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Error estimates for transport coefficients in molecular dynamics

Gabriel STOLTZ

`gabriel.stoltz@enpc.fr`

(CERMICS, Ecole des Ponts & MATHERIALS team, INRIA Paris)

Work also supported by ANR Funding ANR-14-CE23-0012 (“COSMOS”)

MMM16, Dijon, October 2016

Outline

- **Transport coefficients:** "steady-state" dynamical information
 - mobility
 - shear viscosity
 - thermal conductivity
- **Bias** due to timestep for
 - Green-Kubo formulas
 - linear response approaches
- **Variance** reduction for linear response approaches

Linear response and Green-Kubo formula

$$\lim_{\eta \rightarrow 0} \frac{\mathbb{E}_\eta(R)}{\eta} = \int_0^{+\infty} \mathbb{E}_0(R(x_t)S(x_0)) dt$$

T. Lelièvre and G. Stoltz, PDEs and stochastic methods in molecular dynamics, *Acta Numerica* **25**, 681-880 (2016)

A paradigmatic example

Langevin dynamics perturbed by a constant force term

$$\begin{cases} dq_t = M^{-1} p_t dt, \\ dp_t = (-\nabla V(q_t) + \eta F) dt - \gamma M^{-1} p_t dt + \sqrt{\frac{2\gamma}{\beta}} dW_t, \end{cases} \quad (1)$$

where

- $F \in \mathbb{R}^d$ with $|F| = 1$ is a given direction
- $\eta \in \mathbb{R}$ determines the **strength** of the external forcing
- Non-zero velocity in the direction F is expected in the steady-state
- **F does not derive from the gradient of a periodic function**
 - of course, $F = -\nabla W_F(q)$ with $W_F(q) = -F^T q$
 - ...but W_F is not periodic!

Mobility and self-diffusion

- **Linear response approaches:** averages in a nonequilibrium steady-state

Mobility

$$\nu_F = \lim_{\eta \rightarrow 0} \frac{\mathbb{E}_\eta (F^T M^{-1} p)}{\eta} = \beta \int_{\mathcal{E}} F^T M^{-1} p f_{0,1}(q, p) \mu(dq dp) = \beta F^T DF$$

- **Green-Kubo formulas:** integrated correlation functions

Effective diffusion at equilibrium ($\eta = 0$)

Unperiodized displacement $Q_t - Q_0 = \int_0^t M^{-1} p_s ds$

$$F^T DF = \int_0^{+\infty} \mathbb{E}_0 \left[\left(F^T M^{-1} p_t \right) \left(F^T M^{-1} p_0 \right) \right] dt$$

Timestep bias for linear response

Examples of splitting schemes for Langevin dynamics (1)

- Example: Langevin dynamics, discretized using a **splitting** strategy

$$A = M^{-1}p \cdot \nabla_q, \quad B_\eta = \left(-\nabla V(q) + \eta F \right) \cdot \nabla_p, \quad C = -M^{-1}p \cdot \nabla_p + \frac{1}{\beta} \Delta_p$$

- First order splitting schemes: Trotter splitting

$$P_{\Delta t}^{ZYX} = e^{\Delta t Z} e^{\Delta t Y} e^{\Delta t X} \simeq e^{\Delta t A}$$

- **Second order** schemes: Strang splitting

$$P_{\Delta t}^{ZYXYZ} = e^{\Delta t Z/2} e^{\Delta t Y/2} e^{\Delta t X} e^{\Delta t Y/2} e^{\Delta t Z/2}$$

- Other category: **Geometric Langevin** algorithms, e.g. $P_{\Delta t}^{\gamma C, A, B_\eta, A}$
- **Invariant measure** $\mu_{\gamma, \eta, \Delta t}$ (different from μ)

B. Leimkuhler, Ch. Matthews and G. Stoltz, The computation of averages from equilibrium and nonequilibrium Langevin molecular dynamics, *IMA J. Numer. Anal.* **36**(1), 13-79 (2016)

Examples of splitting schemes for Langevin dynamics (2)

