

L^2 -stability of explicit Runge–Kutta methods with SUPG stabilization for transient transport problems

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- Setting
- Main result and illustrations
- Abstract proof: ERK3 and ERK4
- Pedestrian proof: ERK3
- Reference
 - [AE & JLG, hal-05363804, 2025]

Setting

- Model problem
- Finite element setting and SUPG
- Time discretization using ERK

- Hilbert space L
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- **Hille–Yosida Theorem:**

$$\exists! u \in C^0(J; V) \cap C^1(J; L)$$

Reaction-advection equation

- $\mathcal{D} \subset \mathbb{R}^d$, open, bounded, connected, Lipschitz subset
- $\beta \in L^\infty(\mathcal{D})$, $\nabla \cdot \beta \in L^\infty(\mathcal{D})$, $\mu \in L^\infty(\mathcal{D})$ with $\mu - \frac{1}{2} \nabla \cdot \beta \geq \mu_0 > 0$ in \mathcal{D}

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$$\text{with } \partial \mathcal{D}^\pm := \{x \in \partial \mathcal{D} \mid \pm (\beta \cdot n)(x) > 0\}$$

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- $\mathcal{L} : V \rightarrow L$ is maximal monotone [AE & JLG, 06]
- Monotonicity (dissipativity) takes the form

$$\langle \mathcal{L}(v), v \rangle_{L^2} = \int_{\mathcal{D}} \left(\mu - \frac{1}{2} \nabla \cdot \beta \right) v^2 dx + \int_{\partial\mathcal{D}^+} (\beta \cdot n) v^2 ds \geq 0 \quad \forall v \in V$$

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 - (dissipativity) $\langle \mathcal{L}(v_h), v_h \rangle_{L^2} \geq 0$
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- Literature

- [Brooks & Hughes 82 (SUPG)], [Hughes, Franca & Hulbert 89 (GaLS)]
- SUPG = GaLS in the absence of diffusion
- analysis in [Johnson, Nävert & Pitkäranta 84]: $O(h^{k+\frac{1}{2}})$ L^2 -error bound
- textbooks: [Roos, Stynes & Tobiska 08; AE & JLG 04 & 21 (Vol III)]

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- Discrete time nodes $t^0 := 0, \dots, t^N := T$, time step $\tau_n := t^{n+1} - t^n$
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 - SUPG-norm $\| \| v_h \| \| ^2 := \| v_h \|_{L^2}^2 + \delta^2 \| \mathcal{L}(v_h) \|_{L^2}^2$
 - main stability result (assuming $\delta^2 \lesssim \tau$)

$$\| \| u_h^n \| \| \leq C \left\{ \| \| u_h^0 \| \| + t^n \| f \|_{C^0([t^0, t^n]; L^2)} \right\}$$

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 - Further work
 - CN [Burman 10], dG and cPG in time [Ahmed & Matthies 15-16]
 - space-time LS [Besson & de Montmollin 04; Perrochet & Azérad 95]

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- Explicit schemes with CFL condition **popular for first-order PDEs**
- Forward Euler **will not work**
- ERK3 and ERK4 have **better stability properties . . .**

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$$\begin{array}{c|cccc} 0 & 0 & & & \\ c_2 & a_{2,1} & 0 & & \\ \vdots & \vdots & \ddots & \ddots & \\ c_s & a_{s,1} & \cdots & a_{s,s-1} & 0 \\ \hline & b_1 & \cdots & b_{s-1} & b_s \end{array} \longrightarrow \tilde{A} := (\tilde{a}_{ij})_{i,j \in \{1:s\}} = \begin{pmatrix} a_{2,1} & & & & \\ \vdots & \ddots & & & \\ a_{s,1} & \cdots & a_{s,s-1} & & \\ a_{s+1,1} & \cdots & a_{s+1,s-1} & a_{s+1,s} \end{pmatrix}$$

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Main result and illustrations

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$$\text{(ERK3)} \quad \| \|u_h^n\| \leq \| \|u_h^0\| + Ct^n \|f\|_{C^0([t^0, t^n]; L^2)}$$

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- More precise result for ERK4:

$$\|u_h^n\| \leq \max(\|u_h^0\|, \|u_h^1\|) + Ct^n \|f\|_{C^0([t^0, t^n]; L^2)}$$

CFL condition gives $\|u_h^1\| \leq C\|u_h^0\|$

2D transport with smooth solution

- $\mathcal{D} := (0, 1)^2$, $\boldsymbol{\beta} := (1, 1)^\top$, Gaussian-like IC
- $\gamma = 0.04$, $c_{\mathcal{L}} = ((k+1)(k+2))^{\frac{1}{2}}$, $k \in \{1, 2, 3\}$
- Courant number for each ERK3 stage set to 0.25

