On the regularity of a free boundary for a nonlinear obstacle problem arising in superconductor modelling.

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Résumé

Nous étudions les frontières libres asociées à des solutions d'une classe de problèmes de l'obstacle non linéaires. Cette classe de problèmes contient un modèle particulier dérivé des équations de Ginzburg-Landau de la supraconductivité. Nous considérons des solutions dans un ouvert borné Ω à bord Lipschitz, et nous prouvons que la frontière libre est régulière lorsque celle-ci est suffisamment proche du bord fixe $\partial\Omega$. Nous prouvons aussi un résultat de stabilité de la frontière libre et donnons une borne a priori sur la mesure de Hausdorff de cette frontière libre.

Abstract

We study the free boundary of solutions to a class of nonlinear obstacle problems. This class of problems contains a particular model derived from the Ginzburg-Landau equation of superconductivity. We consider solutions in a Lipschitz bounded open set Ω and prove the regularity of the free boundary when it is close enough to the fixed boundary $\partial\Omega$. We also give a result of stability of the free boundary and give a bound on the Hausdorff measure of the free boundary.

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1 Introduction

In this article we are interested in solutions to a nonlinear obstacle problem. This problem is motivated by a work of Chapman, Rubinstein, Schatzman [13] where a model is formally derived from the Ginzburg-Landau theory for a superconductor with a density of vortices in an interior region whose boundary is a free boundary. A rigorous derivation of this model has been done by Sandier, Serfaty [23]. Se also [4, 12, 25, 24] for some related works on the mathematical analysis of superconductivity. Here we will prove rigorous results on the regularity of the free boundary contained in a Lipschitz domain. The core of the technical part of this article is an adaptation in the framework of the nonlinear obstacle problem on non-smooth domains of Caffarelli-type techniques [8, 9] originally developed for linear obstacle problems on smooth domains.

The model that we consider in this paper is a nonlinear obstacle problem in a Lipschitz bounded open set $\Omega \subset \mathbf{R}^n$. We are interested in the minimization of the energy

$$E(u) = \int_{\Omega} F(|\nabla u|^2) + u^2$$

on the convex set

$$K_{\lambda} = \left\{ u \in H^1(\Omega), \quad u \ge \lambda \quad \text{on} \quad \Omega, \quad u = \lambda_0 \quad \text{on} \quad \partial \Omega \right\}$$

where $0 \le \lambda \le \lambda_0$ are two constants. We make the following assumption (which implies that the energy *E* is strictly convex)

(A0) F is a C^{∞} convex function satisfying F'(0) = 1 and $\lim_{q \to +\infty} F'(q) < +\infty$.

It is classical that for each λ there exists a unique minimizer u_{λ} of the energy E on K_{λ} . For such a minimizer the coincidence set is

$$\{u = \lambda\}$$

and the free boundary is

$$\partial \{u = \lambda\}$$

When the free boundary $\partial \{u = \lambda\}$ is smooth, the solution u satisfies the following Euler-Lagrange equation

$$\begin{cases} div \left(F'(|\nabla u|^2) \nabla u \right) = u \quad \text{on} \quad \Omega \setminus \{u = \lambda\} \\ u = \lambda_0 \quad \text{on} \quad \partial \Omega \\ u = \lambda \\ \frac{\partial u}{\partial n} = 0 \end{cases} \quad \text{on} \quad \partial \{u = \lambda\} \end{cases}$$

Although there are two boundary conditions on the free boundary, the problem is not overdeterminated. These two boundary conditions allow to characterize the free boundary $\partial \{u = \lambda\}$ which is an unknown in this problem.

We refer the reader to the monographs [17, 14, 22] for a presentation of the classical results on the free boundary of the obstacle problem.

1.1 Main results

Our main result (for a smooth open set and in the linear case) is the following :

Theorem 1.1 (Regularity transfer from the fixed boundary to the free boundary)

Let us assume that the open set Ω is smooth, and that F(q) = q, then the energy E has a unique minimizer u_{λ} on K_{λ} for all $\lambda \in [0, \lambda_0]$. Moreover there exists $\delta > 0$ such that for all $\lambda \in (\lambda_0 - \delta, \lambda_0)$, the free boundary $\partial \{u_{\lambda} = \lambda\}$ is a C^{∞} (n-1)-dimensional manifold homeomorphic to $\partial \Omega$. Although this result seems very natural, it was an open problem (even in this linear case), that we solve here applying the approach of blow-ups developed by Caffarelli [8] for the regularity of the free boundary of the obstacle problem. Under the assumption that $\partial \Omega \in C^{\infty}$, a nonlinear variant of theorem 1.1 was proved in [5] by A. Bonnet and the author, using the Nash-Moser inverse function theorem in dimension 2. This Nash-Moser approach could work in fact in any dimensions, but it can not be applied to a fixed boundary $\partial \Omega$ less regular than C^{∞} . On the contrary the approach of Caffarelli [8] allows to deal with non-smooth fixed boundaries $\partial \Omega$.

We extend theorem 1.1 to Lipschitz open set Ω and for general convex functions F satisfying assumption (A0). More precisely we make the following two assumptions on the regularity of Ω :

(A1) Exterior sphere condition:

There exists $r_0 > 0$ such that for every point X_0 of the boundary $\partial \Omega$, there exists a point $X_1 \in \mathbf{R}^n$, such that the ball $B_{r_0}(X_1)$ is included in $\mathbf{R}^n \setminus \Omega$ and is tangent to $\partial \Omega$ at X_0 .