- $P_{\Delta t}^{B_\eta, A, \gamma C}$ corresponds to

$$\begin{cases} \tilde{p}^{n+1} = p^n + \left(-\nabla V(q^n) + \eta F \right) \Delta t, \\ q^{n+1} = q^n + \Delta t M^{-1} \tilde{p}^{n+1}, \\ p^{n+1} = \alpha_{\Delta t} \tilde{p}^{n+1} + \sqrt{\frac{1 - \alpha_{\Delta t}^2}{\beta}} M G^n \end{cases}$$

where G^n are i.i.d. Gaussian and $\alpha_{\Delta t} = \exp(-\gamma M^{-1} \Delta t)$

- $P_{\Delta t}^{\gamma C, B_\eta, A, B_\eta, \gamma C}$ for

$$\begin{cases} \tilde{p}^{n+1/2} = \alpha_{\Delta t/2} p^n + \sqrt{\frac{1 - \alpha_{\Delta t/2}}{\beta}} M G^n, \\ p^{n+1/2} = \tilde{p}^{n+1/2} + \frac{\Delta t}{2} \left(-\nabla V(q^n) + \eta F \right), \\ q^{n+1} = q^n + \Delta t M^{-1} p^{n+1/2}, \\ \tilde{p}^{n+1} = p^{n+1/2} + \frac{\Delta t}{2} \left(-\nabla V(q^{n+1}) + \eta F \right), \\ p^{n+1} = \alpha_{\Delta t/2} \tilde{p}^{n+1} + \sqrt{\frac{1 - \alpha_{\Delta t/2}}{\beta}} M G^{n+1/2} \end{cases}$$

Error estimates on linear response

Error estimates for nonequilibrium dynamics

There exists a function $f_{\alpha,1,\gamma} \in H^1(\mu)$ such that

$$\int_{\mathcal{E}} \psi d\mu_{\gamma,\eta,\Delta t} = \int_{\mathcal{E}} \psi \left(1 + \eta f_{0,1,\gamma} + \Delta t^\alpha f_{\alpha,0,\gamma} + \eta \Delta t^\alpha f_{\alpha,1,\gamma} \right) d\mu + r_{\psi,\gamma,\eta,\Delta t},$$

where the remainder is compatible with linear response

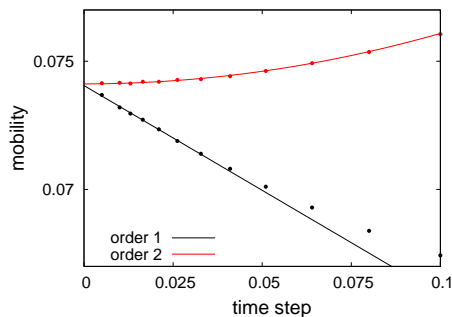
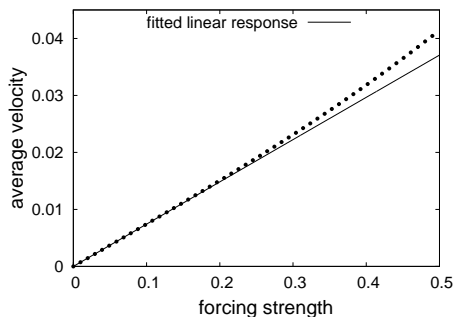
$$|r_{\psi,\gamma,\eta,\Delta t}| \leq K(\eta^2 + \Delta t^{\alpha+1}), \quad |r_{\psi,\gamma,\eta,\Delta t} - r_{\psi,\gamma,0,\Delta t}| \leq K\eta(\eta + \Delta t^{\alpha+1})$$

- Corollary: error estimates on the **numerically computed mobility**

$$\begin{aligned} \nu_{F,\gamma,\Delta t} &= \lim_{\eta \rightarrow 0} \frac{1}{\eta} \left(\int_{\mathcal{E}} F^T M^{-1} p \mu_{\gamma,\eta,\Delta t}(dq dp) - \int_{\mathcal{E}} F^T M^{-1} p \mu_{\gamma,0,\Delta t}(dq dp) \right) \\ &= \nu_{F,\gamma} + \Delta t^\alpha \int_{\mathcal{E}} F^T M^{-1} p f_{\alpha,1,\gamma} d\mu + \Delta t^{\alpha+1} r_{\gamma,\Delta t} \end{aligned}$$

- Results in the **overdamped** limit

Numerical results



Left: Linear response of the average velocity as a function of η for the scheme associated with $P_{\Delta t}^{\gamma C, B_\eta, A, B_\eta, \gamma C}$ and $\Delta t = 0.01, \gamma = 1$.

