

# Adaptive Importance Sampling Strategies

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## The metastability problem

- Applications in computational physics and Bayesian statistics, when some **high dimensional** probability measure has to be sampled
- Measure to be sampled  $\mu(dq) = Z^{-1} e^{-\beta V(q)} dq$  with  $Z = \int_{\mathcal{D}} e^{-\beta V(q)} dq$
- For an ergodic dynamics such as  $dq_t = -\nabla V(q_t) dt + \sqrt{\frac{2}{\beta}} dW_t$ , ensemble averages can be approximated by trajectorial averages:

$$\langle A \rangle = \int_{\mathcal{D}} A(q) \mu(dq) = \lim_{T \rightarrow +\infty} \frac{1}{T} \int_0^T A(q_t) dt \quad (1)$$

- Although the convergence (1) is theoretically ensured, it can be very slow from a numerical viewpoint
- Metastability arises from **free-energy barriers**, which can have either energetic or entropic origins

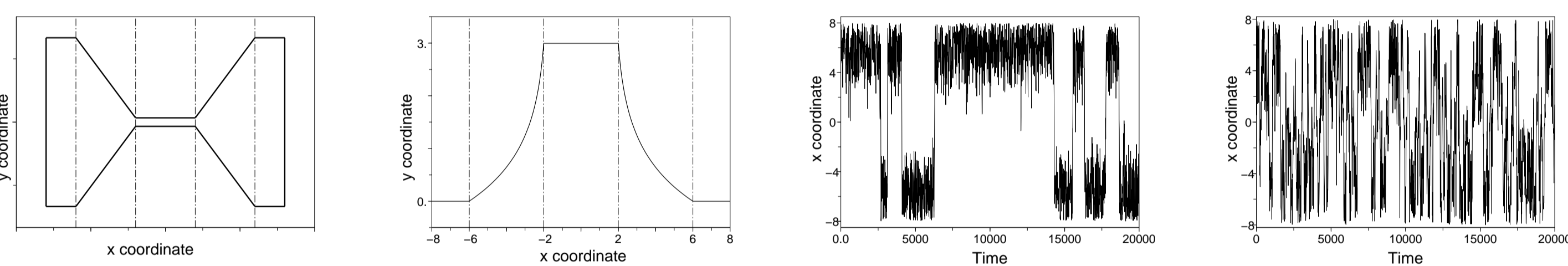
## Free-energy biased sampling

- Consider a function  $\xi : \mathcal{D} \rightarrow \mathbb{R}^m$  ( $m \ll \dim(\mathcal{D})$ ) such that  $\xi(q_t)$  is some slowly evolving degree of freedom (a notion to be precised...)
- Marginal equilibrium distribution ( $m = 1$  to simplify)

$$\mu^\xi(dz) = Z^{-1} \int_{\Sigma(z)} e^{-\beta V(q)} \delta_{\xi(q)-z}(dq) dz = Z^{-1} \int_{\Sigma(z)} e^{-\beta V(q)} \frac{d\sigma_{\Sigma(z)}(dq)}{|\nabla \xi(q)|} dz = e^{-\beta F(z)} dz,$$

where  $\Sigma(z) = \{q \in \mathcal{D} \mid \xi(q) = z\}$  is a submanifold of  $\mathcal{D}$

- **Conditional equilibrium distribution**  $\nu^\xi(dq \mid z) = \frac{e^{-\beta V(q)} |\nabla \xi(q)|^{-1} \sigma_{\Sigma(z)}(dq)}{\int_{\Sigma(z)} e^{-\beta V} |\nabla \xi|^{-1} d\sigma_{\Sigma(z)}}$
- **Mean force**  $\nabla F(z) = \int_{\Sigma(z)} f(q) \nu^\xi(dq \mid z)$  with  $f = \frac{\nabla \xi \cdot \nabla V}{|\nabla \xi|^2} - \beta^{-1} \operatorname{div} \left( \frac{\nabla \xi}{|\nabla \xi|^2} \right)$
- When the potential is biased by the free-energy,  $\mathcal{V}(q) = V(q) - F(\xi(q))$ , the new marginal distribution is constant = **uniform sampling in  $\xi$**  and the metastability is removed in this direction!
- Application: entropic barrier



(1) Potential for which entropic barriers have to be overcome (0 in the region enclosed by the curve,  $+\infty$  outside) and (2) associated free energy profile when  $\xi(x, y) = x$ . Typical trajectories for a simple Metropolis random walk (3) and a dynamics biased by the free energy (4).