(A2) Interior cone condition:

There exist $r_0 > 0$ and an angle $\alpha_0 \in (0, \frac{\pi}{2})$ such that for every point X_0 of the boundary $\partial\Omega$, there exists a unit vector $\nu \in \mathbf{S}^{n-1}$, such that Ω contains the cone

$$\left\{ X \in B_{r_0}(X_0), \quad < \frac{X - X_0}{|X - X_0|}, \nu > \ge \ \cos \alpha_0 \right\}$$

where $\langle \cdot, \cdot \rangle$ is the usual scalar product. Theorem 1.1 is a corollary of the following more general result:

Theorem 1.2 (Regularity transfer from a Lipschitz fixed boundary)

Under assumptions (A0)-(A1)-(A2), the energy E has a unique minimizer u_{λ} on K_{λ} for all $\lambda \in [0, \lambda_0]$. Moreover there exists $\delta > 0$ such that for all $\lambda \in (\lambda_0 - \delta, \lambda_0)$, the free boundary $\partial \{u_{\lambda} = \lambda\}$ is a C^{∞} (n-1)-dimensional manifold homeomorphic to $\partial \Omega$. In the application that we have in mind, namely a nonlinear free boundary problem arising in the description of superconductors in dimension two (see Bonnet, Monneau [5], Berestycki, Bonnet, Chapman [2]), the function F_0 is analytic convex but only defined on $[0, \frac{4}{27})$ by $F'_0(0) = 1$ and

$$h = (1 - v^2)v \iff v = F'_0(h^2)h$$

Using a L^{∞} control on the gradient of the solution we deduce the following result in this particular case:

Corollary 1.3 (Application to a superconducting model)

Under assumption (A1)-(A2), with $F = F_0$, there exists $\delta > 0$ such that $\forall \lambda \in (\lambda_0 - \delta, \lambda_0)$, there exists a unique solution u_{λ} minimizer of E on K_{λ} satisfying $\sup_{\overline{\Omega}} |\nabla u_{\lambda}|^2 < \frac{4}{27}$; moreover the free boundary $\partial \{u_{\lambda} = \lambda\}$ is a C^{∞} (n-1)-dimensional manifold homeomorphic to $\partial \Omega$.

Let us mention that part of the methods of [20] could be adapted to this model of superconductivity to get informations on the singularities of the free boundary when $\lambda < \lambda_0 - \delta$.

We also prove a result on the perturbation (locally in space) of the free boundary.

Theorem 1.4 (Local stability of the free boundary)

We assume (A0)-(A1)-(A2). Let $\lambda^* \in (0, \lambda_0)$ be such that there exists a minimizer u_{λ^*} of the energy E on K_{λ^*} with a free boundary $\partial \{u_{\lambda^*} = \lambda^*\}$ which is C^{∞} in a compact set \mathcal{K}^* of Ω . Then for every smaller compact set $\mathcal{K} \subset \subset \mathcal{K}^*$ there exists $\varepsilon > 0$ such that for every λ satisfying $|\lambda - \lambda^*| < \varepsilon$, the unique solution u_{λ} has a free boundary $\partial \{u_{\lambda} = \lambda\}$ which is C^{∞} in \mathcal{K} .

The proof of this result is based on a geometric criterion for the regularity of the free boundary given by Caffarelli in [8] and on the continuity of the map $\lambda \mapsto u_{\lambda}$. We also refer to the book of Rodrigues [22] for classical results on the global stability of the free boundary.

Finally we give a bound on the Hausdorff measure of the free boundary, generalizing to non-smooth fixed boundaries $\partial\Omega$, a result of Brezis, Kinderlehrer [6] based on fine estimates for variational inequalities. Here the proof is an adaptation of the work of Caffarelli [9], developed for linear equations.

Theorem 1.5 (Bound on the Hausdorff measure of the free boundary)

Under assumptions (A0)-(A1)-(A2), there exists a constant C > 0 only depending on Ω, λ_0, F such that for any minimizer u_{λ} of E on K_{λ} with $\lambda \in [0, \lambda_0]$, we have

$$\mathcal{H}^{n-1}\left(\partial\left\{u_{\lambda}=\lambda\right\}\right) \leq C$$

2 Some known results on blow-up limits

2.1 The simple blow-up limit

To prove regularity results on the free boundary, the main tool (first introduced for the obstacle problem by Caffarelli in [10]) is the notion of blow-up.

Let us consider a solution u to

$$\begin{cases} \Delta u = f \ge 1 \quad \text{on} \quad \{u > 0\} \cap \Omega \\ \\ u \ge 0 \quad \text{on} \quad \Omega \quad \text{and} \quad |D^2 u|_{L^{\infty}(\Omega)} \le M \end{cases}$$
(2.1)

with $f \in C^{0,\alpha}(\Omega)$ and f(0) = 1. We assume that X_0 is a point of the free boundary $\partial \{u = 0\}$. Let us consider the following blow-up sequence of functions

$$u^{\varepsilon}(X) = \frac{u(X_0 + \varepsilon X)}{\varepsilon^2}$$

By assumptions, $u^{\varepsilon}(0) = \nabla u^{\varepsilon}(0) = 0$ and the second derivatives $|D^2 u^{\varepsilon}|$ are bounded by a constant independent on $\varepsilon > 0$. By Ascoli-Arzela theorem, up to extraction of a convergent subsequence (ε'), we get

$$u^{\varepsilon'} \longrightarrow u^0$$
 uniformly on compact sets of \mathbf{R}^n

This function u^0 is called a blow-up limit of the function u at the point X_0 .

In any dimensions, the main result for blow-up limits is the following

Theorem 2.1 (Caffarelli [10, 8, 11], Weiss [26]; Characterization of a Simple Blow-up Limit)

The blow-up limit u^0 is unique and only depends on the point X_0 on the free boundary. Moreover either X_0 is a singular point and then u^0 is a quadratic form, i.e.

$$u^0(X) = \frac{1}{2} \quad {}^t X \cdot Q_{X_0} \cdot X \ge 0$$

where Q_{X_0} is a symmetric matrix $n \times n$ such that $tr \ Q_{X_0} = 1$.

Or X_0 is a **regular** point and then there exists a unit vector $\nu_{X_0} \in \mathbf{S}^{n-1}$ such that

$$u^{0}(X) = \frac{1}{2} \left(\max\left(\langle X, \nu_{X_{0}} \rangle, 0 \right) \right)^{2}$$

and the free boundary is a C^1 (n-1)-dimensional manifold in a neighbourhood of X_0 .

The regularity C^1 can then be improved by Kinderlehrer, Nirenberg results [16], and gives C^{∞} regularity for an obstacle problem where the elliptic operator has C^{∞} coefficients. It is also possible to get similar results with analyticity of the solutions when the coefficients are analytic.

2.2 More general blow-up limits

We now recall a result which characterizes the limits of some more general blow-up sequences where the origin moves with the scaling.