Right: Scaling of the mobility $\nu_{F,\gamma,\Delta t}$ for the first order scheme $P_{\Delta t}^{A, B_\eta, \gamma C}$ and the second order scheme $P_{\Delta t}^{\gamma C, B_\eta, A, B_\eta, \gamma C}$.

Timestep bias for Green–Kubo formulas

Error estimates on Green-Kubo formulas (1)

- Results valid for Langevin or overdamped Langevin dynamics

$$dq_t = -\nabla V(q_t) dt + \sqrt{\frac{2}{\beta}} dW_t$$

- Error of order α on invariant measure: $\int_{\mathcal{X}} \psi d\pi_{\Delta t} = \int_{\mathcal{X}} \psi d\pi + O(\Delta t^\alpha)$
- Expansion of the evolution operator $P_{\Delta t}\varphi(x) = \mathbb{E}\left(\varphi(x^{n+1}) \mid x^n = x\right)$

$$P_{\Delta t}\varphi = \varphi + \Delta t \mathcal{L}\varphi + \Delta t^2 \mathcal{A}_2\varphi + \cdots + \Delta t^{p+1} \mathcal{A}_{p+1}\varphi + \Delta t^{p+2} r_{\varphi, \Delta t}$$

- Suitable ergodicity conditions on $P_{\Delta t}$

M. Fathi and G. Stoltz, Improving dynamical properties of stabilized discretizations of overdamped Langevin dynamics, accepted for publication in *Numer. Math.* (2016)

Error estimates on Green-Kubo formulas (2)

Error estimates on integrated correlation functions

Observables φ, ψ with average 0 w.r.t. invariant measure π

$$\int_0^{+\infty} \mathbb{E}(\psi(x_t)\varphi(x_0)) dt = \Delta t \sum_{n=0}^{+\infty} \mathbb{E}_{\Delta t}(\tilde{\psi}_{\Delta t, \alpha}(x^n)\varphi(x^0)) + \Delta t^\alpha r_{\Delta t}^{\psi, \varphi},$$

where $\mathbb{E}_{\Delta t}$ denotes expectations w.r.t. initial conditions $x_0 \sim \pi_{\Delta t}$ and over all realizations of the Markov chain (x^n) , and

$$\tilde{\psi}_{\Delta t, \alpha} = \psi_{\Delta t, \alpha} - \int_{\mathcal{X}} \psi_{\Delta t, \alpha} d\pi_{\Delta t}$$

with $\psi_{\Delta t, \alpha} = \left(\text{Id} + \Delta t \mathcal{A}_2 \mathcal{L}^{-1} + \dots + \Delta t^{\alpha-1} \mathcal{A}_\alpha \mathcal{L}^{-1}\right) \psi$

- Useful when $\mathcal{A}_k \mathcal{L}^{-1}$ can be computed, e.g. $\mathcal{A}_k = a_k \mathcal{L}^k$
- Reduces to trapezoidal rule for second order schemes

