

Towards 2D overland flow simulations

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Problem context



Preventing overland flow and erosion

From upstream...



(Photos : Yves Le Bissonnais, INRA)

...to downstream.



Downstream zones modifications (watersheds)



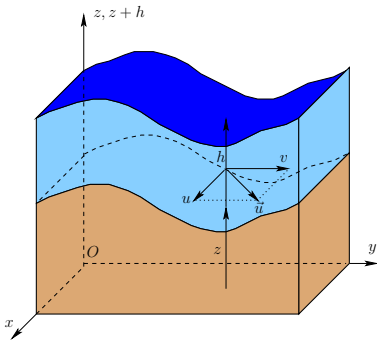
- ▶ Where is the water coming from ?
- ▶ Where is it flowing ?

Use of physical models is required to :

- ▶ simulate flow (volumes and location)
- ▶ suggest changes (grass strip).

~> to carry out improvements

Shallow Water (Saint-Venant) system



Data : topography z , rain P , infiltration I

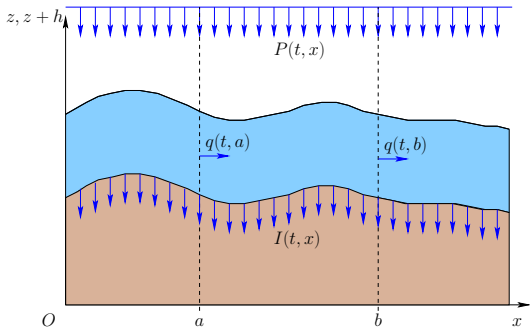
Unknowns : velocities u , v , water height h

$$\begin{cases} \partial_t h + \partial_x (hu) + \partial_y (hv) = P - I \\ \partial_t (hu) + \partial_x (hu^2 + gh^2/2) + \partial_y (huv) = gh(-\partial_x z - S_{f_x}) \\ \partial_t (hv) + \partial_x (huv) + \partial_y (hv^2 + gh^2/2) = gh(-\partial_y z - S_{f_y}) \end{cases}$$

Strategy

- ▶ Properties of the 1D Shallow Water system
- ▶ Choice of the method depending on the properties
- ▶ Validation : analytical solutions and laboratory experiment
- ▶ Application : field data

1D Shallow Water system



Data : topography z , rain P , infiltration I

Unknowns : velocities u , water height h

A system of conservation laws

$$\begin{cases} \partial_t h + \partial_x(hu) = P - I \\ \partial_t(hu) + \partial_x(hu^2 + gh^2/2) = gh(-\partial_x z - S_f) \end{cases} \quad (1)$$

System properties (I) : Hyperbolicity

Setting $q = hu$

$$U = \begin{pmatrix} h \\ q \end{pmatrix}, F(U) = \begin{pmatrix} q \\ q^2/h + gh^2/2 \end{pmatrix}, B = \begin{pmatrix} P - I \\ gh(-\partial_x z - S_f) \end{pmatrix},$$

compact form

$$\partial_t U + \partial_x F(U) = \partial_t U + F'(U)\partial_x U = B,$$

Hyperbolicity if $h > 0$:

$$\lambda_-(U) = u - \sqrt{gh}, \quad \lambda_+(U) = u + \sqrt{gh}$$

Saint-Venant	gaz dynamic
Froude number $Fr = \frac{ u }{c}$ $c = \sqrt{gh}$ free surface waves celerity	Mach number $\frac{ u }{c}$ $c = \sqrt{p'(\rho)}$ sound speed ¹
<u>subcritical</u> $Fr < 1$	subsonic
<u>supercritical</u> $Fr > 1$	supersonic

1. $p(\rho) = \rho RT$ perfect gaz

System properties (II) : Conservation laws

Integral of equation (1) in x

$$\partial_t h + \partial_x q = P - I,$$

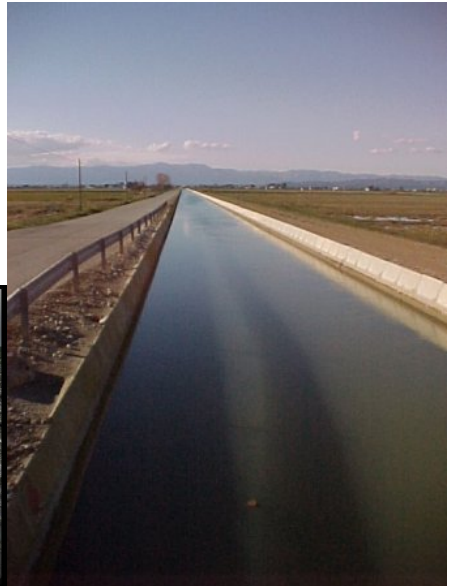
gives

$$\frac{d}{dt} \int_a^b h(t, x) dx = q(t, a) - q(t, b) + \int_a^b P(t, x) - I(t, x) dx,$$

Mass **conservation** of water.