Lemma 2.2 (General Blow-up Limits, [8])

Let

$$u^{\varepsilon}(X) = \frac{u_{\varepsilon}(X_{\varepsilon} + \varepsilon X)}{\varepsilon^2}$$

where u_{ε} is a sequence of solutions to

$$\begin{cases} \Delta u_{\varepsilon} = f_{\varepsilon} \ge 1 \quad on \quad \{u_{\varepsilon} > 0\} \cap \Omega_{\varepsilon} \\ \\ u_{\varepsilon} \ge 0 \quad on \quad \Omega_{\varepsilon} \quad and \quad |D^{2}u_{\varepsilon}|_{L^{\infty}(\Omega_{\varepsilon})} \le M \end{cases}$$

with $|f_{\varepsilon}|_{C^{0,\alpha}(\Omega_{\varepsilon})} \leq M$. We assume that $u_{\varepsilon}(X_{\varepsilon}) = 0$ and that $\frac{1}{\varepsilon}d(X_{\varepsilon},\partial\Omega_{\varepsilon}) \geq r > 0$ as $\varepsilon \to 0$. Then up to extraction of a convergent subsequence (ε') , we get

$$u^{\varepsilon'} \longrightarrow u^0$$
 uniformly on compact sets of Ω^0

for some open set Ω^0 and where u^0 is convex and satisfies

$$\begin{cases} \Delta u^0 = f_0(0) \ge 1 \quad on \quad \left\{ u^0 > 0 \right\} \cap \Omega^0 \\ u^0 \ge 0 \quad on \quad \Omega^0 \quad and \quad |D^2 u^0|_{L^{\infty}(\Omega^0)} \le M \end{cases}$$

Moreover either

i) the interior of the coincidence set of the blow-up limit is empty:

$$\{u^0=0\}^0=\emptyset$$

Or

ii) the interior of the coincidence set of the blow-up limit satisfies

$$\{u^0 = 0\}^0 \neq \emptyset$$

and 0 is a regular point for u^0 and also for all $u^{\varepsilon'}$ with ε' small enough.

Another useful result is the following nondegeneracy property of the solution:

Lemma 2.3 (Nondegeneracy, [8])

Let u be a solution to problem (2.1) and $0 \in \overline{\{u > 0\}}$. If $B_r(0) \subset \Omega$, then

$$\sup_{B_r(0)} \left(u(X) - u(0) \right) \ge \frac{r^2}{2n}$$

Proof of lemma 2.3. Apply the maximum principle to $w(X) = u(X) - u(0) - \frac{1}{2n}|X|^2$ in $B_r(0) \cap \{u > 0\}$.

3 A bound on the second derivatives

In this section we will prove the following result

Proposition 3.1 (Control near the fixed boundary $\partial \Omega$)

Under the assumptions of theorem 1.2, let us define $\varepsilon = \sqrt{2\left(\frac{\lambda_0 - \lambda}{\lambda}\right)}$. Then there exist constants C, c > 0 such that for all $\lambda \in [0, \lambda_0]$ we have

$$u_{\lambda}(X) - \lambda \geq c\varepsilon^2 \quad on \quad \{X \in \Omega, \quad dist(X, \partial\Omega) \leq c\varepsilon\}$$

$$(3.1)$$

$$|\nabla u_{\lambda}(X)| \leq C\varepsilon \quad on \quad \Omega \tag{3.2}$$

and for all $\delta \in (0, 1]$

$$|D^2 u_{\lambda}(X)| \leq C/\delta^2 \quad on \quad \{X \in \Omega, \quad dist(X, \partial\Omega) \geq c\varepsilon\delta\}$$
 (3.3)

Moreover we have

$$div\left(F'(|\nabla u_{\lambda}|^{2})\nabla u_{\lambda}\right) = u_{\lambda} \ 1_{\{u_{\lambda} > \lambda\}} \quad on \quad \Omega$$

where for the function $u_{\lambda} \geq \lambda$ we define

$$1_{\{u_{\lambda}>\lambda\}}(X) = \begin{cases} 1 & \text{if } u_{\lambda}(X) > \lambda \\ 0 & \text{if } u_{\lambda}(X) = \lambda \end{cases}$$

Remark 3.2 For a smooth Ω , some L^{∞} bounds on the second derivatives are given in [6] for fixed λ . Here we need to precise the dependence of the constants as λ goes to λ_0 . The exterior sphere condition gives a control (3.1) from below on u_{λ} , and with the help of Harnack inequality we get the L^{∞} bounds (3.3) on the second derivatives up to the case $\lambda = \lambda_0$. Because the fixed boundary $\partial\Omega$ is not smooth here, the bound (3.3) on the second derivatives goes to infinity when the point reaches the fixed boundary $\partial\Omega$ (case $\delta = 0$).

We consider the minimizer u_{λ} of the convex energy

$$E(u) = \int_{\Omega} F(|\nabla u|^2) + u^2$$

on the convex set

$$K_{\lambda} = \{ u \in H^1(\Omega), \quad u \ge \lambda \quad \text{on} \quad \Omega, \quad u = \lambda_0 \quad \text{on} \quad \partial \Omega \}$$

We first prove that the minimizer u_λ satisfies the following Euler-Lagrange equation

Lemma 3.3 (Euler-Lagrange equation)

$$div\left(F'(|\nabla u_{\lambda}|^{2})\nabla u_{\lambda}\right) = u_{\lambda} \ 1_{\{u_{\lambda} > \lambda\}} \quad on \quad \Omega$$

Although this result seems natural, we do not know any references where it is proved (except in the linear case). We give a complete proof below.

Proof of lemma 3.3

Let

$$(s)^{+} = \begin{cases} s & \text{if } s > 0 \\ 0 & \text{if } s \le 0 \end{cases}$$

Then the minimization of E on K_{λ} is equivalent to the minimization of the convex energy

$$E_{\lambda}(u) = \int_{\Omega} F(|\nabla u|^2) + \left((u - \lambda)^+ + \lambda \right)^2$$

on the convex set

$$K = \left\{ u \in H^1(\Omega), \quad u = \lambda_0 \quad \text{on} \quad \partial \Omega \right\}$$

