







Langevin dynamics at equilibrium and out of equilibrium from hypocoercivity to efficient sampling

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Outline

- A quick introduction to computational statistical physics
- Equilibrium Langevin dynamics
 - Various convergence results
 - A focus on the approach by Dolbeault, Mouhot and Schmeiser

Various extensions/modifications

- Modified kinetic energies
- Rates of convergence for nonequilibrium Langevin dynamics
- Constructing control variates
- Proving the convergence of Temperature Accelerated Dynamics

A quick introduction to computational statistical physics

Computational statistical physics

- Predict macroscopic properties of matter from its microscopic description
- Microstate
 - positions $q = (q_1, \dots, q_N)$ and momenta $p = (p_1, \dots, p_N)$ • energy $V(q) + \sum_{i=1}^N \frac{p_i^2}{2m_i}$
- Macrostate
 - described by a probability measure μ
 - constraints fixed exactly or in average (number of particles, volume, energy)
- Properties :

• static $\langle A \rangle = \int_{\mathcal{E}} A(q, p) \, \mu(dq \, dp)$ (equation of state, heat capacity,...)

• dynamic (transport coefficient, transition pathway, etc)

Examples of molecular systems (1)

What is the melting temperature of Argon?



(a) Solid Argon (low temperature)

(b) Liquid Argon (high temperature)

Examples of molecular systems (2)

Equation of state of Argon: density as a function of pressure at fixed temperature T = 300 K



Examples of molecular systems (3)



Ubiquitin: what is its structure? What are its conformational changes?

Some orders of magnitude...

- Physical orders of magnitude
 - $\bullet~{\rm distances} \sim 1~{\rm \AA} = 10^{-10}~{\rm m}$
 - energy per particle $\sim k_{
 m B} T \sim 4 imes 10^{-21}$ J at 300 K
 - \bullet atomic masses $\sim 10^{-26}~{\rm kg}$
 - typical times $\sim 10^{-15}~{\rm s}$
 - number of particles $\sim \mathcal{N}_{A} = 6.02 \times 10^{23}$

• "Standards" simulations

- 10⁶ particles ["heroic": from 10⁹ particles on]
- total time: (fraction of) ns ["heroic": (fraction of) μs]
- Computation of high dimensional integrals...

$$ightarrow$$
 Ergodic methods $rac{1}{t}\int_{0}^{t} A(q_{s},p_{s})\,ds \xrightarrow[t
ightarrow +\infty]{} \langle A
angle$

Equilibrium Langevin dynamics

Langevin dynamics (1)

• Positions $q \in \mathcal{D} = (L\mathbb{T})^d$ or \mathbb{R}^d and momenta $p \in \mathbb{R}^d$ \rightarrow phase-space $\mathcal{E} = \mathcal{D} \times \mathbb{R}^d$

• Hamiltonian $H(q, p) = V(q) + \frac{1}{2}p^T M^{-1}p$ (more general kinetic energies U(p) can be considered¹)

Stochastic perturbation of the Hamiltonian dynamics

$$\begin{cases} dq_t = M^{-1} p_t \, dt \\ dp_t = -\nabla V(q_t) \, dt - \gamma M^{-1} p_t \, dt + \sqrt{\frac{2\gamma}{\beta}} \, dW_t \end{cases}$$

• Friction $\gamma > 0$ (could be a position-dependent matrix)

¹Redon, Stoltz, Trstanova, J. Stat. Phys. (2016)

Langevin dynamics (2)

- Evolution semigroup $\left(\mathrm{e}^{t\mathcal{L}}\varphi\right)(q,p) = \mathbb{E}\left[\varphi(q_t,p_t) \left| (q_0,p_0) = (q,p) \right]\right]$
- \bullet Generator of the dynamics ${\cal L}$

$$rac{d}{dt}\left(\mathbb{E}\left[arphi(q_t, p_t) \left| (q_0, p_0) = (q, p)
ight]
ight) = \mathbb{E}\left[(\mathcal{L}arphi)(q_t, p_t) \left| (q_0, p_0) = (q, p)
ight]
ight.$$