Second equation : momentum equation

System properties (III) : **Steady states**



System properties (III) : **Steady state**

$$\begin{cases} \partial_t h + \partial_x(hu) = P - I \\ \partial_t(hu) + \partial_x(hu^2 + gh^2/2) = gh(-\partial_x z - S_f) \end{cases} \quad (2)$$

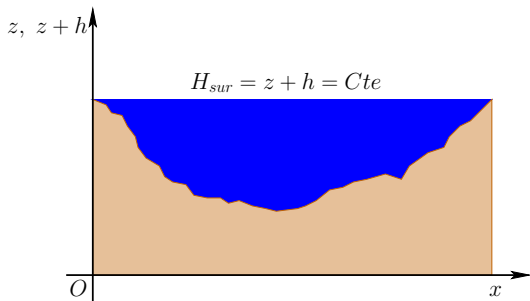
$$\partial_t h = \partial_t u = \partial_t q = 0$$

$$\begin{cases} \partial_x hu = P - I \\ \partial_x(hu^2 + gh^2/2) = gh(-\partial_x z - S_f) \end{cases} \cdot$$

System properties (III) : Steady states

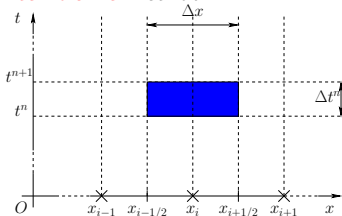
Lac at rest equilibrium

$$\begin{cases} u = 0 \\ g(h + z) = Cst \end{cases} .$$



Numerical method (I)

Finite volume method



we get

$$U_i^{n+1} = U_i^n - \frac{\Delta t}{\Delta x} [F_{i+1/2}^n - F_{i-1/2}^n],$$

with the **interface flux** approximation

$$F_{i+1/2}^n = \mathcal{F}(U_i^n, U_{i+1}^n) \sim \frac{1}{\Delta t} \int_{t^n}^{t^{n+1}} F(U(t, x_{i+1/2})) dt.$$

We integrate
 $\partial_t U + \partial_x F(U) = 0$
on the volume

$$[t^n, t^{n+1}] \times [x_{i-1/2}, x_{i+1/2}],$$

and we set

$$U_i^n = \frac{1}{\Delta x} \int_{x_{i-1/2}}^{x_{i+1/2}} U(t^n, x) dx$$

Numerical method (I)

- ▶ For each choice of $\mathcal{F}(U_G, U_D)$ we have a different **finite volume scheme** :

HLL, kinetic, Rusanov, VFRoe-ncv, suliciu, ...

- ▶ second Order
 - ▶ in space : MUSCL, ENO, modified ENO
 - ▶ in time : Heun

Numerical method (I)

- ▶ For each choice of $\mathcal{F}(U_G, U_D)$ we have a different **finite volume scheme** :

HLL, kinetic, Rusanov, VFRoe-ncv, suliciu, ...

- ▶ second Order
 - ▶ in space : MUSCL, ENO, modified ENO
 - ▶ in time : Heun
- ▶ Coupling with the source term (topography $\partial_x z$)
Necessity : compatibility with steady states

Steady states (II)

$$\begin{cases} \partial_t h + \partial_x(hu) = 0 \\ \partial_t(hu) + \partial_x(hu^2 + gh^2/2) = -gh\partial_x z \end{cases} \quad (3)$$

$$\partial_t h = \partial_t u = \partial_t q = 0$$

$$\begin{cases} hu = Cst \\ u^2/2 + g(h+z) = Cst \end{cases} \cdot$$

We consider

$$\begin{cases} u = Cst \\ g(h+z) = Cst \end{cases} \cdot$$

Hydrostatic reconstruction (II) [Audusse et al., 2004]

We define

$$z^* = \max(z_G, z_D)$$

and

$$\begin{cases} U_G^* = (h_G^*, h_G^* u_G), U_D^* = (h_D^*, h_D^* u_D) \\ h_G^* = \max(h_G + z_G - z^*, 0) \\ h_D^* = \max(h_D + z_D - z^*, 0) \end{cases} .$$

Thus, we have

$$\begin{cases} \mathcal{F}_G(U_G, U_D, \Delta Z) = \mathcal{F}(U_G^*, U_D^*) + \begin{pmatrix} 0 \\ g(h_G^2 - (h_G^*)^2)/2 \end{pmatrix} \\ \mathcal{F}_D(U_G, U_D, \Delta Z) = \mathcal{F}(U_G^*, U_D^*) + \begin{pmatrix} 0 \\ g(h_D^2 - (h_D^*)^2)/2 \end{pmatrix} \end{cases} ,$$

where $\mathcal{F}(U_G, U_D)$ is the numerical flux.

Friction treatment

Shallow Water system with friction f

$$\begin{cases} \partial_t h + \partial_x(hu) = 0, \\ \partial_t(hu) + \partial_x(hu^2 + gh^2/2) + h\partial_x z = -hf, \end{cases} \quad (4)$$

$f = f(h, u)$ friction force (on the bottom)

Several friction laws possible

- ▶ Manning : $f = n^2 \frac{u|u|}{h^{4/3}}$
- ▶ Darcy-Weisbach : $f = F \frac{u|u|}{8gh}$

Friction treatment

- ▶ Apparent topography [Bouchut, 2004]