Because u_{λ} is the minimizer of E_{λ} on K, we have for every $\varphi \in C_0^{\infty}(\Omega)$ and $t \in [0, 1]$:

$$E_{\lambda}(u_{\lambda} + t\varphi) \ge E_{\lambda}(u_{\lambda})$$

Then Lebesgue's dominated convergence theorem gives

$$0 \leq \lim_{t \to 0} \left(\frac{E_{\lambda}(u_{\lambda} + t\varphi) - E_{\lambda}(u_{\lambda})}{t} \right)$$
$$= \int_{\Omega} 2F' \left(|\nabla u_{\lambda}|^{2} \right) \nabla u_{\lambda} \nabla \varphi + 2 u_{\lambda} \left(\varphi \operatorname{sgn}^{+}(u_{\lambda} - \lambda) + \varphi^{+} \left(1 - \operatorname{sgn}^{+}(u_{\lambda} - \lambda) \right) \right)$$

where

$$\operatorname{sgn}^+(s) = \begin{cases} 1 & \text{if } s > 0 \\ \\ 0 & \text{if } s \le 0 \end{cases}$$

Considering φ and $-\varphi$ we get that div $(F'(|\nabla u_{\lambda}|^2)\nabla u_{\lambda}) \in L^{\infty}(\Omega)$. Using the regularity theory for elliptic equations (see [21]) we deduce that $u \in C_{loc}^{1,\alpha}(\Omega)$. Consequently $\{u_{\lambda} > \lambda\}$ is an open set and the Euler-Lagrange equation is satisfied on this open set. Furthermore a classical argument using the nondegeneracy lemma 2.3 proves that the Lebesgue measure of the free boundary $\partial \{u_{\lambda} = \lambda\}$ is zero. This implies the full Euler-Lagrange equation. This ends the proof of lemma 3.3.

Let us recall that when Ω is smooth, there exists a constant $C_0 > 0$ such that for each $\lambda \in [0, \lambda_0]$ we have the following properties (see Brézis, Kinderlehrer [6]): (H1)

$$|\nabla u_{\lambda}(X)| \le C_0 \quad \text{on} \quad \Omega$$

(H2)

$$u \in C^{1,1}_{loc}(\Omega)$$

In a first case we will prove proposition 3.1 assuming (H1)-(H2), and in a second case we will justify these assumptions.

Case A: we assume (H1)-(H2) and that $\partial \Omega$ is smooth.

Step 1: proof of (3.1)

We will build a subsolution u_0 such that (for some point X_{ε} which will be precised below)

$$\frac{u_{\lambda}(X) - \lambda}{\lambda} \geq \varepsilon^2 u_0 \left(\frac{|X - X_{\varepsilon}|}{\varepsilon}\right) \quad \text{for} \quad \frac{|X - X_{\varepsilon}|}{\varepsilon} \in [r_0, r_0 + \tau_0] \quad (3.4)$$

with $\varepsilon = \sqrt{2\left(\frac{\lambda_0 - \lambda}{\lambda}\right)}.$

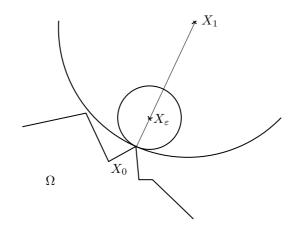


Figure 1: Construction of a subsolution outside the ball $B_{|X_0-X_\varepsilon|}(X_\varepsilon)$

For some $\tau_0 > 0$, we consider a solution u_0 of

$$\Delta u_0 = \mu > 1 \quad \text{on} \quad B_{r_0+\tau_0}(0) \setminus B_{r_0}(0)$$
$$u_0 = \frac{1}{2} \quad \text{on} \quad \partial B_{r_0}(0)$$
$$u_0 = 0 \quad \text{on} \quad \partial B_{r_0+\tau_0}(0)$$

By symmetry we have $u_0(X) = u_0(|X|)$. Let us recall that for each point $X_0 \in \partial\Omega$, there exists $X_1 \in \mathbf{R}^n$, such that $B_{r_0}(X_1)$ is included in $\mathbf{R}^n \setminus \Omega$ and is tangent to $\partial\Omega$ at X_0 . Now considering the function u_{λ} at a scale close to the fixed boundary $\partial\Omega$ we introduce the point $X_{\varepsilon} = X_0 + \varepsilon (X_1 - X_0)$ and the following function (see figure 1)

$$w^{\varepsilon}(X) = \frac{u_{\lambda}(X_{\varepsilon} + \varepsilon X) - \lambda}{\lambda \varepsilon^2}$$

which satisfies on $\frac{\Omega - X_{\varepsilon}}{\varepsilon}$:

$$\begin{cases} A_{\varepsilon}(w^{\varepsilon}) \leq 1\\ 0 \leq w^{\varepsilon} \leq \frac{1}{2} \end{cases}$$

where the quasilinear elliptic partial differential operator A_{ε} is defined in (4.1). Moreover for a good choice of $\mu > 1, \tau_0 > 0$, we have on $B_{r_0+\tau_0}(0) \setminus B_{r_0}(0)$:

$$\begin{cases} A_{\varepsilon}(u_0) \ge 1\\ 0 \le u_0 \le \frac{1}{2} \end{cases}$$

Then by the Maximum Principle (see Berestycki, Nirenberg [3]), we can slide u_0 below w^{ε} and we get

$$w^{\varepsilon} \ge u_0$$
 on $B_{r_0+\tau_0}(0) \setminus B_{r_0}(0)$

This is equivalent to (3.4) whose we deduce (3.1). This ends the proof of step 1.

Step 2: proof of (3.2): estimate on the gradient : $|\nabla u_{\lambda}| \leq \lambda \varepsilon |u'_0(r_0)|$

We first remark that a straightforward consequence of step 1 is that

$$\limsup_{X \to \partial \Omega} \left(\frac{\lambda_0 - u_\lambda}{\operatorname{dist} \left(X, \partial \Omega \right)} \right) \leq \lambda \varepsilon |u_0'(r_0)|$$

From the fact that $u = constant = \lambda_0$ on $\partial\Omega$, we deduce that $|\nabla u| \leq \lambda \varepsilon |u'_0(r_0)|$ on $\partial\Omega$. Now the estimate on the gradient comes from the fact that the gradient is maximal on the boundary $\partial\Omega$. For the convenience of the reader we recall this classical argument. For $u = u_{\lambda}$, we have

$$a_{ij} (\nabla u) u_{ij} = u \quad \text{on} \quad \Omega \setminus \{u = \lambda\}$$

where $a_{ij}(p) = F'(|p|^2)\delta_{ij} + 2F''(|p|^2)p_ip_j$. Let us take $v = \partial_{\xi} u$ where $\xi \in \mathbf{S}^{n-1}$. Then

$$a_{ij}v_{ij} + b_k v_k = v \quad \text{on} \quad \Omega \setminus \{u = \lambda\}$$

where $b_k = (a_{ij})'_{p_k} \cdot u_{ij}$. The Maximum Principle implies that $v = \partial_{\xi} u$ is maximal on $\partial \Omega \cup \partial \{u = \lambda\}$. Taking all directions $\xi \in \mathbf{S}^{n-1}$ we deduce that $|\nabla u|$ is maximal on $\partial \Omega$, because $\nabla u = 0$ on $\partial \{u = \lambda\}$.