Generator of the Langevin dynamics $\mathcal{L} = \mathcal{L}_{\rm ham} + \gamma \mathcal{L}_{\rm FD}$

$$\mathcal{L}_{ham} = p^T M^{-1} \nabla_q - \nabla V^T \nabla_p, \qquad \mathcal{L}_{FD} = -p^T M^{-1} \nabla_p + \frac{1}{\beta} \Delta_p.$$

• Existence and uniqueness of the invariant measure characterized by

$$orall arphi \in C_0^\infty(\mathcal{E}), \qquad \int_{\mathcal{E}} \mathcal{L} arphi \, d\mu = 0$$

• Here, canonical measure

$$\mu(dq\,dp)=Z^{-1}\mathrm{e}^{-eta H(q,p)}\,dq\,dp=
u(dq)\,\kappa(dp)$$

Fokker–Planck equations

• Evolution of the law $\psi(t,q,p)$ of the process at time $t \ge 0$

$$\frac{d}{dt}\left(\int_{\mathcal{E}}\varphi\,\psi(t)\right) = \int_{\mathcal{E}}(\mathcal{L}\varphi)\,\psi(t)$$

• Fokker–Planck equation (with \mathcal{L}^{\dagger} adjoint of \mathcal{L} on $L^{2}(\mathcal{E})$)

$$\partial_t \psi = \mathcal{L}^\dagger \psi$$

• It is convenient to work in $L^2(\mu)$ with $f(t) = \psi(t)/\mu$

• denote the adjoint of ${\mathcal L}$ on $L^2(\mu)$ by ${\mathcal L}^*$

$$\mathcal{L}^* = -\mathcal{L}_{ham} + \gamma \mathcal{L}_{FD}$$

- Fokker–Planck equation $\partial_t f = \mathcal{L}^* f$
- Convergence results for $\mathrm{e}^{t\mathcal{L}}$ on $L^2(\mu)$ are very similar to the ones for $\mathrm{e}^{t\mathcal{L}^*}$

Hamiltonian and overdamped limits

- As $\gamma \rightarrow$ 0, the Hamiltonian dynamics is recovered
- Overdamped limit $\gamma \to +\infty$ or $m \to 0$

$$q_{\gamma t}-q_0=-rac{1}{\gamma}\int_0^{\gamma t}
abla V(q_s)\,ds+\sqrt{rac{2}{\gammaeta}}W_{\gamma t}-rac{1}{\gamma}\left(p_{\gamma t}-p_0
ight)$$

which converges to the solution of $dQ_t = -\nabla V(Q_t) \, dt + \sqrt{rac{2}{eta}} \, dW_t$

- In both cases, slow convergence to equilibrium
 - it takes time to change energy levels in the Hamiltonian limit²
 - \bullet for m fixed, time has to be rescaled by a factor γ

²Hairer and Pavliotis, *J. Stat. Phys.*, **131**(1), 175-202 (2008) Gabriel Stoltz (ENPC/INRIA)

Ergodicity results (1)

- Almost-sure convergence³ of ergodic averages $\widehat{\varphi}_t = \frac{1}{t} \int_0^t \varphi(q_s, p_s) ds$
- Asymptotic variance of ergodic averages

$$\sigma_{\varphi}^{2} = \lim_{t \to +\infty} t \mathbb{E} \left[\widehat{\varphi}_{t}^{2} \right] = 2 \int_{\mathcal{E}} \left(-\mathcal{L}^{-1} \Pi_{0} \varphi \right) \Pi_{0} \varphi \, d\mu$$

where $\Pi_0 \varphi = \varphi - \mathbb{E}_\mu(\varphi)$

• A central limit theorem holds⁴ when the equation has a solution in $L^2(\mu)$

Poisson equation in $L^2(\mu)$

$$-\mathcal{L}\Phi = \Pi_0 \varphi$$

• Well-posedness of such equations? Hypoelliptic operator

³Kliemann, *Ann. Probab.* **15**(2), 690-707 (1987) ⁴Bhattacharya, *Z. Wahrsch. Verw. Gebiete* **60**, 185–201 (1982) Gabriel Stoltz (ENPC/INRIA)