We consider : $z_{app} = z + b^n$

with $\partial_x b^n = S_f^n$

Friction treatment

- ▶ **Apparent topography** [Bouchut, 2004]

$$\text{We consider : } z_{app} = z + b^n$$

with $\partial_x b^n = S_f^n$

- ▶ **Semi-implicit** [Bristeau and Coussin, 2001]

$$q_i^{n+1} + F \frac{|q_i^n| q_i^{n+1}}{8h_i^n h_i^{n+1}} \Delta t = q_i^n + \frac{\Delta t}{\Delta x} (F_{i+1/2} - F_{i-1/2})$$

with q_i^{n+1*} for the right part, we have

$$q_i^{n+1} = \frac{q_i^{n+1*}}{1 + \Delta t \frac{F|u_i^n|}{8h_i^{n+1}}}$$

Validation on analytical solutions – SWASHES

New test cases :

- ▶ Saint-Venant/shallow water :
 - ▶ data z
 - ▶ unknowns h et u (and so q)

Validation on analytical solutions – SWASHES

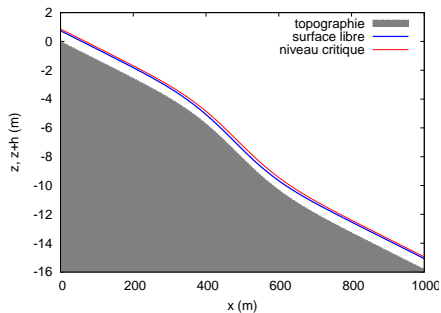
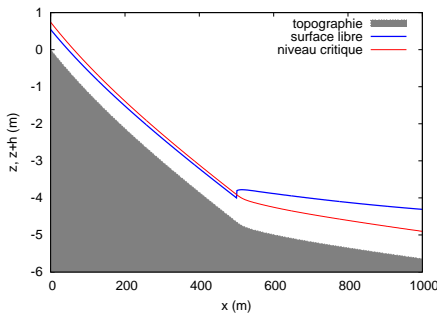
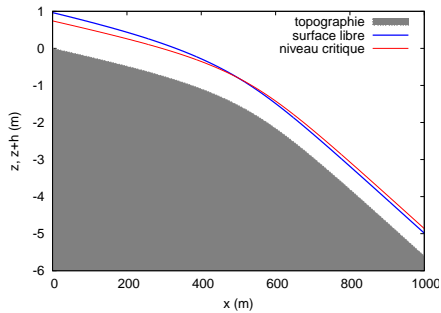
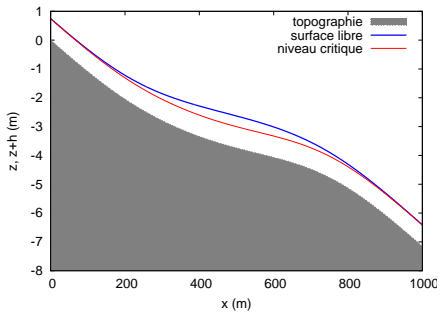
New test cases :

- ▶ Saint-Venant/shallow water :
 - ▶ data z
 - ▶ unknowns h et u (and so q)
- ▶ test cases
 - ▶ data h and q (and so u)
 - ▶ unknown z

Validation on analytical solutions – SWASHES

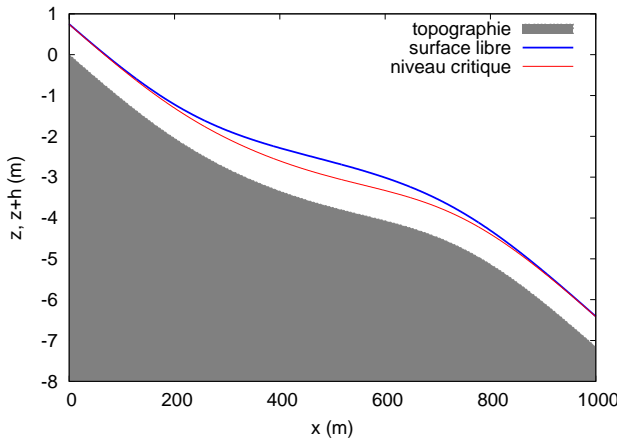
New test cases :

- ▶ Saint-Venant/shallow water :
 - ▶ data z
 - ▶ unknowns h et u (and so q)
- ▶ test cases
 - ▶ data h and q (and so u)
 - ▶ unknown z
- ▶ Several possibilities
 - ▶ several friction laws
 - ▶ diffusion source term [Delestre and Marche, 2010]
 - ▶ rain source term



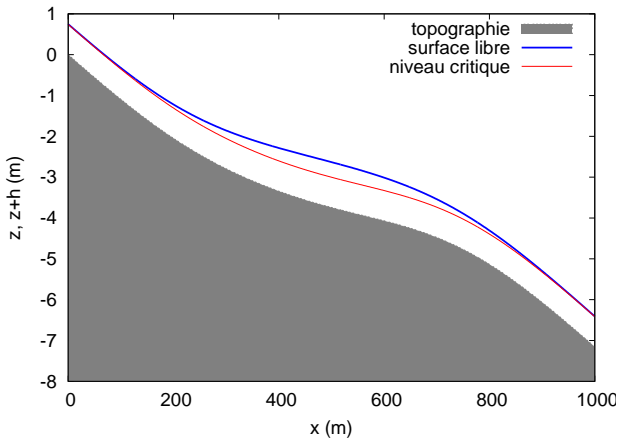
Validation on analytical solutions – SWASHES

Apparent topography (subcritical-subcritical)