This ends the proof of step 2.

Step 3: proof of (3.3)

Let

$$w(X) = \frac{u_{\lambda}(\varepsilon X) - \lambda}{\lambda \varepsilon^2}$$

Then

$$\begin{cases} A_{\varepsilon}(w) = 1 & \text{on} \quad \{w > 0\} \\ \\ 0 \le w \le \frac{1}{2} \end{cases}$$

where the operator A_{ε} is defined in (4.1). Let $Y_0 \in \frac{\Omega}{\varepsilon}$ such that dist $(Y_0, \frac{\partial\Omega}{\varepsilon}) \geq c$. We will prove a bound on $|D^2w(Y_0)|$. To this end we will apply the method of Alt and Phillips [1], using the following Harnack inequality of Krylov, Safonov for non-divergence operator (a similar Harnack inequality for divergence operator is also applicable, see Gilbarg, Trudinger [15]):

Theorem 3.4 (Harnack inequality for non-divergence operators; [7]) If

$$\begin{cases} a_{ij}v_{ij} = f \quad on \quad B_1 \subset \mathbf{R}^n \\ v \ge 0 \quad on \quad B_1 \end{cases}$$

and for the matrix $a = (a_{ij})$

$$0 < c_0 \le a \le C_0$$

then there exists a constant $C = C(n, C_0, c_0) > 0$ such that

$$\sup_{B_{\frac{1}{2}}} v \le C\left(\inf_{B_{\frac{1}{2}}} v + |f|_{L^{n}(B_{1})}\right)$$

We will also use the following interior estimate:

Theorem 3.5 (Interior estimate, [15])

Let us assume that

$$a_{ij}v_{ij} + cv = f$$
 on $B_r \subset \mathbf{R}^r$

and for the matrix $a = (a_{ij})$

 $0 < c_0 \le a$

If for some $\alpha \in (0,1)$ there exists a constant $C_0 > 0$ such that

$$|a_{ij}|_{L^{\infty}(B_r)} + r^{\alpha}[a_{ij}]_{\alpha;B_r} + r^2|c|_{L^{\infty}(B_r)} + r^{2+\alpha}[c]_{\alpha;B_r} \le C_0$$

where $[\cdot]_{\alpha;B_r}$ is defined by

$$[g]_{\alpha;B_r} = \sup_{x,y\in B_r, x\neq y} \left(\frac{|g(x) - g(y)|}{|x - y|^{\alpha}}\right)$$

Then

$$r^{2}|D^{2}v|_{L^{\infty}(B_{\frac{r}{2}})} \leq C\left(|v|_{L^{\infty}(B_{r})} + r^{2}|f|_{L^{\infty}(B_{r})} + r^{2+\alpha}[f]_{\alpha;B_{r}}\right)$$

for some constant $C = C(n, \alpha, C_0, c_0) > 0$.

Let $w_r(X) = w(Y_0 + rX)$. Applying Harnack inequality theorem 3.4 to w_r we get

$$\sup_{B_{\frac{r}{2}}(Y_0)} w \le C\left(\inf_{B_{\frac{r}{2}}(Y_0)} w + r^2\right)$$
(3.5)

Let

$$\rho = \sqrt{\frac{w(Y_0)}{2C}}$$

i) Case $\rho < c\delta$.

Then Y_0 is close to $\{w = 0\}$ and ρ can be arbitrarily small. We apply Harnack inequality (3.5) with $r = \rho$ and we get

$$0 < w(Y_0) \le \sup_{B_{\frac{\rho}{2}}(Y_0)} w \le 2C \inf_{B_{\frac{\rho}{2}}(Y_0)} w$$

Let us remark that we have (see theorem 6.1, p. 281 of Ladyshenskaya, Ural'tseva [18])

$$[w]_{\alpha;B_1} \le C$$

where the constant C has the following dependence $C = C(n, \alpha, |w|_{L^{\infty}(B_2)}, F, \lambda_0, r_0) > 0$. Then applying theorem 3.5, we deduce that

$$r^{2}|D^{2}w|_{L^{\infty}\left(B_{\frac{r}{2}(Y_{0})}\right)} \leq C\left(|w|_{L^{\infty}(B_{r}(Y_{0}))} + r^{2}\right)$$

With the choice $r = \rho$, this implies

$$|D^2 w(Y_0)| \le C$$

ii) case $\rho \ge c\delta$.

We apply the previous interior estimate with $r = c\delta$. Using the fact that $|w| \leq \frac{1}{2}$, we find

$$|D^2 w(Y_0)| \le C/\delta^2$$

iii) Conclusion :

$$|D^2 u_{\lambda}| \le C/\delta^2$$
 on $\{X \in \Omega, \text{ dist}(X, \partial \Omega) \ge c\varepsilon\delta\}$

i.e. (3.3) is proved.

Case B: justification of (H1)-(H2).

Here we consider a general Lipschitz bounded open set Ω satisfying assumptions (A1), (A2) of theorem 1.2. We can mollify this open set Ω such that it gives a bigger and smooth open set Ω^{η} where η is the mollification parameter such that $\Omega^{\eta} = \Omega$ for $\eta = 0$. This smooth open set Ω^{η} still satisfies assumptions (A1), (A2) uniformly in η small enough. We can in particular consider the minimizer u_{λ}^{η} of the energy

$$E^{\eta}(u) = \int_{\Omega^{\eta}} F\left(|\nabla u|^2\right) + u^2\right)$$

on the convex set

$$K^{\eta}_{\lambda} = \left\{ u \in H^1(\Omega^{\eta}), \quad u \geq \lambda \quad \text{on} \quad \Omega^{\eta}, \quad u = \lambda_0 \quad \text{on} \quad \partial \Omega^{\eta} \right\}$$

This minimizer u_{λ}^{η} satisfies (H1)-(H2), and then (3.1),(3.2),(3.3).