Ergodicity results (2)

• Invertibility of \mathcal{L} on subsets of $L_0^2(\mu) = \left\{ \varphi \in L^2(\mu) \mid \int_{\mathcal{E}} \varphi \, d\mu = 0 \right\}$?

$$-\mathcal{L}^{-1} = \int_0^{+\infty} \mathrm{e}^{t\mathcal{L}} \, dt$$

- \bullet Prove exponential convergence of the semigroup $\mathrm{e}^{t\mathcal{L}}$
 - various Banach spaces $E \cap L^2_0(\mu)$
 - Lyapunov techniques^{5,6,7} $L_W^{\infty}(\mathcal{E}) = \left\{ \varphi \text{ measurable}, \left\| \frac{\varphi}{W} \right\|_{L^{\infty}} < +\infty \right\}$
 - standard hypocoercive⁸ setup $H^1(\mu)$
 - $E = L^2(\mu)$ after hypoelliptic regularization⁹ from $H^1(\mu)$
 - coupling arguments¹⁰

⁵L. Rey-Bellet, *Lecture Notes in Mathematics* (2006)

- ⁶Hairer and Mattingly, Progr. Probab. **63** (2011)
- ⁷Mattingly, Stuart and Higham, Stoch. Proc. Appl. (2002)
- ⁸Villani (2009) and before Talay (2002), Eckmann/Hairer (2003), Hérau/Nier (2004)
 ⁹F. Hérau, J. Funct. Anal. 244(1), 95-118 (2007)
- ¹⁰A. Eberle, A. Guillin and R. Zimmer, arXiv preprint **1703.01617** (2017)

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Direct $L^2(\mu)$ approach

- Assume that the potential V is smooth and 11,12
 - the marginal measure ν satisfies a Poincaré inequality

$$\|\Pi_0\varphi\|_{L^2(\nu)}^2 \leqslant \frac{1}{C_{\nu}} \|\nabla_q\varphi\|_{L^2(\nu)}^2.$$

 \bullet there exist $c_1>$ 0, $c_2\in[0,1)$ and $c_3>$ 0 such that V satisfies

$$\Delta V \leqslant c_1 + rac{c_2}{2} |
abla V|^2, \quad |
abla^2 V| \leqslant c_3 \left(1 + |
abla V|\right).$$

There exist C > 0 and $\lambda_{\gamma} > 0$ such that, for any $\varphi \in L_0^2(\mu)$, $\forall t \ge 0, \qquad \left\| e^{t\mathcal{L}} \varphi \right\|_{L^2(\mu)} \leqslant C e^{-\lambda_{\gamma} t} \|\varphi\|_{L^2(\mu)}.$

with convergence rate of order min (γ, γ^{-1}) : there exists $\overline{\lambda} > 0$ such that $\lambda_{\gamma} \ge \overline{\lambda} \min(\gamma, \gamma^{-1}).$

¹¹Dolbeault, Mouhot and Schmeiser, *C. R. Math. Acad. Sci. Paris* (2009) ¹²Dolbeault, Mouhot and Schmeiser, *Trans. AMS*, **367**, 3807–3828 (2015) Gabriel Stoltz (ENPC/INRIA)

Sketch of proof

• Modified square norm $\mathcal{H}[\varphi] = \frac{1}{2} \|\varphi\|^2 - \varepsilon \langle A\varphi, \varphi \rangle$ for $\varepsilon \in (-1, 1)$ and

$$A = \left(1 + (\mathcal{L}_{\mathrm{ham}} \Pi_{\rho})^* (\mathcal{L}_{\mathrm{ham}} \Pi_{\rho})\right)^{-1} (\mathcal{L}_{\mathrm{ham}} \Pi_{\rho})^*, \qquad \Pi_{\rho} \varphi = \int_{\mathbb{R}^D} \varphi \, d\kappa$$