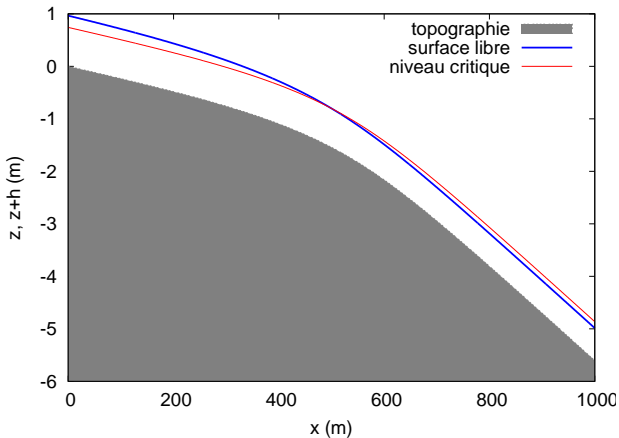
Validation on analytical solutions – SWASHES

Semi-implicit (subcritical-subcritical)



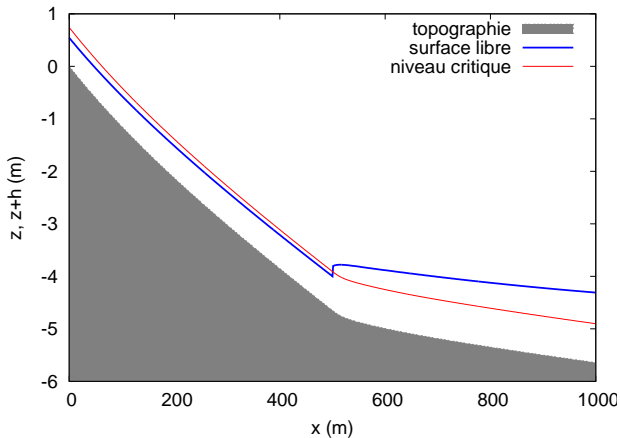
Validation on analytical solutions – SWASHES

Semi-implicit (subcritical-supercritical)



Validation on analytical solutions – SWASHES

Semi-implicit (supercritical-subcritical)



Summary of the chosen numerical method

- ▶ Numerical flux : HLL
- ▶ Second order scheme : MUSCL
- ▶ Friction : semi-implicit treatment
- ▶ Shallow Water system with rain P

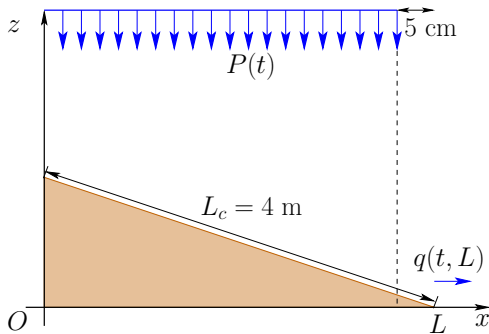
$$\begin{cases} \partial_t h + \partial_x(hu) = P \\ \partial_t(hu) + \partial_x(hu^2 + gh^2/2) + h\partial_x z = -hf \end{cases} \quad (5)$$

time splitting/explicit treatment

Validation on experiments – INRA rain simulator



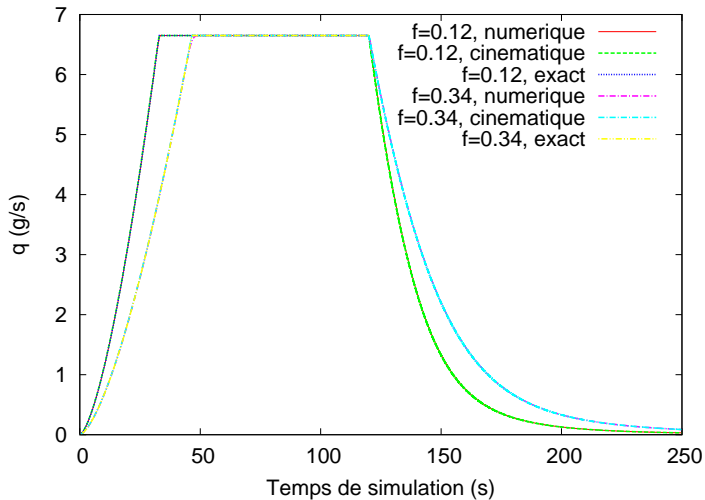
Settings of the experiment



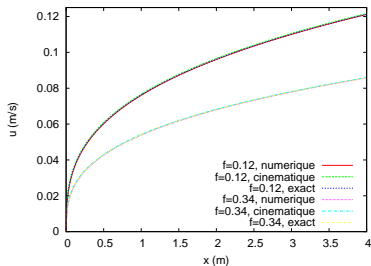
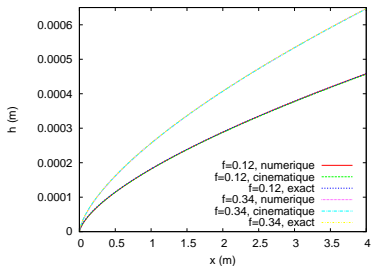
$$0 \leq t \leq 250\text{s}$$

$$R(x, t) = \begin{cases} 50 \text{ mm/h} & \text{if } (x, t) \in [0, L] \times [5, 125] \\ 0 & \text{else} \end{cases}$$

