversion θ .

and expresses the property that one monetary unit more than the anchorage gives one unit of utility, while one unit less gives $-\theta$.

Loss aversion framing

(Meyerowitz-Chaiken, 1987)

• You can gain several potential health benefits by spending only five minutes each month doing breast self-examination

∧

- You can lose several potential health benefits by failing to spend only five minutes each month doing breast self-examination
- Subjects who read a pamphlet with arguments framed in loss language manifested more positive breast self-examination attitudes, intentions, and behaviors $(57\% > 38\%$ at the 4-month follow-up)

A toy portfolio problem

• A portfolio with two assets

$$
\text{Profit}(a, \xi) = a \underbrace{\xi^0}_{\text{sure}} + (1 - a) \underbrace{\xi^1}_{\mathcal{N}(M, \Sigma)}
$$

 $\xi^0{=}1$ 030 US\$

- \bullet $M = 1$ 113.3425 US\$ and the standard deviation $\Sigma = 186.29$ US\$ (annual MSCI world developed market performance index between 1970 and 2009).
- Now, handling risk can be done by "bounding the gains below". We choose the Conditional Value-at-Risk constraint

 $\mathtt{CVaR}_p\big(-\mathtt{Profit}\big(a,\xi\big)\big) \leq \gamma\ .$

Loss aversion coefficient θ^{\sharp} as function of confidence level p

$$
\rho\mapsto \theta^\sharp=1+\frac{\lambda^\sharp(\rho)}{1-\rho}
$$

Notice that θ^\sharp does not depend on $\gamma.$

Loss aversion coefficient θ^{\sharp} as function of confidence level p

- We observe high values for loss aversion for $p > 0.9$, well above the empirical findings (median value of 2.25 in (Tversky-Kahneman, 1992)).
- Dealing with risk by controlling this portfolio Conditional Value-at-Risk at usual confidence levels $p = 0.95$ and $p = 0.99$ reveals high loss aversion.
- Controlling this portfolio Conditional Value-at-Risk at lower confidence levels between 0.7 and 0.8 reveals a quite acceptable loss aversion slightly higher than 3.

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Dynamical system

We consider the following dynamical system

 $X(t + 1) = \text{DYN}(X(t), a(t), W(t)), t = t_0, \ldots, T - 1,$

with

- $t = t_0, \ldots, T-1$ the time supposed to be discrete,
- $X(t) \in \mathbb{R}^n$ the state, with $X(t_0) = X_0$ given,
- $a(t) \in \mathbb{R}^m$ the decision variable,
- $W(t) \in \mathbb{R}^k$ the noise, with $W(t_0), \ldots, W(T-1)$ a sequence of i.i.d. random variables,
- **• DYN** the dynamics (stocks variations, etc.).

Optimization problem

The optimization problem that we consider is

$$
\max_{\text{Rule}(\cdot)} \mathbb{E}\Big[\sum_{t=t_0}^{T-1} \text{Profit}(X(t), a(t), W(t)) + K(X(T))\Big]
$$

under dynamic constraints

$$
X(t+1) = \text{DYN}(X(t), a(t), W(t))
$$

$$
a(t) = \text{Rule}(t, X(t)) \quad \text{(Rule feedback)}
$$

and risk constraints

 $\text{Risk}_\rho\left[-\text{Profit}\big(X(t), s(t), W(t)\big) \right] \leq \gamma(t)\,,\, t=t_0,\dots,\, T-1\,.$

Two equivalent problems

Under technical hypotheses, the dynamic maximisation problem subject to risk constraint is equivalent to

max min
(Rule(·), η (·)) (Util_{to},...,Util₇ $(\mathtt{Util}_{t_0},\!\ldots\!,\!\mathtt{Util}_{\mathcal{T}-1}){\in}\mathcal{U}^{\mathcal{T}-t_0}$ $\mathbb{E}\Big[\sum_{t=t_0}^{T-1} \texttt{Util}_t\big(\texttt{Profit}(X(t),\textit{a}(t), \textit{W}(t)), \eta(t)\big) + \mathcal{K}(X(\mathcal{T}))\Big]$

where the set of utility functions U is defined by:

$$
\mathcal{U}:=\left\{\mathtt{Util}^{(\lambda)}:\mathbb{R}^2\to\mathbb{R}\,,\,\,\lambda\geq 0\mid\mathtt{Util}^{(\lambda)}(\mathsf{x},\eta)=\mathsf{x}+\lambda\big(-\rho(-\mathsf{x},\eta)+\gamma\big)\right\}.
$$

Application

We aim at optimizing the electrical production when financial risk constraints are added.