• $A = \prod_p A(1 - \prod_p)$ and $\mathcal{L}_{ham}A$ are bounded so that $\mathcal{H} \sim \| \cdot \|_{L^2(\mu)}^2$

Coercivity in the scalar product $\langle \langle \cdot, \cdot \rangle \rangle$ induced by \mathcal{H}

$$\mathscr{D}[\varphi] := \langle \langle -\mathcal{L}\varphi, \varphi \rangle \rangle \geqslant \widetilde{\lambda}_{\gamma} \|\varphi\|^2,$$

• Idea: control of $||(1 - \Pi_p)\varphi||^2$ by $\langle -\mathcal{L}_{FD}\varphi, \varphi \rangle$ (Poincaré); for $||\Pi_p\varphi||^2$,

$$\|\mathcal{L}_{\mathrm{ham}}\Pi_{\rho}\varphi\|^{2} \geqslant rac{DC_{\nu}}{eta m}\|\Pi_{\rho}\varphi\|^{2}, \qquad \mathrm{hence} \ \mathcal{A}\mathcal{L}_{\mathrm{ham}}\Pi_{\rho} \geqslant \lambda_{\mathrm{ham}}\Pi_{
ho}$$

• Gronwall inequality $\frac{d}{dt} \left(\mathcal{H}\left[e^{t\mathcal{L}} \varphi \right] \right) = -\mathscr{D}\left[e^{t\mathcal{L}} \varphi \right] \leqslant -\frac{2\lambda_{\gamma}}{1+\varepsilon} \mathcal{H}\left[e^{t\mathcal{L}} \varphi \right]$

Extensions/modifications

Using modified kinetic energies

- General kinetic energy function U(p) in the Langevin dynamics
 - heavy/light tails
 - ∇U vanishes on open sets (ARPS)
- Can still prove convergence results (Lyapunov¹³ or hypocoercivity¹⁴) although the dynamics is not hypoelliptic
- \bullet Dedicated numerical schemes to integrate non-globally Lipschitz ∇U
 - Strang splitting between Hamiltonian part and fluctuation/dissipation
 - Metropolization of FD using a HMC-like scheme (weak order 3/2)

• Possible reduction of metastability by good choices of U (e.g. U = V in low dimensions)

¹³S. Redon, G. Stoltz and Z. Trstanova, J. Stat. Phys. (2016)

¹⁴G. Stoltz and Z. Trstanova, accepted in *Multiscale Model. Sim.* (2018)

Rates of convergence for nonequilibrium Langevin dynamics

• Compact position space $\mathcal{D}=(2\pi\mathbb{T})^d$, constant force $|\mathsf{F}|=1$

Langevin dynamics perturbed by a constant force term

$$\begin{cases} dq_t = \frac{p_t}{m} dt, \\ dp_t = (-\nabla V(q_t) + \tau F) dt - \gamma \frac{p_t}{m} dt + \sqrt{\frac{2\gamma}{\beta}} dW_t, \end{cases}$$

- Non-zero velocity in the direction F is expected in the steady-state
- F does not derive from the gradient of a periodic function
 of course, F = -∇W_F(q) with W_F(q) = -F^Tq
 - ...but W_F is not periodic!

Rates of convergence for nonequilibrium Langevin dynamics

- Lyapunov approaches are non-perturbative but also non-quantitative
- Suboptimal results by the standard hypocoercive approach in $H^1(\mu)$ \rightarrow nonequilibrium perturbation¹⁵ of direct $L^2(\mu)$ strategy
- Invariant measure $\psi_\eta = h_\tau \mu$ with $h_\tau \in L^2(\mu)$ for $|\tau|$ small

Uniform rates for nonequilibrium perturbations

There exist $C, \delta_* > 0$ such that, for any $\delta \in [0, \delta^*]$, there is $\overline{\lambda}_{\delta} > 0$ for which, for all $\gamma \in (0, +\infty)$ and all $\tau \in [-\delta \min(\gamma, 1), \delta \min(\gamma, 1)]$,

$$\left\| \mathrm{e}^{t\mathcal{L}^*_{\gamma,\tau}} f - h_\tau \right\|_{L^2(\mu)} \leqslant C \mathrm{e}^{-\overline{\lambda}_\delta \min(\gamma,\gamma^{-1})t} \|f - h_\tau\|_{L^2(\mu)}$$