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- L^1 -error at $T = 0.5$

\mathbb{P}_1 approximation			\mathbb{P}_2 approximation			\mathbb{P}_3 approximation		
I	L^1 err	rate	I	L^1 err	rate	I	L^1 err	rate
961	2.97E-01	2.96	961	2.76E-01	–	961	6.26E-01	–
3721	4.95E-02	2.65	1681	1.48E-01	2.22	3721	9.38E-02	2.80
8281	1.44E-02	3.08	6561	3.92E-02	1.95	8281	2.65E-02	3.16
14641	5.50E-03	3.39	14641	1.66E-02	2.14	14641	8.58E-03	3.96
32761	1.26E-03	3.66	32761	6.20E-03	2.45	32761	1.61E-03	4.15

- CV rates better than, or close to, **expected rate** $O(h^{k+\frac{1}{2}})$

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453	3.92E-01	–	458	3.43E-01	–	460	4.50E-01	–
1716	2.39E-01	0.75	1746	1.95E-01	0.84	1711	2.44E-01	0.93
6497	1.35E-01	0.85	6735	1.12E-01	0.82	6751	1.29E-01	0.93
25049	8.04E-02	0.77	25734	6.75E-02	0.75	27091	7.54E-02	0.78
98752	4.72E-02	0.78	99690	3.98E-02	0.78	99859	4.59E-02	0.76

- Close to **expected rate $O(h)$** in L^1 -norm
- Errors and rates for \mathbb{P}_2 and \mathbb{P}_3 better than [Guermond, Nazarov & Popov 24]
 \implies **benefit of using linear stabilization for nonsmooth problems**

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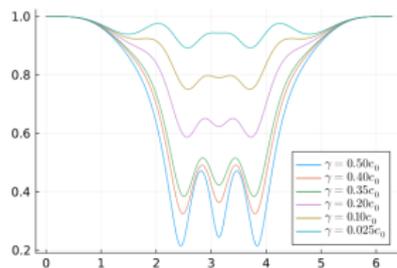
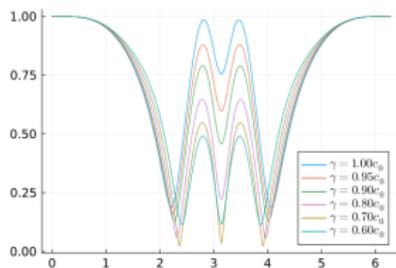
$$P_3(x) = 1 + x + \frac{1}{2}x^2 + \frac{1}{6}x^3, \quad \Lambda(\theta) := \lambda \frac{2\gamma(\cos(\theta) - 1) - i \sin(\theta)}{\frac{1}{3}(\cos(\theta) + 2) - i\gamma \sin(\theta)}$$

Fourier analysis in 1D

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- $|g_3(\theta)|$ as a function of θ for decreasing values of $\lambda\gamma$



- $|g_3(\theta)| \leq 1$ for all $\lambda \in (0, 1]$ and $\lambda\gamma \in (0, c_0 := 0.196]$

Abstract proof: ERK3 and ERK4

Stability of ERK3 and ERK4 schemes (1/2)

- Equip V_h with inner product $((\bullet, \bullet))$, associated norm $\|\bullet\| := ((\bullet, \bullet))^{\frac{1}{2}}$

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 - (inverse inequality) $\|C_h(v_h)\| \leq c_* h^{-1} \|v_h\|$
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- Theorem.** [AE & JLG 25] Let $P_s(z) := \sum_{l \in \{0:s\}} \frac{1}{l!} z^l$. There is $\sigma_0 > 0$ so that, for all $\lambda \leq \sigma_0$,

$$\|P_3(-\tau_n C_h)\|_{\mathcal{L}(V_h)} \leq 1, \quad \|P_4(-\tau_n C_h)^2\|_{\mathcal{L}(V_h)} \leq 1$$

Seminal ideas in [Sun & Shu 19; Xu, Zhang, Shu & Wang 19]

Stability of ERK3 and ERK4 schemes (2/2)

- s -stage ERK scheme rewrites

$$u_h^{n+1} = P_s(-\tau_n C_h)(u_h^n) + \tau_n \sum_{r \in \{1:s\}} (-\tau_n C_h)^{r-1} (\Phi_r(g_h))$$

$$\text{with } \Phi_r(g_h) := \sum_{j \in \{1:s-r+1\}} (bA^{r-1})_j g_h^{n,j-1}$$

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- **Corollary.** (above theorem, triangle ineq., inverse ineq., CFL condition)

$$\text{(ERK3)} \quad \| \| u_h^{n+1} \| \| \leq \| \| u_h^n \| \| + C\tau_n \max_{t \in [t^n, t^{n+1}]} \| \| g_h(t) \| \|_{L^2}$$

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- Summing over n gives

$$\text{(ERK3)} \quad \|u_h^n\| \leq \|u_h^0\| + Ct^n \|g_h\|_{C^0([t^0, t^n]; L^2)}$$

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Fitting ERK-SUPG into canonical form

- Recall ERK-SUPG scheme

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- We reach the canonical form by defining $C_h : V_h \rightarrow V_h$ s.t.

$$((C_h(v_h), w_h)) := ((\mathcal{A}_h(v_h), B_h^{-1}(w_h)))$$

(We shall see that B_h is indeed invertible.)