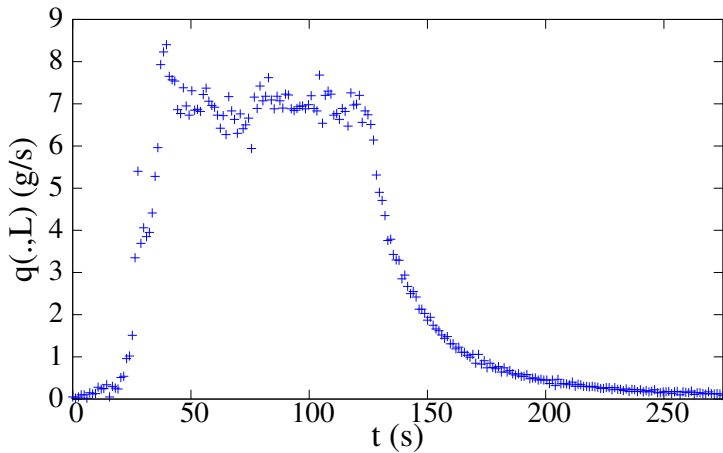
Analytical solutions and simulations



Water height and velocity at equilibrium

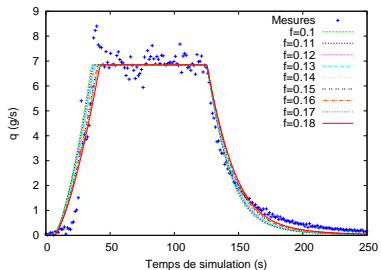


What about reality ?

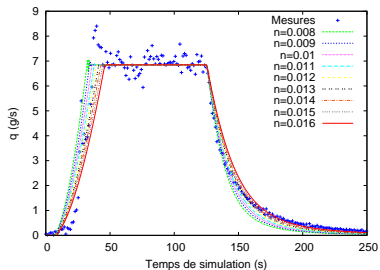


"Calibration"

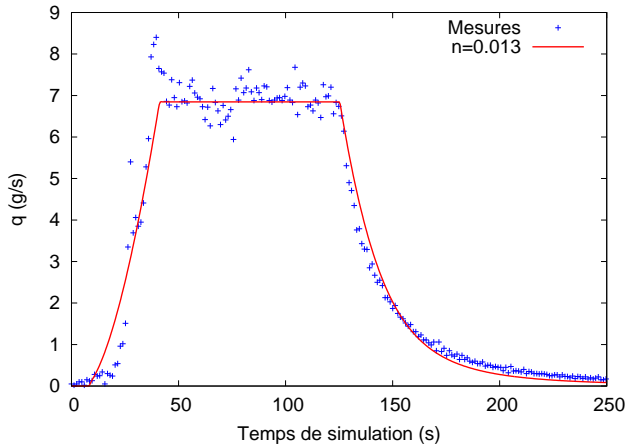
Darcy-Weisbach



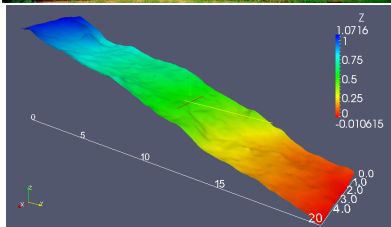
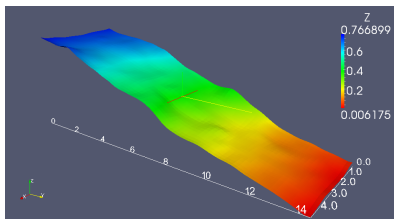
Manning



A simulation result (Manning)

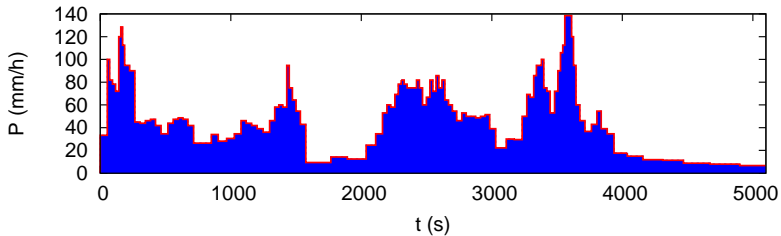


Parcels in Niger ([Esteves et al., 2000], IRD)