Taking the limit $\eta \to 0$, we can extract (by Ascoli-Arzela theorem) a convergent subsequence $u_{\lambda}^{\eta} \to u$ such that u still satisfies (3.1),(3.2),(3.3).

We have the

Lemma 3.6 The limit u is the minimizer u_{λ} of the energy E on K_{λ} .

This ends the proof of proposition 3.1.

Proof of lemma 3.6

Let us recall that by (3.2), u^{η}_{λ} is bounded in $W^{1,\infty}$ uniformly in η small enough. Let

$$\tilde{u}_{\lambda} = \begin{cases} \lambda_0 & \text{on} & \Omega^{\eta} \backslash \Omega \\ \\ \\ u_{\lambda} & \text{on} & \Omega \end{cases}$$

By construction, we have

$$E^{\eta}(\tilde{u}_{\lambda}) \ge E^{\eta}(u_{\lambda}^{\eta})$$

At the limit $\eta = 0$, we get

$$E(u_{\lambda}) \ge E(u)$$

The uniqueness of the minimizer u_{λ} proves that $u = u_{\lambda}$. This ends the proof of the lemma 3.6.

4 Regularity of the free boundary near $\partial \Omega$: proof of theorem 1.2

We will prove theorem 1.2, thanks to Caffarelli result (lemma 2.2) applied to a particular blow-up sequence.

Case F(q) = q

If theorem 1.2 is false, then there exist a sequence of reals $\varepsilon_n = \sqrt{2\left(\frac{\lambda_0 - \lambda^n}{\lambda^n}\right)} \to 0$ and a sequence of singular points $X_{\lambda^n} \in \partial \{u_{\lambda^n} = \lambda^n\}$. Because of proposition 3.1, we have $\operatorname{dist}(X_{\lambda^n}, \partial \Omega) > c\varepsilon_n$. Then we define

$$w^{\varepsilon_n}(X) = \frac{u_{\lambda^n}(X_{\lambda^n} + \varepsilon_n X) - \lambda^n}{\lambda^n \varepsilon_n^2}$$

We have

$$\begin{cases} \Delta w^{\varepsilon_n} = 1 + \varepsilon_n^2 w^{\varepsilon_n} \quad \text{on} \quad \{w^{\varepsilon_n} > 0\} \\ 0 \le w^{\varepsilon_n} \le \frac{1}{2} \end{cases}$$

Now from proposition 3.1 we have the following L^{∞} bound on the second derivatives:

$$|D^2 w^{\varepsilon_n}(X)| \le C$$
 for $\operatorname{dist}(X_{\lambda^n} + \varepsilon_n X, \partial \Omega) \ge c\varepsilon_n$

Consequently from lemma 2.2, there exists a subsequence which converges to a convex function w^0 defined on Ω_0 , where Ω_0 is the limit of the sets $\frac{1}{\varepsilon_n} (\Omega - X_{\lambda^n})$ (for an extracted

subsequence). Moreover w^0 satisfies

$$\begin{cases} \Delta w^0 = 1 \quad \text{on} \quad \left\{ w^0 > 0 \right\} \\ \\ 0 \le w^0 \le \frac{1}{2} \quad \text{and} \quad \left| D^2 w^0(X) \right| \le C \quad \text{for} \quad \operatorname{dist}(X, \partial \Omega_0) \ge c \end{cases}$$

Because Ω satisfies an interior cone condition (A2), Ω_0 inherits the same property. Moreover because we have made a blow-up close to the fixed boundary $\partial\Omega$, we deduce that Ω_0 contains an infinite cone C_0 with a non-empty interior. Now we have two cases (see lemma 2.2):

i) the interior of the coincidence set of the blow-up limit is empty, and then the closure $\overline{\{w^0 > 0\}}$ contains the cone \mathcal{C}_0 . It is then sufficient to take a ball $B_r \subset \mathcal{C}_0$ with r large enough such that (by the nondegeneracy lemma 2.3)

$$\sup_{B_r} w^0 \ge \frac{r^2}{2n}$$

which is in contradiction with $0 \le w^0 \le \frac{1}{2}$.

ii) the interior of the coincidence set of the blow-up limit is not empty, and then 0 is a regular point for w^0 , and also a regular point for $w^{\varepsilon'_n}$ for ε'_n small enough. This means that X_{λ^n} are regular points for u_{λ^n} . Contradiction.

Case F general

In this case we introduce the operator (for $\varepsilon = \sqrt{2\left(\frac{\lambda_0 - \lambda}{\lambda}\right)}$)

$$A_{\varepsilon}(w) = a\left(\left(\frac{\lambda_0}{1+\frac{\varepsilon^2}{2}}\right)\varepsilon\nabla w\right)D^2w - \varepsilon^2w \tag{4.1}$$

where $a(p) = F'(p^2)Id + 2F''(p^2)p \otimes p$. Then we have

$$\begin{cases} A_{\varepsilon_n}(w^{\varepsilon_n}) = 1 & \text{on} \quad \{w^{\varepsilon_n} > 0\} \\ 0 \le w^{\varepsilon_n} \le \frac{1}{2} \end{cases}$$

A generalization of previous Caffarelli results to more general linear elliptic operators

$$L = \alpha_{ij}\partial_{ij} + \beta_i\partial_i + \gamma$$

is available in [8]. This allows to get similar results in the same way for our general case. This ends the proof of theorem 1.2.

5 Stability: proof of theorem 1.4

In this section we will prove theorem 1.4 on stability. A similar result is already known in the linear case (see for instance the book of Rodrigues [22] for general results of stability). In our case we use the approach of Caffarelli [8].