• As a corollary: lower bounds on the spectral gap of order min (γ, γ^{-1}) \rightarrow can be checked numerically ¹⁶

¹⁵E. Bouin, F. Hoffmann, and C. Mouhot, *arXiv preprint* 1605.04121
 ¹⁶A. Iacobucci, S. Olla and G. Stoltz, to appear in *Ann. Math. Quebec* (2017)
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Constructing control variates

• The computation of transport coefficients by nonequilibrium steady-state techniques involves the computations of quantities of the form

$$rac{\mathbb{E}_\eta({\sf R})}{\eta}, \qquad |\eta| \ll 1$$

- \rightarrow Magnification of the statistical error
- Typical cases: $\mathcal{L}_{\eta} = \mathcal{L}_{0} + \eta \widetilde{\mathcal{L}}$
 - nonequilibrium perturbation
 - coupling parameter between otherwise independent systems
 - anharmonic part in an otherwise linear dynamics
- Control variate idea
 - note that $\mathbb{E}_\eta(R-\mathcal{L}_\eta\Phi)=\mathbb{E}_\eta(R)$ for all Φ
 - ...but it may happen that $\operatorname{Var}_{\eta}(R \mathcal{L}_{\eta}\Phi) \ll \operatorname{Var}_{\eta}(R)$
 - Optimal choice $\Phi = \mathcal{L}_{\eta}^{-1}(R \mathbb{E}_{\eta}(R))$ unknown
 - approximate it by $\mathcal{L}_0^{-1}(R \mathbb{E}_0(R))$

Constructing control variates

- Error estimates for Galerkin discretization¹⁷
 - spectral basis (weighted Fourier modes + Hermites polynomials)
 - (non-)conformal formulation (basis functions of mean 0 or not)
 - estimation of consistency and approximation errors
- Error estimates on the variance for approximate control variate¹⁸
 - modified estimator based on $R + \mathcal{L}_\eta \Phi_0$
 - the asymptotic variance is of order η^2 when Φ_0 is exactly computed
 - applications to (i) 1D nonequilibrium Langevin, (2) thermal transport in 1D chains, (3) dimer in WCA solvent

¹⁷J. Roussel and G. Stoltz, to appear in M2AN (arXiv preprint 1702.04718)

¹⁸J. Roussel and G. Stoltz, *arXiv preprint* **1712.08022**

Proving the convergence of TAMD

• Additional variable z (e.g. free energy computation), higher temperature $\bar{\beta}^{-1}$, acceleration factor $\delta^{-1} \rightarrow$ Nonequilibrium dynamics

$$\begin{cases} dq_t = \delta^{-1} M^{-1} p_t dt, \\ dp_t = -\delta^{-1} \nabla_q U_{\kappa}(q_t, z_t) dt - \delta^{-1} \gamma M^{-1} p_t dt + \sqrt{2\gamma(\beta\delta)^{-1}} dW_t^p, \\ dz_t = -\nabla_z U_{\kappa}(q_t, z_t) dt + \sqrt{2\overline{\beta}^{-1}} dW_t^z. \end{cases}$$

 \bullet Effective dynamics as $\delta \rightarrow 0$

$$dar{z}_t = -
abla_z A(ar{z}_t) \, dt + \sqrt{2ar{eta}^{-1}} \, dW^z_t, \qquad \mathrm{e}^{-eta A(z)} = \int_{\mathcal{D}_q} \mathrm{e}^{-eta U(q,z)} dq$$

- Convergence results¹⁹
 - Exponential decay of semigroup, rate close to effective dynamics
 - Expansion of the invariant measure in powers of $\boldsymbol{\delta}$
 - Asymptotic variance agrees at first order in δ with effective dynamics

¹⁹G. Stoltz and E. Vanden-Eijnden, *arXiv preprint* **1708.08800** Gabriel Stoltz (ENPC/INRIA)