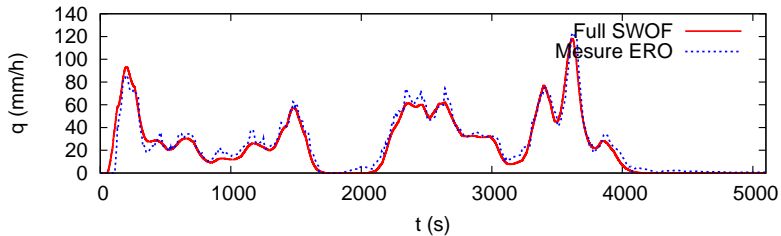


Darcy-Weisbach

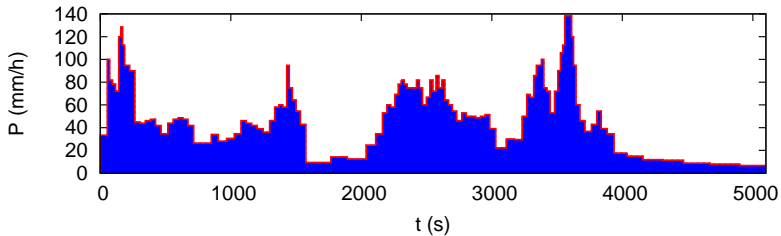
Hyetogramme



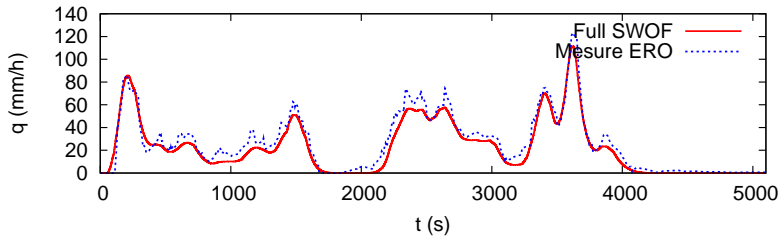
Hydrogramme



Hyetogramme



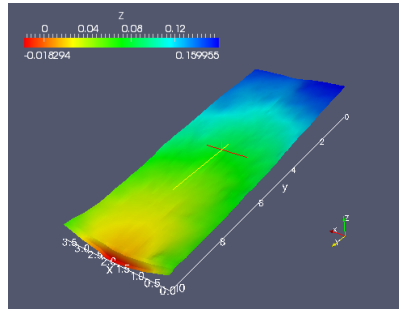
Hydrogramme



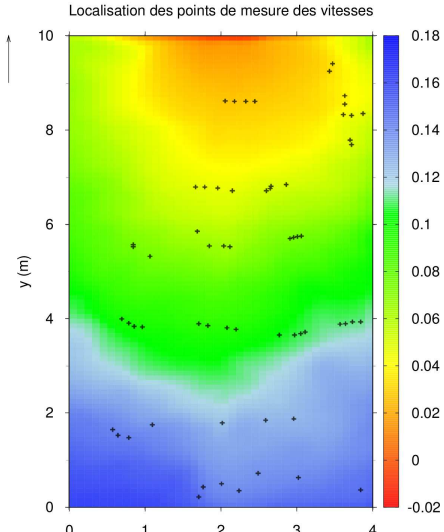
Thies parcel – Senegal ([Tatard et al., 2008], IRD)

Velocity measures by SVG [Planchon et al., 2005]

Number of cells : 40×100 (4 m \times 10 m)

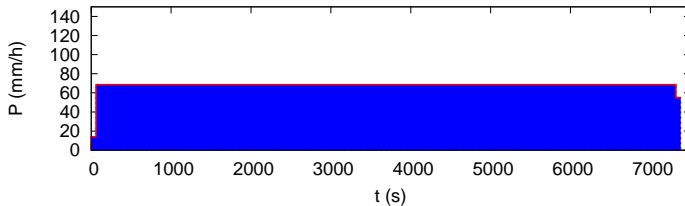


Thies parcel – Senegal ([Tatard et al., 2008], IRD)

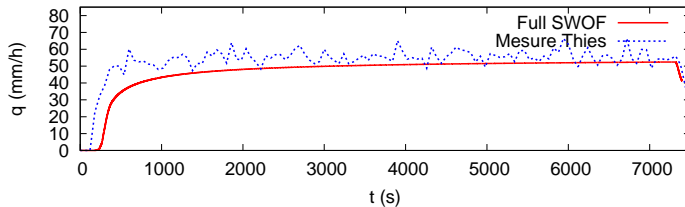


Thies parcel – Senegal ([Tatard et al., 2008], IRD)

Hyetogramme

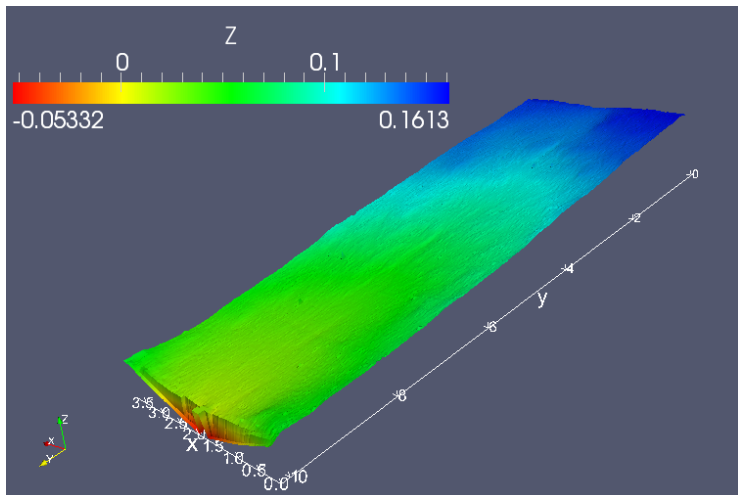


Hydrogramme



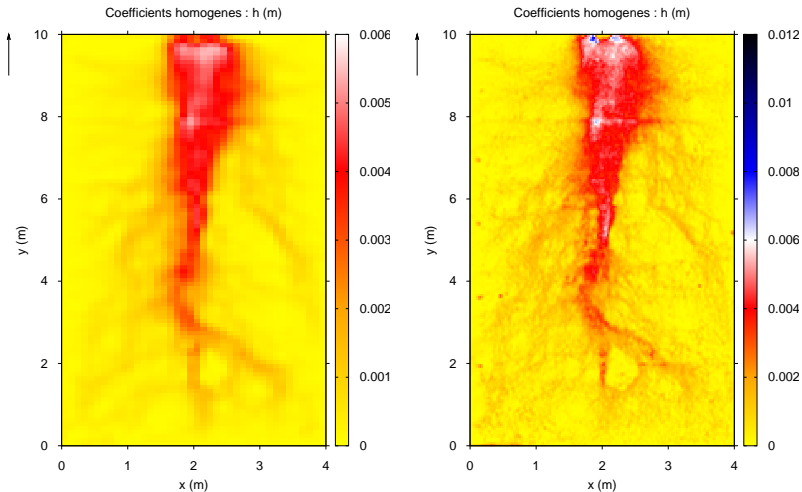
Thies parcel – Senegal ([Tatard et al., 2008], IRD)