Proof of theorem 1.4

Let us assume that the theorem is false. Then for a compact set $\mathcal{K} \subset \subset \mathcal{K}^*$ we can find a sequence $(\lambda^n)_n$ such that $\lambda^n \to \lambda^*$ and a sequence of singular points $(X_{\lambda^n})_n$ of the free boundaries $\partial \{u_{\lambda^n} = \lambda^n\} \cap \mathcal{K}$. Up to extract a subsequence we can assume

$$X_{\lambda^{n'}} \longrightarrow X_{\lambda^*} \in \{u_{\lambda^*} = \lambda^*\} \cap \mathcal{K}$$

where we have used the continuity of the map

$$\lambda \longmapsto u_{\lambda}$$

The continuity of this map is a consequence of the L^{∞} bound on the gradient of u_{λ} uniformly in λ (see (3.2)). This continuity easily follows by a classical argument from Ascoli-Arzela theorem, and the uniqueness of the solutions u_{λ} for each λ . Let us recall that for $\varepsilon = \sqrt{2\left(\frac{\lambda_0 - \lambda}{\lambda}\right)}$ we have (the operator A_{ε} is defined in (4.1))

$$A_{\varepsilon}(w_{\lambda}) = 1 \quad \text{on} \quad \{w_{\lambda} > 0\}$$

where for some point $X_{\lambda} \in \Omega$:

$$w_{\lambda}(X) = \frac{u_{\lambda}(X_{\lambda} + \varepsilon X) - \lambda}{\lambda \varepsilon^2}$$

Using the adaptation of the nondegeneracy lemma 2.3 (see Caffarelli [8]) for general linear elliptic operators, we get the existence of a constant $c_0 > 0$ such that

$$\sup_{B_r(X_{\lambda^n})} \left(u_{\lambda^n}(X) - \lambda^n \right) \ge c_0 r^2$$

Then at the limit we get

$$\sup_{B_r(X_{\lambda^*})} \left(u_{\lambda^*}(X) - \lambda^* \right) \ge c_0 r^2$$

which proves that $X_{\lambda^*} \in \partial \{u_{\lambda^*} = \lambda^*\}$. In particular because X_{λ^*} is a regular point for u_{λ^*} , i.e. 0 is a regular point for w_{λ^*} , we get that the blow-up sequence

$$w_{\lambda^*}^{\delta}(X) = \frac{w_{\lambda^*}(\delta X)}{\delta^2}$$

converges (up to extraction of a subsequence) to a blow-up limit of regular type (see theorem 2.1; for an extension to general linear elliptic operators, see Caffarelli [8]):

$$w_{\lambda^*}^0(X) = \frac{1}{2} \left(\max\left(\langle X, \nu_{X_{\lambda^*}} \rangle, 0 \right) \right)^2$$

We realize that the origin 0 is obviously a regular point of $w_{\lambda^*}^0$. Finally we can consider the other blow-up sequence:

$$w_{\lambda^n}^{\delta^n}(X) = \frac{w_{\lambda^n}(\delta^n X)}{(\delta^n)^2}$$

Because for $\delta^n = \delta$ fixed and $\lambda^n \to \lambda^*$, this sequence of functions converges to $w_{\lambda^*}^{\delta}$, we see that we can choose a sequence $(\delta^n)_n$ slowly decreasing to zero such that

$$w_{\lambda^n}^{\delta^n} \longrightarrow w_{\lambda^*}^0$$

Then applying an adaptation of lemma 2.2 (see Caffarelli [8]) still true for general linear elliptic operators, we deduce from the fact that 0 is a regular point for the blow-up limit of $w_{\lambda^n}^{\delta^n}$, that 0 is also a regular point for $w_{\lambda^n}^{\delta^n}$ for *n* large enough. This means that X_{λ^n} is a regular point for u_{λ^n} . Contradiction. This ends the proof of theorem 1.4.

6 Hausdorff measure of the free boundary: proof of theorem 1.5

In this section we give the proof of theorem 1.5, which is an adaptation of a method of Caffarelli presented in the linear case in [9, 19]. We perform the proof in two steps.

Step 1

For the function $u = u_{\lambda}$, let

$$O^{\eta} = \{ X \in \Omega, \quad |\nabla u(X)| < \eta \quad \text{and} \quad u(X) > \lambda \}$$

For a function $u \ge \lambda$, we note

$$1_{\{u>\lambda\}}(X) = \begin{cases} 1 & \text{if } u(X) > \lambda \\ 0 & \text{if } u(X) = \lambda \end{cases}$$

Lemma 6.1 (Estimate in a neighbourhood of the free boundary)

$$\begin{split} & If \\ & \left\{ \begin{array}{ll} \nabla \cdot (F'(|\nabla u|^2) \nabla u) = u \ \mathbf{1}_{\{u > \lambda\}} & on \quad \Omega \\ \\ & u \geq \lambda > 0 & on \quad \partial \Omega \\ \\ & |D^2 u(X)| \leq M & on \quad \{X \in \Omega, \quad dist(X, \partial \Omega) \geq c\varepsilon\} \end{array} \right. \end{split}$$

then for all compact $\mathcal{K} \subset \{X \in \Omega, \quad dist(X, \partial \Omega) \ge c\varepsilon\}$ such that $\partial \mathcal{K}$ is C^1 , there is a constant C = C(M), such that

$$|O^{\eta} \cap \mathcal{K}| \le \eta C \lambda^{-2} (|\mathcal{K}| + \mathcal{H}^{n-1}(\partial \mathcal{K}))$$

where $|\mathcal{K}|$ is the volume of \mathcal{K} and $\mathcal{H}^{n-1}(\partial \mathcal{K})$ is the (n-1) dimensional Hausdorff measure of its perimeter.

Remark 6.2 (The Hausdorff measure)

Let us recall the definition of the Hausdorff measure. If U is a set, let

diam
$$(U) = \sup_{X, X' \in U} |X' - X|$$

Then for $s \ge 0$ and a set A let

$$\mathcal{H}^{s}_{\delta}(A) = c_{s} \inf_{\{\{U^{i}\}_{i}, A \subset \cup_{i} U^{i}, \text{diam } U^{i} \leq \delta\}} \sum_{i} (\text{diam } U^{i})^{s}$$

which is a nondecreasing function of δ . Then the s-dimensional Hausdorff measure is

$$\mathcal{H}^s(A) = \lim_{\delta \to 0} \mathcal{H}^s_\delta(A)$$

The constant c_s must be chosen such that the Hausdorff measure coincides with the Lebesgue measure of \mathbf{R}^s if $s \in \mathbf{N}$.