Metropolized overdamped Langevin dynamics

- Superimpose Metropolis-Hastings correction to discretization of SDE

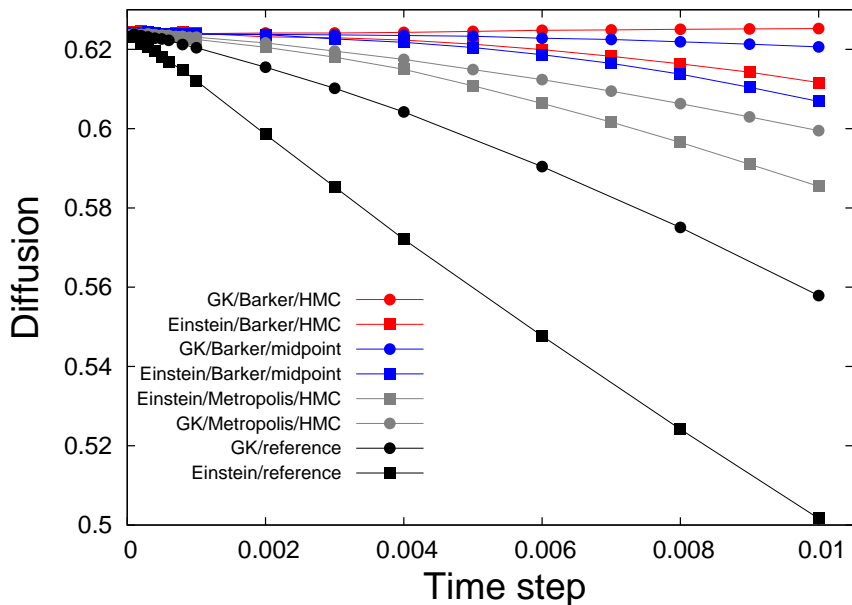
$$\tilde{q}^{n+1} = q^n + \Delta t \nabla V(q^n) + \sqrt{\frac{2\Delta t}{\beta}} G^n$$

- **no bias** on invariant measure / **stabilization** for singular potentials
- error estimates on the diffusion of order Δt

- **HMC-like** scheme $\tilde{q}^{n+1} = q^n + \Delta t \nabla V \left(q^n + \sqrt{\frac{\Delta t}{2\beta}} G^n \right) + \sqrt{\frac{2\Delta t}{\beta}} G^n$

- Error of order $\Delta t^{3/2}$ when the Metropolis-Hastings rule is used
 - Reduced to Δt^2 when a **Barker rule** is used (replace $\min(1, r)$ by $r/(r+1)$)
 - Requires some **time renormalization** since rejection rate $\simeq 1/2$
 - Trade-off between **increased variance** (factor 2) and reduced bias
- Extension to diffusions with multiplicative noise

Results in 1D for $\varphi = \psi = V'$ and cosine potential



Variance reduction approaches for linear response

The need for variance reduction

- Response function $R(q, p) = F^T M^{-1} p$
- Standard approach: compute the steady-state average as

$$\frac{1}{t} \int_0^t R(q_s, p_s) ds \xrightarrow{t \rightarrow +\infty} \int_{\mathcal{E}} R \psi_{\eta} = O(\eta)$$

when R vanishes at equilibrium

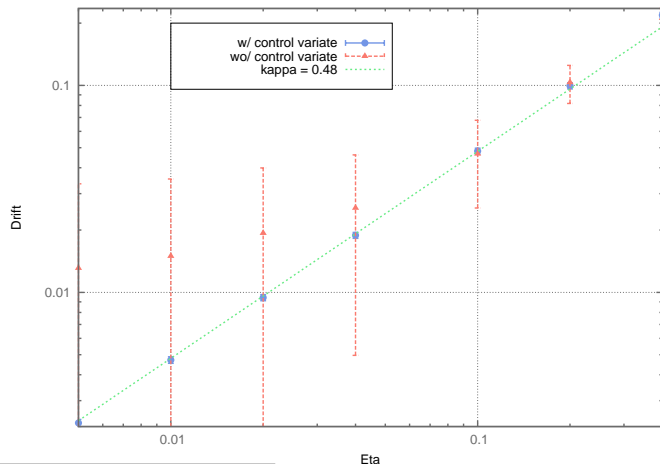
- Variance of order 1 \rightarrow **relative error of order $1/\eta$!**
- Need for **variance reduction**... but
 - no straightforward importance sampling
 - no easy stratification

Control variate approach

$$\frac{\mathbb{E}_{\eta}(R)}{\eta} = \frac{\mathbb{E}_{\eta}(R - \mathcal{L}_{\eta}\Phi)}{\eta} \quad \text{with} \quad \text{Var}_{\eta}(R - \mathcal{L}_{\eta}\Phi) \ll \text{Var}_{\eta}(R)$$

Control variates for linear response

- Idea:¹ consider Φ such that $-\mathcal{L}_0\Phi = R$ (Galerkin discretization)
- Variance of order η^2 when Φ is exactly computed \rightarrow relative error $O(1)$



¹J. Roussel and G. Stoltz, in preparation