Number of cells : 160×200



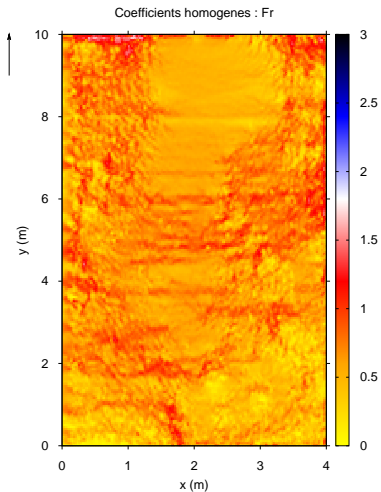
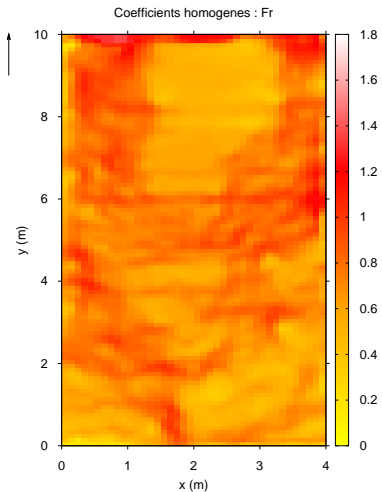
Thies parcel – Senegal ([Tatard et al., 2008], IRD)

Homogeneous coefficients



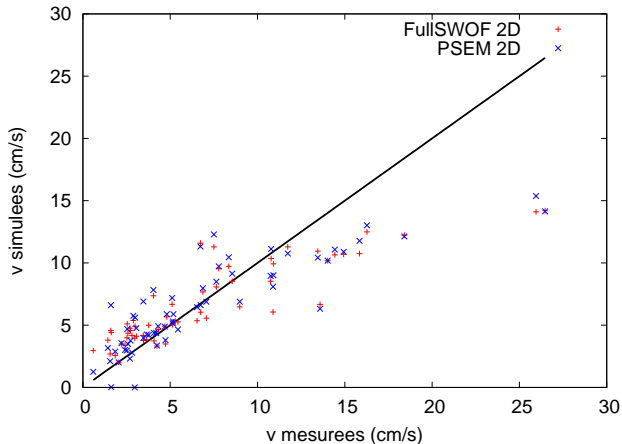
Thies parcel – Senegal ([Tatard et al., 2008], IRD)

Homogeneous coefficients



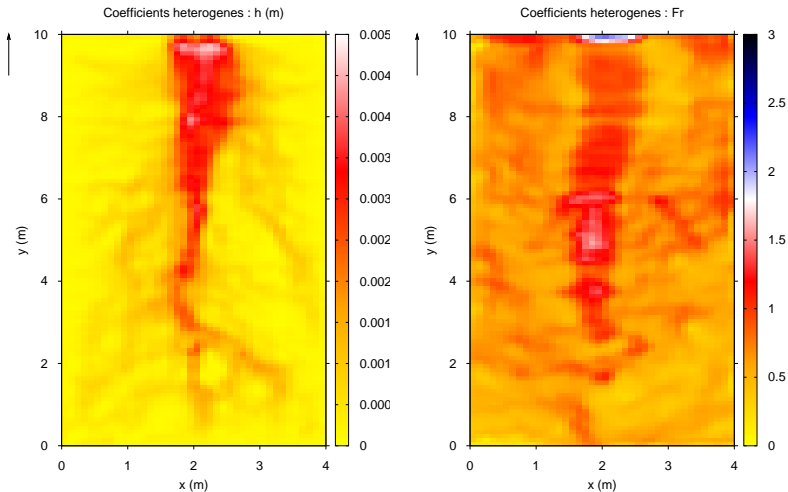
Thies parcel – Senegal ([Tatard et al., 2008], IRD)

Velocities



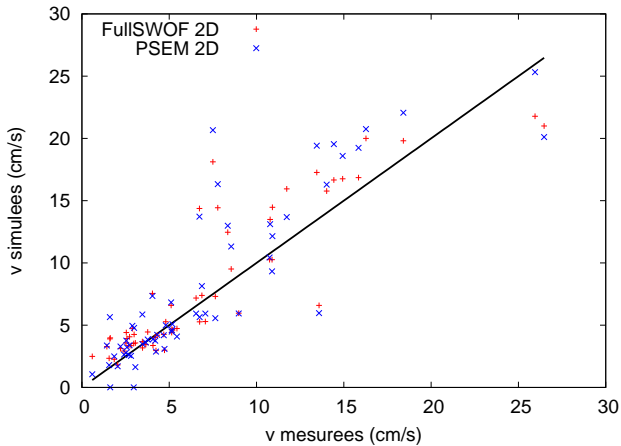
Thies parcel – Senegal ([Tatard et al., 2008], IRD)