Mathematically, the problem consists in minimizing the expected production cost under the following constraints

- **e** energy balance
- **•** dynamic on hydraulic generation
- admissible actions
- **o** financial risk constraint

The electrical production

• Thermal generation: $c_i(t)$ is a unitary cost depending on the source (coal, fuel, gas, etc.), while $u_i(t)$ is a quantity

cost of thermal generation
$$
=\sum_{i=1}^{l} c_i(t) u_i(t)
$$
.

- Hydraulic generation takes into account
	- the random hydraulic inflows $A_i(t)$,
	- the release $w_i(t)$,

with the following dynamic:

$$
R_j(t+1) = R_j(t) + \Delta t (A_j(t) - w_j(t)).
$$

The energy market

• The forward market

forward market cost
$$
= \sum_{p \in \mathcal{P}} (t_e(p) - t_f(p)) F_p(t) q_p(t),
$$

where $t_e(p)$ and $t_f(p)$ denote initial and final dates for delivering the future contract p .

• The spot market

spot market cost = $v(t)S(t)$.

Uncertainties affecting electrical production

- \bullet the hydraulic inflows $A(t)$,
- \bullet the demand $D(t)$,
- the prices $F_p(t)$ and $S(t)$,
- • the breakdown $N_p(t)$ and $N_r(t)$ on the electrical production.

Production cost

At the end of the last period T , the cost is

$$
L(\mathcal{T}) = \sum_{t=t_0}^{\mathcal{T}-1} \Delta L(t)
$$

where we have denoted the instantaneous cost at time t by

$$
\Delta L(t) = \sum_{i=1}^{l} c_i(t) u_i(t) + v(t) S(t) \n+ \sum_{p \in P(t)} (t_e(p) - t_f(p)) (q_p(t) F_p(t) + |q_p(t)| B(t)) \n+ \delta(t) d(t).
$$

The optimization problem

The problem is

$$
\min_{u(\cdot),\,v(\cdot),\,\mathbf{q}(\cdot),\,w(\cdot)}\mathbb{E}\Big[\sum_{t=t_0}^{T-1}\Delta L(t)\Big],
$$

subject to

 \bullet financial risk constraints.

$$
\text{CVaR}_p\Big(\Delta L(t)\Big)\leq \gamma(t)\;,\quad \forall t=0,\ldots,\,T-1\;,
$$

- **•** dynamic on hydraulics and on forward contracts,
- bounds on the state and decision variables,
- non-anticipativity measurability constraints on decisions variables.

The reference problem: optimization without risk constraint

- Let us denote C^* the optimal cost without risk constraint.
- $\Delta L(t)$ denotes the optimal instantaneous cost at time t.

Optimal cost with risk constraint

• We choose a constant constraint level

$$
\gamma(t)=\gamma=\min_{s=0,...,T-1}\text{CVaR}(\Delta\overline{L}(s))\,.
$$

so that the following constraint is binding:

$$
\text{CVaR}_\rho\Big(\Delta \overline{L}(t)\Big)\leq \gamma\ ,\quad \forall t=0,\ldots,\, \mathcal{T}-1\ .
$$

Thus, the optimal cost with risk constraint is strictly higher than without risk constraint

• Difficulties: the algorithm is delicate to tune and the computation is long; it makes use of dynamic programming.

Utility function approach

The risk is taken into account via a single utility function

$$
\texttt{Util}(x) = x + \eta + (1 - \theta)(-x - \eta)_+.
$$

• We compute
$$
\eta = \frac{1}{T} \sum_{t=0}^{T-1} \text{VaR}(\Delta \overline{L}(t)),
$$

• and we fix the loss aversion $\theta = 4$, we obtain

Table: Optimal cost with utility function

Comparisons

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- Theoretical results
	- Economic interpretation of an "engineer" stochastic optimization problem under risk constraints
	- CVaR constraint associated to utility functions exhibiting loss aversion "à la Kahneman and Tversky"
- Application:

taking risk into account in electrical portfolio management