## Adaptive methods: A general framework and consistency results [5]

- Bottom line of adaptive methods: add a **biasing term, depending on  $\xi$**  only, and **adapt it on-the-fly** in order to reach a uniform distribution of  $\xi(q_t)$ .
- The resulting potential is  $\mathcal{V}_t = V - F_t \circ \xi$ , and rules to update the bias are needed
- Denote by  $\psi(t, q)$  the law of the process  $dq_t = -\nabla(V - F_t \circ \xi)(q_t) dt + \sqrt{\frac{2}{\beta}} dW_t$
- General update formula for **Adaptive Biasing Potential** method [4, 8] using the *observed free energy*

$$\frac{dF_t(z)}{dt} = \mathcal{F}_t(F_{\text{obs}}(t, z)), \quad F_{\text{obs}}(t, z) = -\beta^{-1} \ln \left( \int_{\Sigma(z)} \psi(t, \cdot) \frac{d\sigma_{\Sigma(z)}}{|\nabla \xi|} \right)$$

- General update formula for **Adaptive Biasing Force** method [1, 2] using the *observed mean force*

$$\frac{d\Gamma_t(z)}{dt} = \mathcal{G}_t(\Gamma_{\text{obs}}(t, z) - \Gamma_t(z)), \quad \Gamma_{\text{obs}}(t, z) = \int_{\Sigma(z)} f d\psi^\xi(t, \cdot | z)$$

Possibly, set  $\Gamma_t(z) = \Gamma_{\text{obs}}(t, z)$

- If some equilibrium is reached and the updating functions  $\mathcal{F}_t$  and  $\mathcal{G}_t$  are strictly increasing (with  $\mathcal{G}_t(0) = 0$ ), then  $F_\infty = F + c$  and  $\Gamma_\infty = \nabla F_\infty$
- Issues with the case  $m > 1$ : ABF is not a gradient dynamics

## References

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## Convergence of the Adaptive Biasing Force method [6]

- Dynamics 
$$\begin{cases} dq_t = -\nabla(V - F_t \circ \xi - \beta^{-1} \ln(|\nabla \xi|^{-2})) (q_t) |\nabla \xi|^{-2}(q_t) dt + \sqrt{2\beta^{-1}} |\nabla \xi|^{-1}(q_t) dW_t, \\ F'_t(z) = \mathbb{E} \left( f(X_t) \mid \xi(X_t) = z \right) = \int_{\Sigma(z)} f(q) d\psi^\xi(t, z) \end{cases}$$

- Existence and uniqueness of the solution [3]

$$\begin{cases} \partial_t \psi = \operatorname{div} \left( \frac{\nabla(V - F_t \circ \xi) \psi + \beta^{-1} \nabla \psi}{|\nabla \xi|^{-2}} \right), \\ F'_t(z) = \frac{\int_{\Sigma(z)} f |\nabla \xi|^{-1} \psi(t, \cdot) d\sigma_{\Sigma(z)}}{\int_{\Sigma(z)} |\nabla \xi|^{-1} \psi(t, \cdot) d\sigma_{\Sigma(z)}}. \end{cases}$$

- Expected longtime limits:  $F_t(z) \rightarrow F(z)$ ,  $\psi_t(q) \rightarrow \psi_\infty(q) = e^{-\beta(V(q) - F(\xi(q)))}$

- Proof using **entropy estimates**. The relative entropy of  $\mu$  with respect to  $\nu$  is  $H(\mu \mid \nu) = \int \ln \left( \frac{d\mu}{d\nu} \right) d\mu$ . Then the total entropy can be decomposed as

$$E(t) = H(\psi(t, \cdot) \mid \psi_\infty) = E_M(t) + E_m(t),$$

where the macroscopic and microscopic entropies are respectively

$$E_M(t) = H(\psi^\xi(t, \cdot) \mid \psi_\infty^\xi), \quad E_m(t) = \int_{\mathcal{M}} e_m(t, z) \psi^\xi(t, z) dz \quad e_m(t, z) = H(\nu^\xi(t, \cdot \mid z) \mid \nu^\xi(\infty, \cdot \mid z))$$