Heterogeneous coefficients



Thies parcel – Senegal ([Tatard et al., 2008], IRD)

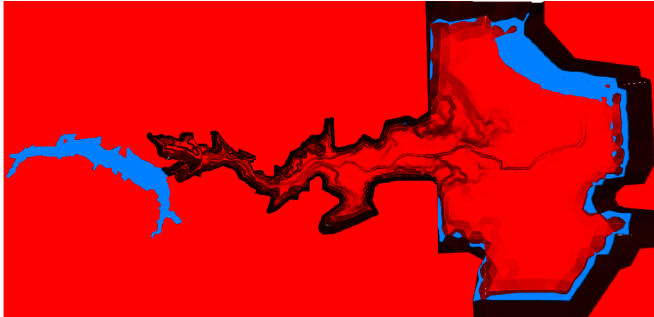
Velocities



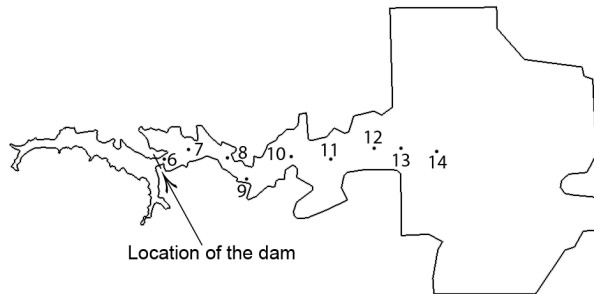
FuIIISWOF

- ▶ object and inheritance
- ▶ variables encapsulation
- ▶ vector class (2d)
- ▶ objects "distributor"
- ▶ fixed CFL and fixed Δt
- ▶ Doxygen documentation
- ▶ Free open source software

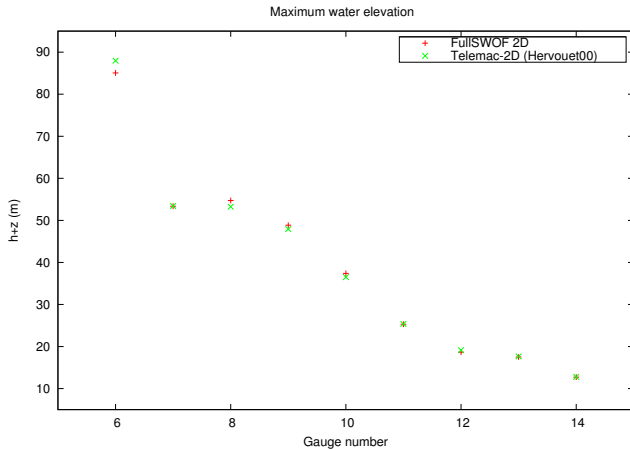
Malpasset dam break simulation (Cordier et al., CEMRACS 2012)



Malpasset dam break simulation



Malpasset dam break simulation



Thank You!

HLL flux

$$\mathcal{F}(U_G, U_D) = \begin{cases} F(U_G) & \text{if } 0 < c_1 \\ F(U_D) & \text{if } c_2 < 0 \\ \frac{c_2 F(U_G) - c_1 F(U_D)}{c_2 - c_1} + \frac{c_1 c_2 (U_D - U_G)}{c_2 - c_1} & \text{else} \end{cases},$$

with two parameters

$$c_1 < c_2.$$

For c_1 and c_2 , we take

$$c_1 = \inf_{U=U_G, U_D} \left(\inf_{j \in \{1,2\}} \lambda_j(U) \right) \text{ and } c_2 = \sup_{U=U_G, U_D} \left(\sup_{i \in \{1,2\}} \lambda_i(U) \right).$$

with $\lambda_1(U) = u - \sqrt{gh}$ and $\lambda_2(U) = u + \sqrt{gh}$. [▶ retour](#)



Audusse, E., Bouchut, F., Bristeau, M.-O., Klein, R., and Perthame, B. (2004).

A fast and stable well-balanced scheme with hydrostatic reconstruction for shallow water flows.

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Nonlinear stability of finite volume methods for hyperbolic conservation laws, and well-balanced schemes for sources, volume 2/2004.

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Boundary conditions for the shallow water equations solved by kinetic schemes.

[Technical Report 4282, INRIA](#).



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[J. Sci. Comput.](#), DOI 10.1007/s10915-010-9393-y.



Esteves, M., Faucher, X., Galle, S., and Vauclin, M. (2000).

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Planchon, O., Silvera, N., Gimenez, R., Favis-Mortlock, D., Wainwright, J., Le Bissonnais, Y., and Govers, G. (2005).

An automated salt-tracing gauge for flow-velocity measurement.

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Tatard, L., Planchon, O., Wainwright, J., Nord, G., Favis-Mortlock, D., Silvera, N., Ribolzi, O., Esteves, M., and Huang, C.-h. (2008).

Measurement and modelling of high-resolution flow-velocity data under simulated rainfall on a low-slope sandy soil.

[Journal of Hydrology](#), 348(1-2) :1–12.