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Properties of C_h and g_h

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- These bounds **prove our main result** for ERK3 and ERK4 for $\gamma \leq \frac{1}{2}$

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 - ④ (Step 2 + CS) $\implies ((B_h(v_h) - v_h, w_h)) \leq \delta \|\mathcal{L}(v_h)\|_{L^2} \|w_h\|$

Proof insights: Properties of B_h

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- **Corollary.** B_h invertible for $\gamma < 1$

Proof insights: C_h is dissipative

- Recall $((C_h(v_h), v_h)) = ((\mathcal{A}_h(v_h), B_h^{-1}(v_h)))$ and set $w_h := B_h^{-1}(v_h)$ so that
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- $-\frac{1}{2\delta} \|B_h(w_h) - w_h\|_{L^2}^2 + \frac{\delta}{2} \|\mathcal{L}(w_h)\|_{L^2}^2 \geq 0$ and \mathcal{L} dissipative $\implies ((C_h(v_h), v_h)) \geq 0$

Pedestrian proof: ERK3

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- Test ERK stages by
 - the solution at different stages (coercivity argument)
 - increments between stages (akin to time derivatives)

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- Can we reproduce this for **explicit** schemes with **multiple stages**?

- Recall ERK scheme

$$\langle u_h^{n,i} - u_h^{n,0}, v_h + \delta \mathcal{L}(v_h) \rangle_{L^2} + \tau_n \sum_{j \in \{1:i\}} \tilde{a}_{i,j} \langle \mathcal{L}(u_h^{n,j-1}) - f^{n,j-1}, v_h + \delta \mathcal{L}(v_h) \rangle_{L^2} = 0$$

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- Compact notation in \mathbb{R}^s :**

$$\langle [\Delta u_h^n], [v_h] + \delta \mathcal{L}[v_h] \rangle_{\ell^2(L^2)} + \tau_n \langle \hat{A}(\mathcal{L}[\check{u}_h^n] - [\check{f}^n]), [v_h] + \delta \mathcal{L}[v_h] \rangle_{\ell^2(L^2)} = 0$$

with

$$[\Delta u_h^n] := \begin{pmatrix} \Delta u_h^{n,1} \\ \vdots \\ \Delta u_h^{n,s} \end{pmatrix} \quad [\check{u}_h^n] := \begin{pmatrix} u_h^{n,0} \\ \vdots \\ u_h^{n,s-1} \end{pmatrix} \quad [\check{f}^n] := \begin{pmatrix} f^{n,0} \\ \vdots \\ f^{n,s-1} \end{pmatrix}$$

- Recall incremental ERK scheme

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Incrementally r -quasi-stable matrices

- Recall incremental ERK scheme

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- We want to test with $[v_h] := B[\check{u}_h^n]$ and with $[v_h] := \frac{\delta}{\tau_n} B'[\Delta u_h^n]$ for suitable matrices $B, B' \in \mathbb{R}^{s,s}$

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- Example for $s = 3$ [Burman, AE & Fernandez]

$$B = \begin{pmatrix} \frac{1}{2} & \frac{1}{6} & \frac{1}{3} \\ \frac{1}{3} & 0 & \frac{2}{3} \\ 0 & 0 & 1 \end{pmatrix}, \quad B \begin{pmatrix} u_h^{n,0} \\ u_h^{n,1} \\ u_h^{n,2} \end{pmatrix} \cdot \begin{pmatrix} u_h^{n,1} - u_h^{n,0} \\ u_h^{n,2} - u_h^{n,1} \\ u_h^{n,3} - u_h^{n,2} \end{pmatrix} = \frac{1}{2} \left\{ |u_h^{n,3}|^2 - |u_h^{n,0}|^2 \right\} + \frac{1}{6} |\Delta u_h^{n,2}|^2 - \frac{1}{2} |\Delta u_h^{n,3}|^2$$

The matrices C and B'

- We require that the matrix $C := B^T \widehat{A} \in \mathbb{R}^{s,s}$ is **symmetric**
- We require that $\langle C[\check{u}_h^n], [\check{u}_h^n] \rangle_{\ell^2} \geq -\kappa \sum_{l \in \{r:s\}} |\Delta u_h^{n,l}|^2$ for some $\kappa \geq 0$

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- The matrix $B' := B \widehat{A}^{-1} \in \mathbb{R}^{s,s}$ is also **symmetric**
- We require that $\langle B' [\check{v}_h^n], [\check{v}_h^n] \rangle_{\ell^2} \geq -\kappa \sum_{l \in \{r:s\}} |v_h^{n,l}|^2$ for some $\kappa \geq 0$

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 - By linearity, we can focus on one specific ERK3 scheme
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The matrices C and B'

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!! Thank you for your attention !!