- The marginal density satisfies a **simple diffusion equation**  $\partial_t \psi^\xi = \beta^{-1} \partial_{zz} \psi^\xi$ , therefore  $E_M \rightarrow 0$
- Control of the microscopic entropy when assuming some uniform ergodicity for the dynamics at fixed  $\xi(q) = z$  (logarithmic Sobolev inequality)
- The overall rate of convergence of the method is limited by the rate of convergence of the projected dynamics, so that the metastability in the  $\xi$  direction is removed

## Application to Statistical Physics: Multiple replica & Selection

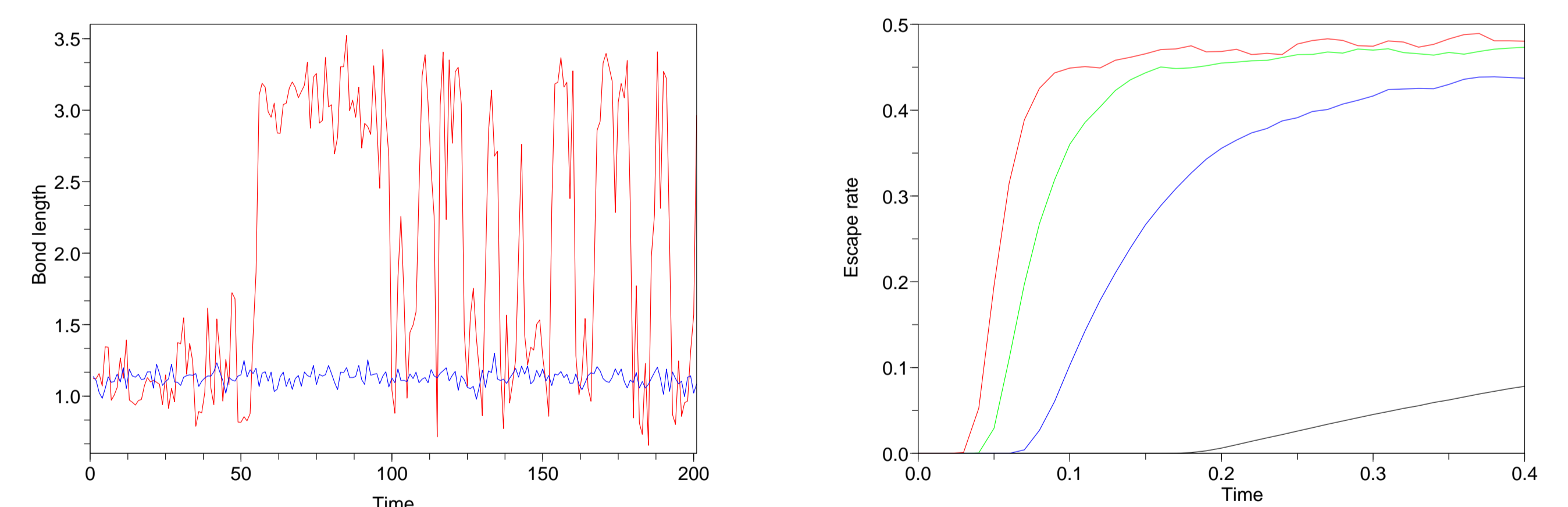
- Model dimer in a solvent (double-well potential), solvent particles interacting through the purely repulsive potential (truncated Lennard-Jones):

$$V_{\text{WCA}}(r) = \begin{cases} 4\epsilon \left[ \left( \frac{\sigma}{r} \right)^{12} - \left( \frac{\sigma}{r} \right)^6 \right] + \epsilon & \text{if } r \leq \sigma, \\ 0 & \text{if } r > \sigma, \end{cases} \quad V_{\text{dimer}}(r) = h \left[ 1 - \frac{(r - \sigma - w)^2}{w^2} \right]^2$$

- Two energy minima (compact state  $r = r_0 = 2^{1/6}\sigma$ , stretched state  $r = r_0 + 2w$ ), energy barrier  $h$

- Reaction coordinate = dimer bond length:  $\xi(q) = \frac{|q_1 - q_2| - r_0}{2w}$

- Implementation with **multiple replicas** [7] and **selection procedure** with the fitness function  $S = c \frac{\partial_{zz} \psi_t^\xi}{\psi_t^\xi}$



Left: Dynamics with and without bias. Right: Selection procedure with increasing selection strength  $c$ .