Proof of lemma 6.1

Because $F' \in C^{1,1}$, we have $h_i \in C^{0,1}$ where

$$h_{i} = \begin{cases} -\eta & \text{if } F' \nabla_{i} u \leq -\eta \\ F' \cdot \nabla_{i} u & \text{if } |F' \nabla_{i} u| \leq \eta \\ \eta & \text{if } F' \nabla_{i} u \geq \eta \end{cases}$$
(6.1)

We note X_i the vector field defined by $X_i = \nabla_i (F' \nabla u) \in L^\infty$. Then the Stokes formula gives :

$$\int_{\mathcal{K}} \nabla h_i \cdot X_i = \int_{\partial \mathcal{K}} h_i (X_i \cdot n) - \int_{\mathcal{K}} h_i (\nabla \cdot X_i)$$
(6.2)

But $\nabla \cdot X_i = \nabla_i (\nabla \cdot (F' \nabla u)) = \nabla_i u$ on $\{u > \lambda\}$, and $h_i = 0$ on $\{u = \lambda\}$. Then

$$\int_{O^{\eta}\cap\mathcal{K}} \nabla(F'\nabla_{i}u) \cdot \nabla_{i}(F'\nabla u) \leq \eta C(M)(|\mathcal{K}| + \mathcal{H}^{n-1}(\partial\mathcal{K}))$$
(6.3)

But

$$\nabla(F'\nabla_i u) \cdot \nabla_i (F'\nabla u) = [\nabla_i (F'\nabla_i u)]^2 + \sum_{k \neq i} [F'D_{ik}^2 u]^2 + O(|\nabla u|^2)$$

 $\quad \text{and} \quad$

$$\left| \int_{O^{\eta} \cap \mathcal{K}} O(|\nabla u|^2) \right| \leq \eta C(M) |\mathcal{K}|$$

Making the sum \sum_i , we get

$$\int_{O^{\eta}\cap\mathcal{K}}\sum_{i}\left(\nabla_{i}(F'\nabla_{i}u)\right)^{2} \leq \eta C(M)(|\mathcal{K}| + \mathcal{H}^{n-1}(\partial\mathcal{K}))$$
(6.4)

But

$$\sum_{i} \left(\nabla_i (F' \nabla_i u) \right)^2 \geq \left(\frac{\nabla \cdot (F' \nabla u)}{2} \right)^2 \geq \frac{u^2}{4} \geq \frac{\lambda^2}{4}$$

and then we get the expected result.

Step 2

The Hausdorff measure is bounded from above by:

$$\mathcal{H}^{n-1}(\Gamma) \leq \lim_{\eta \to 0} \inf_{\{B_{\eta}(Y_i)\}} \frac{1}{\eta} \sum_{i} |B_{\eta}(Y_i)|$$
(6.5)

where $\Gamma = \partial \{u = \lambda\}$ is the free boundary, and where $\{B_{\eta}(Y_i)\}_i$ is a recovering of Γ by balls of center Y_i on Γ and of radius η .

From proposition 3.1, we know that

$$u(X) - \lambda \ge c\varepsilon^2$$
 while $\operatorname{dist}(X, \partial\Omega) < c\varepsilon$ where $\varepsilon = \sqrt{2\left(\frac{\lambda_0 - \lambda}{\lambda}\right)}$

which in particular implies

dist
$$(\{u = \lambda\}, \partial \Omega) \ge c\varepsilon$$

Now starting from a point Y_i on $\partial \{u = \lambda\}$ we have from (3.3)

$$u(X) - \lambda \leq \frac{1}{2}C |X - Y_i|^2 \text{ while } \operatorname{dist}(X, \partial \Omega) \geq c\varepsilon$$

Therefore we get

dist
$$(B_{\eta}(Y_i), \partial \Omega) \ge c\varepsilon$$
 while $\frac{1}{2}C\eta^2 < c\varepsilon^2$

i.e. for η small enough.

Then for such η we have

$$B_{\eta}(Y_i) \cap \{u > \lambda\} \quad \subset \quad B_{\eta}(Y_i) \cap \{u > \lambda, \quad |\nabla u| \le C\eta\} \quad \subset \quad B_{\eta}(Y_i) \cap O^{C\eta}$$

From the nondegeneracy lemma 2.3, we deduce the existence of a real $\gamma \in (0, 1)$ such that

$$|B_{\eta}(Y_i) \cap \{u > \lambda\}| \ge \gamma |B_{\eta}(Y_i)|$$

As a consequence we get

$$|B_{\eta}(Y_i)| \le \gamma^{-1} \left| B_{\eta}(Y_i) \cap O^{C\eta} \right|$$

Thus

$$\begin{split} \eta^{-1} \sum_{i} |B_{\eta}(Y_{i})| &\leq \eta^{-1} \gamma^{-1} \sum_{i} |B_{\eta}(Y_{i}) \cap O^{C\eta}| \\ &\leq \eta^{-1} \gamma^{-1} \int_{\Omega} \sum_{i} \mathbb{1}_{B_{\eta}(Y_{i})} \mathbb{1}_{O^{C\eta}} \\ &\leq \eta^{-1} \gamma^{-1} \sup(\sum_{i} \mathbb{1}_{B_{\eta}(Y_{i})}) \int_{\Omega} \mathbb{1}_{O^{C\eta}} \\ &\leq \eta^{-1} \gamma^{-1} \sup(\sum_{i} \mathbb{1}_{B_{\eta}(Y_{i})}) \left| O^{C\eta} \right| \\ &\leq \gamma^{-1} C_{n} C' \lambda^{-2} \left(|\mathcal{K}_{\varepsilon}| + \mathcal{H}^{n-1}(\partial \mathcal{K}_{\varepsilon}) \right) \end{split}$$

where we have used the fact that we can always use locally finite recovering $\{B_{\eta}(Y_i)\}_i$ such that $\sum_i \mathbb{1}_{B_{\eta}(Y_i)} \leq C_n$ where the constant only depends on the dimension n. On the other hand we have applied lemma 6.1 introducing a smooth compact set $\mathcal{K}_{\varepsilon}$ such that

$$\mathcal{K}_{\varepsilon} \subset \{X \in \Omega, \quad 2c\varepsilon \ge \operatorname{dist}(X, \partial\Omega) \ge c\varepsilon\}$$

In fact $\mathcal{K}_{\varepsilon}$ can be seen as a smooth approximation of $\partial \Omega$. Consequently we get

$$\mathcal{H}^{n-1}(\Gamma) \le C$$

where the constant C only depends on Ω , λ_0 and F, and is uniform with respect to $\lambda \in [0, \lambda_0]$. This proves theorem 1.5.

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