## Application to Bayesian statistics (Monte-Carlo ABF)

- Hidalgo stamp problem: the thickness of  $N_{\text{data}} = 485$  stamps are measured, and the corresponding histogram is approximated by a mixture of  $N$  Gaussians.

- Parameters  $x = (q_1, \dots, q_{N-1}, \mu_1, \dots, \mu_N, v_1, \dots, v_N) \in \mathcal{S}_{N-1} \times [\mu_{\min}, \mu_{\max}]^N \times [v_{\min}, +\infty) \subset \mathbb{R}^{3N-1}$ , with  $\mathcal{S}_{N-1} = \{(q_1, \dots, q_{N-1}) \mid 0 \leq q_i \leq 1, q_1 + \dots + q_{N-1} \leq 1\}$

- The corresponding mixture is  $f(y \mid x) = \sum_{i=1}^N q_i \sqrt{\frac{v_i}{2\pi}} \exp\left(-\frac{v_i}{2}(y - \mu_i)^2\right)$ , where  $q_N = 1 - \sum_{i=1}^{N-1} q_i$

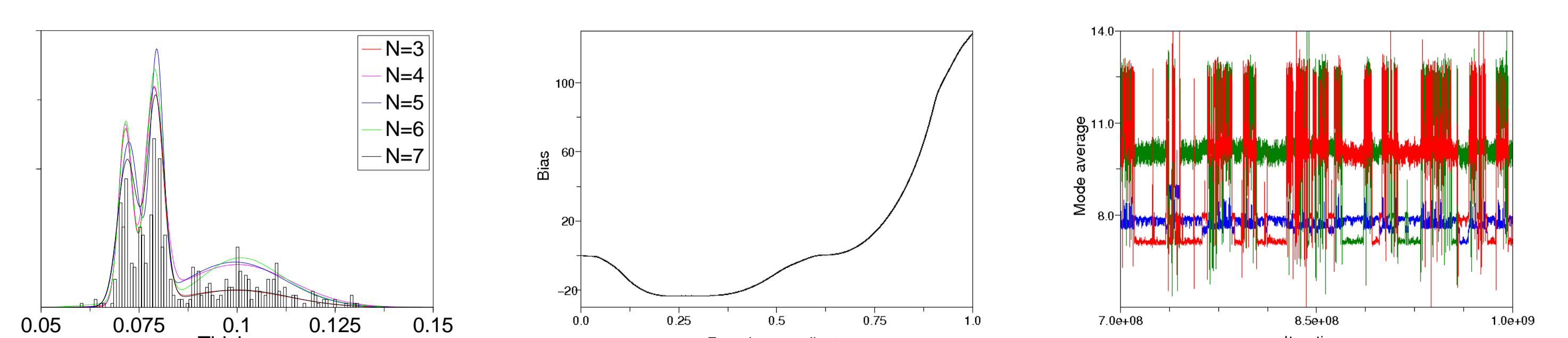
- The likelihood of observing the data  $\{y_i, 1 \leq i \leq N_{\text{data}}\}$  is  $\Pi(y \mid x) = \prod_{d=1}^{N_{\text{data}}} f(y_d \mid x) \propto e^{-\beta V_{\text{likelihood}}}$

- Potential  $V = V_{\text{prior}} + V_{\text{likelihood}}$  such that the probability of a given configuration is proportional to  $\exp(-V)$

- A simple Metropolis random-walk is metastable

- Use a Monte-Carlo ABF dynamics where  $\xi(x) = q_1$  is the reaction coordinate.

- Principle of the method is to update the average force experienced in the  $q_1$  direction and obtain the free-energy bias by integrating the approximated mean force



Left: Histogram of the data, and fit with several gaussian modes. Middle: Biasing potential obtained from a Monte-Carlo ABF dynamics. Right: Evolution of the averages  $\mu_1$ ,  $\mu_2$  and  $\mu_3$  for a biased dynamics